

# Laplace transform-homotopy perturbation method as a powerful tool to solve nonlinear problems with boundary conditions defined on finite intervals

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**Abstract** This article proposes Laplace transform-homotopy perturbation method (LT-HPM) to solve nonlinear differential equations with Dirichlet, mixed, and Neumann boundary conditions. After comparing figures between approximate and exact solutions, we will see that the proposed solutions are of high accuracy and, therefore, that LT-HPM is extremely efficient.

**Keywords** Homotopy perturbation method · Nonlinear differential equation · Approximate solutions · Laplace transform · Laplace transform homotopy perturbation method · Dirichlet · Boundary condition · Neumann boundary condition · Gelfand's differential equation

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## 1 Introduction

Laplace transform (LT) (or operational calculus) has played an important role in mathematics, not only for its theoretical interest, but also because his methods let to solve, in a simpler fashion, many problems in science and engineering, in comparison with other mathematical techniques. In particular, the Laplace transform is useful not only for solving linear ordinary differential equations with constant coefficients, with initial conditions, but also for solving some cases of differential equations with variable coefficients and partial differential equations (Spiegel 1988). On the other hand, applications of LT for nonlinear ordinary differential equations mainly aim to find approximate solutions; thus in reference (Aminikhan and Hemmatnezhad 2012) was reported a combination of homotopy perturbation (HPM) and LT methods (LT-HPM) to obtain highly accurate solutions for these equations. However, just as with LT, LT-HPM method has been used mainly to find solutions to problems with initial conditions (Aminikhan and Hemmatnezhad 2012; Aminikhah 2012), because it is directly related to them. Therefore, this paper presents three application examples of LT-HPM, in the search for approximate solutions for nonlinear problems with Dirichlet, mixed, and Neumann boundary conditions defined on finite intervals.

The case of equations with boundary conditions on infinite intervals has been studied in some articles and correspond often to problems defined on semi-infinite ranges (Hossein 2011; Khan et al. 2011). However the methods of solving these problems are different from what will be presented in this paper.

The importance of research on nonlinear differential equations is that many phenomena, practical or theoretical, are of nonlinear nature. In recent years, several methods focused to find approximate solutions to nonlinear differential equations, as an alternative to classical methods, have been reported, such those based on variational approaches (Assas 2007; He 2007; Kazemnia et al. 2008; Noorzad 2008), tanh method (Evans and Raslan 2005), exp-function (Xu 2007; Mahmoudi et al. 2008), Adomian's decomposition method (Adomian 1988; Babolian and Biazar 2002; Kooch and Abadyan 2012, 2011; Vanani et al. 2011; Chowdhury 2011), parameter expansion (Zhang and Xu 2007), homotopy perturbation method (He 2000, 1999, 2006, 2008; Belendez et al. 2009; El-Shaed 2005; He 2006; Ganji et al. 2009, 2008; Fereidon et al. 2010; Sharma and Methi 2011; Hossein 2011; Vazquez-Leal et al. 2012a, b; Filobello-Nino et al. 2012; Biazar and Aminikhan 2009; Biazar and Ghazvini 2009; Filobello-Nino et al. 2012; Yasir Khan and Qingbiao Wu 2011; Madani et al. 2011; Aminikhan and Hemmatnezhad 2012; Aminikhah 2012; Khan et al. 2011), homotopy analysis method (Patel et al. 2012), and perturbation method (Filobello-Nino et al. 2013) among many others. From all the above methods, the HPM method is one of the most employed because it has been successfully used in many nonlinear problems, and its practical application is simpler than other techniques.

This paper is organized as follows: in Sect. 2, we introduce the basic idea of standard HPM method. Section 3 provides a basic idea of Laplace transform. For Sect. 4 we introduce Laplace transform homotopy perturbation method. Additionally, Sect. 5 presents three case studies. Besides, a discussion on the results is presented in Sect. 6. Finally, a brief conclusion is given in Sect. 7.

## 2 Standard homotopy perturbation method (HPM)

The standard HPM was proposed by Ji Huan He as a powerful tool to approach various kinds of nonlinear problems. The homotopy perturbation method is considered as a combination of

the classical perturbation technique and the homotopy (whose origin is in the topology), but not restricted to small parameters as occur with traditional perturbation methods. For example, HPM method requires neither small parameter nor linearization, but only few iterations to obtain highly accurate solutions (He 2000, 1999).

