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# **Distributed Multimedia Synchronization Based on Fuzzy Causal Relations**

by

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Thesis submitted in partial fulfillment of the requirements for the degree of doctor in Computer Science at the National Institute for Astrophysics, Optics and Electronics.

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**Sta. Ma. Tonantzintla, Puebla. 2009**

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# Acknowledgment

This thesis would not have been possible unless the support and the guideline of my phd Advisors Dr. Saul Pomares and Dr Gustavo Rodriguez, thanks for all your advices. Besides, my deepest gratitude to Dr. Pomares's wife by their time and patience when she reviewed the writing of this dissertation.

I am grateful with my doctoral review commite for all their inputs in order to improve the quality of the dissertation, thank you for your time and your dedication to make this work better.

I owe my gratitude to CONACYT by support this dissertation with the scholarship granted.

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# DEDICATION

To my parents  
by teaching me everything.

To my sister  
by give me all her love.

To Mariana  
my inspiration muse.

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# Abstract

In this dissertation, the research is focused on the field of distributed multimedia systems (DMS). One of the main problems in DMS is the data synchronization. Synchronization is concerned with the preservation of temporal dependencies among the application data from the time of generation to the time of presentation. The synchronization problem can be characterized as an event ordering problem. Event ordering addresses the problem of establishing a certain order among the events that occur in a distributed system (DS) according to some particular criteria. The criteria used for event ordering in a DS are: no order, FIFO, causal,  $\Delta$ -causal, total, and causal-total. They mainly differ in the degree of asynchronous execution allowed. One of the most important orderings is the causal order (CO), which is based on Lamport's happened-before relation. It establishes that the events must be seen in the cause-effect order as they occur in the system. However, for certain applications, for example multimedia synchronization, where some degradation of the system is allowed, ensuring the CO based on Lamport's relation is rigid and negatively affects the performance of the system. In this dissertation a new ordering for DS is introduced in order to achieve a more asynchronous execution than the CO. This new ordering is called Fuzzy Causal Order (FCO). In addition, the Fuzzy Causal Relation (FCR) and