To figure out how HPM method works, consider a general nonlinear equation in the form

$$A(u) - f(r) = 0, \quad r \in \Omega, \quad (1)$$

with the following boundary conditions:

$$B(u, \partial u / \partial n) = 0, \quad r \in \Gamma, \quad (2)$$

where  $A$  is a general differential operator,  $B$  is a boundary operator,  $f(r)$  a known analytical function, and  $\Gamma$  is the domain boundary for  $\Omega$ .  $A$  can be divided into two operators  $L$  and  $N$ , where  $L$  is linear and  $N$  nonlinear so that (1) can be rewritten as

$$L(u) + N(u) - f(r) = 0, \quad (3)$$

Generally, a homotopy can be constructed as (He 2000, 1999)

$$H(U, p) = (1-p)[L(U) - L(u_0)] + p[L(U) + N(U) - f(r)] = 0, \quad p \in [0, 1], \quad r \in \Omega. \quad (4)$$

or

$$H(U, p) = L(U) - L(u_0) + p[L(u_0) + N(U) - f(r)] = 0, \quad p \in [0, 1], \quad r \in \Omega \quad (5)$$

where  $p$  is a homotopy parameter, whose values are within range of 0 and 1, and  $u_0$  is the first approximation for the solution of (3) that satisfies the boundary conditions.

Assuming that solution for (4) or (5) can be written as a power series of  $p$

$$U = v_0 + v_1 p + v_2 p^2 + \dots \quad (6)$$

Substituting (6) into (5) and equating identical powers of  $p$  terms, there can be found values for the sequence  $v_0, v_1, v_2, \dots$

When  $p \rightarrow 1$ , it yields in the approximate solution for (1) in the form

$$U = v_0 + v_1 + v_2 + v_3 \dots \quad (7)$$

### 3 Basic idea of laplace transform

Laplace transform of  $F(t)$  is denoted by  $\mathfrak{L}\{F(t)\}$  and is defined by the integral

$$\mathfrak{L}\{F(t)\} = f(s) = \int_0^{\infty} e^{-st} F(t) dt \quad (8)$$

Among its most important properties is linearity, that is,

$$\mathfrak{L}\{c_1 F_1(t) + c_2 F_2(t)\} = c_1 f_1(s) + c_2 f_2(s), \quad (9)$$

where  $c_1$  and  $c_2$  are constants and  $\mathfrak{L}\{F_1(t)\} = f_1(s)$ ,  $\mathfrak{L}\{F_2(t)\} = f_2(s)$ .

Some known properties of LT, employed in this study are

i)

$$\mathfrak{L}\{1\} = \frac{1}{s} \quad (s > 0) \quad (10)$$

ii)

$$\mathfrak{S} \{t^n\} = \frac{n!}{s^{n+1}} \quad (s > 0) \quad (11)$$

iii)

$$\mathfrak{S} \{F^{(n)}(t)\} = s^n f(s) - s^{n-1} F(0) - s^{n-2} F'(0) - \dots - F^{(n-1)}(0), \quad (12)$$

where  $F^{(n)}(t)$  denotes the  $n$ -th derivative of  $F(t)$  and  $\mathfrak{S} \{F(t)\} = f(s)$ .

If Laplace transform of  $F(t)$  is  $f(s)$ , then  $F(t)$  is called the inverse Laplace transform of  $f(s)$  and is expressed by  $F(t) = \mathfrak{S}^{-1} \{f(s)\}$ , where  $\mathfrak{S}^{-1}$  is called the inverse Laplace transform operator.

From equations (10) and (11) it is clear that

$$1 = \mathfrak{S}^{-1} \left( \frac{1}{s} \right), \quad (13)$$

$$t^n = \mathfrak{S}^{-1} \left( \frac{n!}{s^{n+1}} \right), \quad (14)$$

The following result is obtained from (9) and denotes the linearity property of  $\mathfrak{S}^{-1}$ :

$$\mathfrak{S}^{-1} \{c_1 f_1(s) + c_2 f_2(s)\} = c_1 F_1(t) + c_2 F_2(t). \quad (15)$$

#### 4 Basic idea of Laplace transform homotopy perturbation method (LT-HPM)

The objective of this section is employ LT-HPM to find analytical approximate solutions of ODEs, as (3).

For this purpose LTHPM follows the same steps of standard HPM until (5); next we apply Laplace transform on both sides of homotopy equation (5) to obtain

$$\mathfrak{S} \{L(U) - L(u_0) + p[L(u_0) + N(U) - f(r)]\} = 0, \quad (16)$$

using the differential property of LT, we have

$$s^n \mathfrak{S} \{U\} - s^{n-1} U(0) - s^{n-2} U'(0) - \dots - U^{(n-1)}(0) = \mathfrak{S} \{L(u_0) - pL(u_0) + p[-N(U) + f(r)]\}, \quad (17)$$

or

$$\mathfrak{S}(U) = \left( \frac{1}{s^n} \right) \left\{ s^{n-1} U(0) + s^{n-2} U'(0) + \dots + U^{(n-1)}(0) \right\} + \mathfrak{S} \{L(u_0) - pL(u_0) + p[-N(U) + f(r)]\} \quad (18)$$

Applying inverse Laplace transform to both sides of (18), we obtain

$$U = \mathfrak{S}^{-1} \left\{ \left( \frac{1}{s^n} \right) \left\{ s^{n-1} U(0) + s^{n-2} U'(0) + \dots + U^{(n-1)}(0) \right\} + \mathfrak{S} \left\{ L(u_0) - pL(u_0) + p[-N(U) + f(r)] \right\} \right\} \quad (19)$$

Assuming that the solutions of (3) can be expressed as a power series of  $p$

$$U = \sum_{n=0}^{\infty} p^n v_n, \quad (20)$$

Then substituting (20) into (19), we get

$$\begin{aligned} \sum_{n=0}^{\infty} p^n v_n = \mathfrak{S}^{-1} \left\{ \left( \frac{1}{s^n} \right) \left\{ s^{n-1} U(0) + s^{n-2} U'(0) + \dots + U^{(n-1)}(0) \right\} \right. \\ \left. + \mathfrak{S} \left\{ L(u_0) - pL(u_0) + p \left[ -N \left( \sum_{n=0}^{\infty} p^n v_n \right) + f(r) \right] \right\} \right\}, \quad (21) \end{aligned}$$

Comparing coefficients of  $p$  with the same power leads to

$$\begin{aligned} p^0 : v_0 &= \mathfrak{S}^{-1} \left\{ \left( \frac{1}{s^n} \right) \left( s^{n-1} U(0) + s^{n-2} U'(0) + \dots + U^{(n-1)}(0) \right) + \mathfrak{S} \{ L(u_0) \} \right\}, \\ p^1 : v_1 &= \mathfrak{S}^{-1} \left\{ \left( \frac{1}{s^n} \right) \left( \mathfrak{S} \{ N(v_0) - L(u_0) + f(r) \} \right) \right\}, \\ p^2 : v_2 &= \mathfrak{S}^{-1} \left\{ \left( \frac{1}{s^n} \right) \mathfrak{S} \{ N(v_0, v_1) \} \right\}, \\ p^3 : v_3 &= \mathfrak{S}^{-1} \left\{ \left( \frac{1}{s^n} \right) \mathfrak{S} \{ N(v_0, v_1, v_2) \} \right\}, \\ &\dots \\ p^j : v_j &= \mathfrak{S}^{-1} \left\{ \left( \frac{1}{s^n} \right) \mathfrak{S} \{ N(v_0, v_1, v_2, \dots, v_j) \} \right\}, \\ &\dots \end{aligned} \quad (22)$$

Assuming that the initial approximation has the form  $U(0) = u_0 = \alpha_0$ ,  $U'(0) = \alpha_1, \dots, U^{n-1}(0) = \alpha_{n-1}$ ; therefore, the exact solution may be obtained as follows:

$$u = \lim_{p \rightarrow 1} U = v_0 + v_1 + v_2 + \dots \quad (23)$$

## 5 Case studies

### 5.1 Dirichlet boundary conditions

The equation to solve is Gelfand's differential equation which governs combustible gas dynamics (He 2006).

$$\frac{d^2 y(x)}{dx^2} + \varepsilon e^{y(x)} = 0, \quad 0 \leq x \leq 1, \quad y(0) = 0, \quad y(1) = 0, \quad (24)$$

where  $\varepsilon$  is a positive parameter.

It is possible to find a handy solution by applying the LT-HPM method.

Identifying terms:

$$L(y) = y''(x), \quad (25)$$

$$N(y) = \varepsilon e^{y(x)}, \quad (26)$$

where prime denotes differentiation with respect to  $x$ .

To solve approximately (24), first we expand the exponential term of Gelfand's problem, resulting in

$$y'' + \varepsilon \left( 1 + y + \frac{1}{2}y^2 + \frac{1}{6}y^3 + \dots \right) = 0, \quad 0 \leq x \leq 1, \quad y(0) = 1, \quad y(1) = 0 \quad (27)$$

In order to obtain an approximate analytical solution we construct a homotopy in accordance with (4)

$$(1 - p)(y'' - y_0'') + p \left[ y'' + \varepsilon \left( 1 + y + \frac{1}{2}y^2 + \frac{1}{6}y^3 \right) \right] = 0, \quad (28)$$

or

$$y'' = y_0'' + p \left[ -y_0'' - \varepsilon \left( 1 + y + \frac{1}{2}y^2 + \frac{1}{6}y^3 \right) \right]. \quad (29)$$

Applying Laplace transform algorithm, we get

$$\Im(y'') = \Im \left( y_0'' + p \left( -y_0'' - \varepsilon \left( 1 + y + \frac{1}{2}y^2 + \frac{1}{6}y^3 \right) \right) \right), \quad (30)$$

and after substituting (12) for  $n = 2$ , we obtain

$$s^2 Y(s) - s y(0) - y'(0) = \Im \left( y_0'' + p \left( y_0'' - \varepsilon \left( 1 + y + \frac{1}{2}y^2 + \frac{1}{6}y^3 \right) \right) \right). \quad (31)$$

Solving for  $Y(s)$  and applying Laplace inverse transform  $\Im^{-1}$

$$y(x) = \Im^{-1} \left\{ \frac{1}{s^2} \left( A + \Im \left( y_0'' + p \left( -y_0'' - \varepsilon \left( 1 + y + \frac{1}{2}y^2 + \frac{1}{6}y^3 \right) \right) \right) \right) \right\}, \quad (32)$$

where we defined  $A = y'(0)$  and employed the condition  $y(0) = 0$ .

Next, we assume a series solution for  $y(x)$ , in the form

$$y(x) = \sum_{n=0}^{\infty} p^n v_n, \quad (33)$$

and choosing

$$v_0(x) = Ax, \quad (34)$$

as the first approximation for the solution of (24) that satisfies the condition  $y(0) = 0$ . Substituting (33) and (34) into (32), we get

$$\sum_{n=0}^{\infty} p^n v_n = \Im^{-1} \left\{ \frac{1}{s^2} \left( A - \varepsilon \Im \left( p(1 + v_0 + p v_1 + p^2 v_2 + \dots) \frac{1}{2} (v_0 + p v_1 + p^2 v_2 + \dots)^2 + \frac{1}{6} (v_0 + p v_1 + p^2 v_2 + \dots)^3 \right) \right) \right\} \quad (35)$$

On comparing the coefficients of like powers of  $p$  we have

$$p^0 : v_0(x) = \mathfrak{S}^{-1} \left\{ \frac{A}{s^2} \right\}, \quad (36)$$

$$p^1 : v_1(x) = \mathfrak{S}^{-1} \left\{ \left( -\frac{\varepsilon}{s^2} \right) \mathfrak{S} \left( 1 + v_0 + \frac{v_0^2}{2} + \frac{v_0^3}{6} \right) \right\}, \quad (37)$$

$$p^2 : v_2(x) = \mathfrak{S}^{-1} \left\{ \left( -\frac{\varepsilon}{s^2} \right) \mathfrak{S} \left( v_1 + v_0 v_1 + \frac{v_0^2 v_1}{2} \right) \right\}, \quad (38)$$

...

Solving the above equations for  $v_0(x)$ ,  $v_1(x)$ ,  $v_2(x)$ , ..., we obtain

$$v_0(x) = Ax, \quad (39)$$

$$v_1(x) = -\frac{\varepsilon}{2}x^2 - \frac{\varepsilon A}{6}x^3 - \frac{\varepsilon A^2}{24}x^4 - \frac{\varepsilon A^3}{120}x^5, \quad (40)$$

$$v_2(x) = \frac{\varepsilon^2}{24}x^4 + \frac{\varepsilon^2 A}{30}x^5 + \frac{11\varepsilon^2 A^2}{720}x^6 + \frac{\varepsilon^2 A^3}{315}x^7 + \frac{\varepsilon^2 A^4}{1920}x^8 + \frac{\varepsilon^2 A^5}{17280}x^9, \quad (41)$$

...

and so on.

By substituting solutions (39), (40) and (41) into (23) and calculating the limit when  $p \rightarrow 1$  results in a second-order approximation

$$y(x) = Ax - \frac{\varepsilon}{2}x^2 - \frac{\varepsilon A}{6}x^3 + \left( \frac{\varepsilon^2}{24} - \frac{\varepsilon A^2}{24} \right) x^4 + \left( \frac{\varepsilon^2 A}{30} - \frac{\varepsilon A^3}{120} \right) x^5 + \frac{11\varepsilon^2 A^2}{720}x^6 + \frac{\varepsilon^2 A^3}{315}x^7 + \frac{\varepsilon^2 A^4}{1920}x^8 + \frac{\varepsilon^2 A^5}{17280}x^9 \quad (42)$$

In order to calculate the value of  $A$ , we require that (42) satisfies the boundary condition  $y(1) = 0$ , resulting an equation for  $A$ . After considering the value of  $\varepsilon = 1/2$  as a case study, we obtain the following result:

$$A = 0.2603191187. \quad (43)$$

Substituting (43) into (42), we obtain

$$y(x) = 0.2603191187x - 0.25x^2 - 0.02169326x^3 + 0.0090048741x^4 + 0.002095822669x^5 + 0.0002588286386x^6 + 0.00001400063x^7 + 5.979474818x10^{-7}x^8 + 1.729524016x10^{-8}x^9 \quad (44)$$

## 5.2 Mixed boundary conditions

Now we will consider the following nonlinear differential equation:

$$\frac{d^2 y(x)}{dx^2} - \varepsilon y^4(x) = 0, \quad 0 \leq x \leq 1, \quad y'(0) = 0, \quad y(1) = 1 \quad (45)$$

which describes the temperature distribution in a uniformly thick rectangular fin radiation to free space with nonlinearity of high order (Marinca and Herisanu 2011).

We will find a handy solution for (45) by applying the LTHPM method.

Identifying terms:

$$L(y) = y''(x), \quad (46)$$

$$N(y) = -\varepsilon y^4(x), \quad (47)$$

where prime denotes differentiation with respect to  $x$ .

In order to obtain an approximate analytical solution we construct a homotopy in accordance with (4)

$$(1 - p)(y'' - y_0'') + p[y'' - \varepsilon y^4] = 0, \quad (48)$$

or

$$y'' = y_0'' + p[-y_0'' + \varepsilon y^4]. \quad (49)$$

Applying Laplace transform algorithm we get

$$\Im(y'') = \Im(y_0'' + p(-y_0'' + \varepsilon y^4)), \quad (50)$$

and after substituting (12) for  $n = 2$

$$s^2 Y(s) - sy(0) - y'(0) = \Im(y_0'' + p(-y_0'' + \varepsilon y^4)). \quad (51)$$

Solving for  $Y(s)$  and applying Laplace inverse transform  $\Im^{-1}$

$$y(x) = \Im^{-1} \left\{ \frac{1}{s^2} (A + \Im(y_0'' + p(-y_0'' + \varepsilon y^4))) \right\}, \quad (52)$$

where we defined  $A = y(0)$ , and employed the condition  $y'(0) = 0$ .

Next, we assume a series solution for  $y(x)$ , in the form

$$y(x) = \sum_{n=0}^{\infty} p^n v_n, \quad (53)$$

and we choose

$$v_0(x) = A, \quad (54)$$

as the first approximation for the solution of (45) that satisfies the condition  $y'(0) = 0$ .

Substituting (53) and (54) into (52), we get

$$\sum_{n=0}^{\infty} p^n v_n = \Im^{-1} \left\{ \frac{1}{s^2} (As + p\varepsilon \Im((v_0 + pv_1 + p^2 v_2 + \dots)^4)) \right\} \quad (55)$$



On comparing the coefficients of like powers of  $p$  we have

$$p^0 : v_0(x) = \mathfrak{S}^{-1} \left\{ \frac{A}{s} \right\}, \quad (56)$$

$$p^1 : v_1(x) = \varepsilon \mathfrak{S}^{-1} \left\{ \left( \frac{1}{s^2} \right) \mathfrak{S}\{v_0^4\} \right\}, \quad (57)$$

$$p^2 : v_2(x) = \varepsilon \mathfrak{S}^{-1} \left\{ \left( \frac{1}{s^2} \right) \mathfrak{S}(4v_0^3 v_1) \right\}, \quad (58)$$

$$p^3 : v_3(x) = \varepsilon \mathfrak{S}^{-1} \left\{ \left( \frac{1}{s^2} \right) \mathfrak{S}(6v_0^2 v_1^2 + 4v_0^3 v_2) \right\} \quad (59)$$

$$p^4 : v_4(x) = \varepsilon \mathfrak{S}^{-1} \left\{ \left( \frac{1}{s^2} \right) \mathfrak{S}(4v_1^3 v_0 + 12v_0^2 v_1 v_2 + 4v_0^3 v_3) \right\}, \quad (60)$$

...

Solving the above Laplace transforms for  $v_0(x)$ ,  $v_1(x)$ ,  $v_2(x)$ , ... we obtain

$$p^0 : v_0(x) = A, \quad (61)$$

$$p^1 : v_1(x) = \frac{\varepsilon A^4}{2} x^2, \quad (62)$$

$$p^2 : v_2(x) = \frac{\varepsilon^2 A^7}{6} x^4, \quad (63)$$

$$p^3 : v_3(x) = \frac{13\varepsilon^3 A^{10}}{180} x^6, \quad (64)$$

$$p^4 : v_4(x) = \frac{161\varepsilon^4 A^{13}}{5040} x^8, \quad (65)$$

...

and so on.

By substituting solutions (61)–(65) into (23) and calculating the limit when  $p \rightarrow 1$  results in a fourth-order approximation

$$y(x) = A + \frac{\varepsilon A^4}{2} x^2 + \frac{\varepsilon^2 A^7}{6} x^4 + \frac{13\varepsilon^3 A^{10}}{180} x^6 + \frac{161\varepsilon^4 A^{13}}{5040} x^8 + \dots \quad (66)$$

In order to calculate the value of  $A$ , we require that (66) satisfies the boundary condition  $y(1) = 1$ ; this gives rise to an equation for  $A$ . Considering as case study  $\varepsilon = 1$ , we obtain the value

$$A = 0.7792914176 \quad (67)$$

Substituting (67) into (66), we obtain

$$y(x) = 0.7792914176 + 0.1844036774x^2 + 0.02909028680x^4 + 0.005965814985x^6 + 0.001248803057x^8. \quad (68)$$

### 5.3 Neumann boundary conditions

Finally, we will find an approximate solution for

$$\frac{d^2 y(x)}{dx^2} + y(x) - y^2(x) = 0, \quad 0 \leq x \leq 1, \quad y'(0) = 0, \quad y'(1) = \pi/4, \quad (69)$$

To obtain a precise solution for (69) by applying the LTHPM method, we identify

$$L(y) = y''(x), \quad (70)$$

$$N(y) = y(x) - y^2(x), \quad (71)$$

where prime denotes differentiation with respect to  $x$ .

We construct the following homotopy in accordance with (4):

$$(1 - p)(y'' - y_0'') + p[y'' + y - y^2] = 0, \quad (72)$$

or

$$y'' = y_0'' + p[-y_0'' - y + y^2]. \quad (73)$$

Applying Laplace transform to (73) we get

$$\mathfrak{S}(y'') = \mathfrak{S}(y_0'' + p(-y_0'' - y + y^2)), \quad (74)$$

and after substituting (12), for  $n = 2$

$$s^2 Y(s) - sy(0) - y'(0) = \mathfrak{S}(y_0'' + p(-y_0'' - y + y^2)). \quad (75)$$

Solving for  $Y(s)$  and applying Laplace inverse transform  $\mathfrak{S}^{-1}$

$$y(x) = \mathfrak{S}^{-1} \left\{ \frac{A}{s} \right\} + \mathfrak{S}^{-1} \left\{ \frac{1}{s^2} (\mathfrak{S}(y_0'' + p(-y_0'' - y + y^2))) \right\}, \quad (76)$$

where we defined  $A = y(0)$ , and employed the condition  $y'(0) = 0$ .

Next, suppose that the solution for (69) has the form

$$y(x) = \sum_{n=0}^{\infty} p^n v_n, \quad (77)$$

and choosing

$$v_0(x) = A, \quad (78)$$

as the first approximation for the solution of (69) that satisfies the condition  $y'(0) = 0$ .

Substituting (77) and (78) into (76), we get

$$\begin{aligned} \sum_{n=0}^{\infty} p^n v_n = \mathfrak{S}^{-1} \left\{ \frac{A}{s} + p \left\{ \left( \frac{1}{s^2} \right) \mathfrak{S} \{ -(v_0 + pv_1 + p^2v_2 + \dots) \right. \right. \\ \left. \left. + (v_0 + pv_1 + p^2v_2 + \dots)^2 \right\} \right\} \end{aligned} \quad (79)$$

Equating terms with identical powers of  $p$ , we obtain

$$p^0 : v_0(x) = \mathfrak{S}^{-1} \left\{ \frac{A}{s} \right\}, \tag{80}$$

$$p^1 : v_1(x) = \mathfrak{S}^{-1} \left\{ \left( \frac{1}{s^2} \right) \mathfrak{S}(-v_0 + v_0^2) \right\}, \tag{81}$$

$$p^2 : v_2(x) = \mathfrak{S}^{-1} \left\{ \left( \frac{1}{s^2} \right) \mathfrak{S}(-v_1 + 2v_0v_1) \right\}, \tag{82}$$

$$p^3 : v_2(x) = \mathfrak{S}^{-1} \left\{ \left( \frac{1}{s^2} \right) \mathfrak{S}(-v_2 + v_1^2 2v_0v_2) \right\}, \tag{83}$$

$$p^4 : v_2(x) = \mathfrak{S}^{-1} \left\{ \left( \frac{1}{s^2} \right) \mathfrak{S}(-v_3 + 2v_0v_3 + 2v_1v_2) \right\}, \tag{84}$$

...

Solving the above equations for  $v_0(x)$ ,  $v_1(x)$ ,  $v_2(x)$ , ... we obtain

$$p^0 : v_0(x) = A, \tag{85}$$

$$p^1 : v_1(x) = \frac{(A^2 - A)x^2}{2}, \tag{86}$$

$$p^2 : v_2(x) = \frac{(A^2 - A)(2A - 1)x^2}{4!}, \tag{87}$$

$$p^3 : v_3(x) = \frac{[(A^2 - A)(2A - 1)^2 + 6(A^2 - A)^2]x^6}{6!}, \tag{88}$$

$$p^4 : v_4(x) = \frac{(2A - 1)(A^2 - A)[(2A - 1)^2 + 36(A^2 - A)]x^8}{8!}, \tag{89}$$

...

and so on.

By substituting solutions (85)–(89) into (23) results in a fourth-order approximation

$$y(x) = A + \left( \frac{A^2 - A}{2} \right) x^2 + \frac{(A^2 - A)(2A - 1)}{4!} x^4 + \frac{((A^2 - A)(2A - 1)^2 + 6(A^2 - A)^2)}{6!} x^6 + \frac{(A^2 - A)(2A - 1)((2A - 1)^2 + 36(A^2 - A))}{8!} x^8. \tag{90}$$

In order to calculate the value of  $A$ , we require that (90) satisfies the boundary condition  $y'(1) = \pi/4$  so that we obtain

$$A = -0.6793160999. \tag{91}$$

Substituting (91) into (90), we obtain

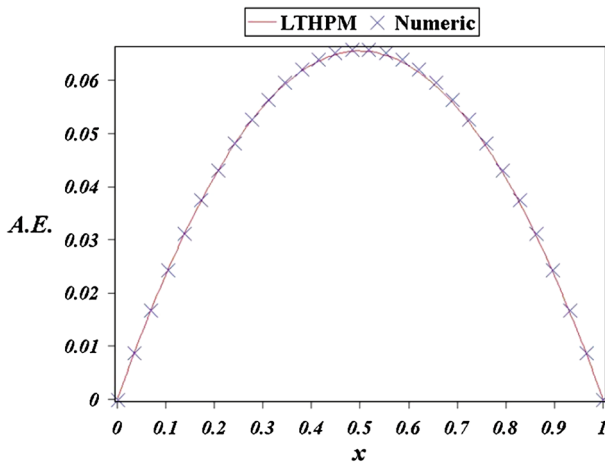
$$y(x) = -0.6793160999 + 0.5703932320x^2 - 0.1121123203x^4 + 0.01965933892x^6 - 0.003111881558x^8. \tag{92}$$

### 6 Discussion

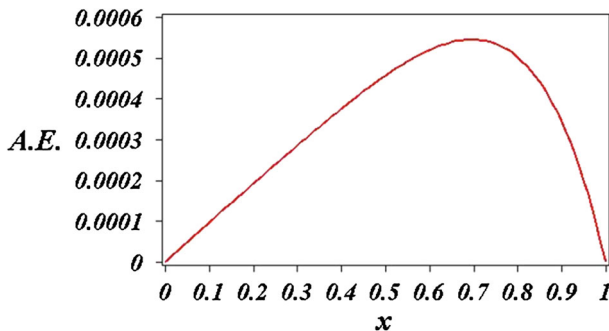
In this work, LT-HPM was used in the search for handy accurate analytical approximate solutions for nonlinear ordinary differential equations with boundary conditions defined on

finite intervals. In order to show the versatility of this method, we chose equations subject to Dirichlet, mixed and Neumann boundary conditions; as a matter of fact, Figs. 1, 2, 3, 4, 5, 6, which compare our approximations with the numerical solution, showed good confirmation for all cases. Since LT-HPM is expressed in terms of initial conditions for a given differential equation [see (22)], our procedure was aimed to express the approximate solutions in terms of an unknown quantity  $A$ , related to  $y(0)$  or  $y'(0)$ . We noted that the value of  $A$  can be determined requiring that approximate solution satisfies a given second boundary condition, from which one obtain an algebraic equation in terms of  $A$ , whose solution concludes the procedure. The above was systematically shown with our examples and proved to be very efficient.

In the first case study, we found an approximate solution for Gelfand's equation (24), which is subject to Dirichlet boundary conditions. Figure 1 shows the comparison between numerical solution and (44) solutions for  $\varepsilon = 1/2$ . It can be noticed that curves are in good agreement, from which is clear the accuracy of our approximation, as a matter of fact Fig. 2, shows that the biggest absolute error (AE) of (44) is scarcely between 0.0005 and 0.0006, which is remarkably precise, above all taking into account that (44) is just a second order approximate solution for (24).



**Fig. 1** Comparison numerical solution of (24) and LT-HPM approximation (44)



**Fig. 2** Absolute error (AE) between numerical solution of (24) and LT-HPM approximation (44)

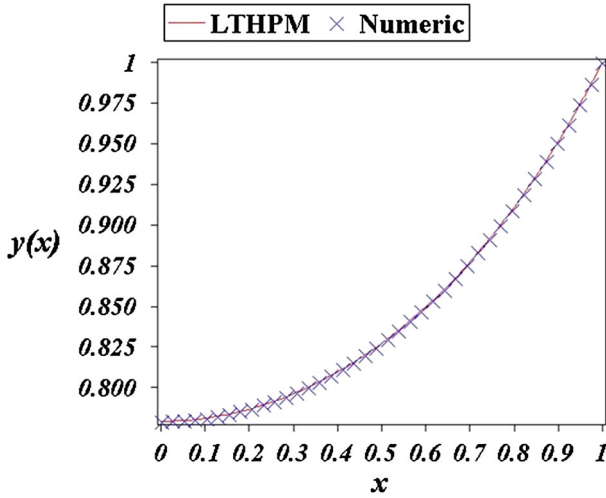


Fig. 3 Comparison numerical solution of (45) and LT-HPM approximation (68)

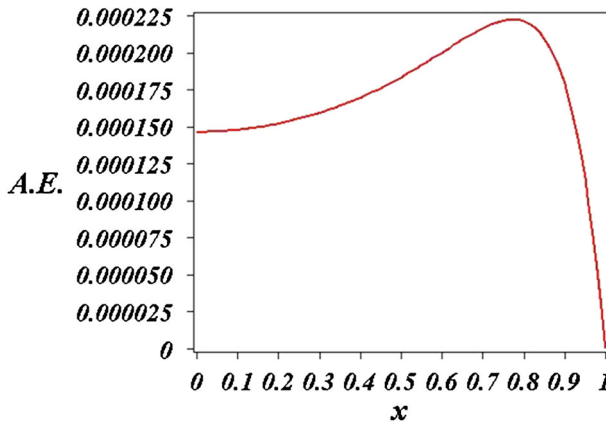


Fig. 4 Absolute error (AE) between numerical solution of (45) and LT-HPM approximation (68)

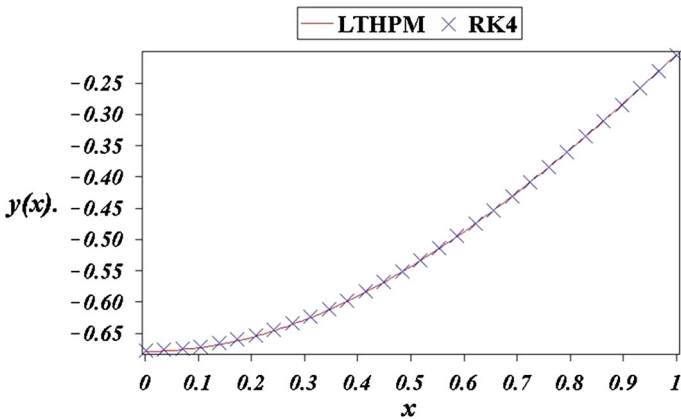
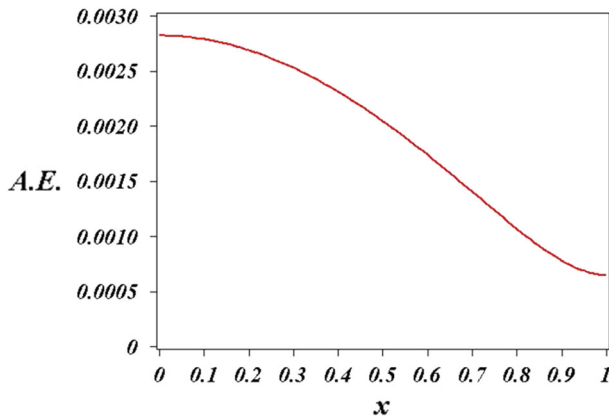


Fig. 5 Comparison numerical solution of (69) and LT-HPM approximation (92)



**Fig. 6** Absolute error (AE) between numerical solution of (69) and LTPHM approximation (92)

Next, we found an approximate solution for temperature distribution equation (45), which is subject to mixed boundary conditions. Figure 3 shows that (68) is an accurate analytical approximate solution for (45); from Fig. 4 we deduce that the biggest absolute error is only 0.000225, whereby the reliability of LT-HPM method in the search for approximate solutions of equations like (45) is clear.

In the last case study, we employed LT-HPM method to find an approximate solution for (69), subject to Neumann boundary conditions. In the same way, we obtained a very precise result, as shown in Figs. (5) and (6), from where it is clear that our fourth-order approximation (92) has an absolute error whose value is between 0.0005 and 0.0030, which is also accurate. From the examples studied, we conclude that the approximate solutions, obtained by using LTHPM are of high accuracy.

## 7 Conclusions

In this paper LT-HPM was employed to provide approximate analytical solutions for nonlinear differential equations with Dirichlet, mixed and Neumann boundary conditions. The proposed procedure is to express the problem of solving a nonlinear ordinary differential equation, in terms of solving an algebraic equation for an unknown condition  $A$  [see (43), (67), and (91)]. Figs. 1,2,3,4,5,6 show the efficiency of this method for solving boundary value nonlinear problems.

The above is an additional advantage for the method, considering that LT-HPM does not need to solve several recurrence differential equations, by which is a tool extremely efficient, useful and precise in practical applications.

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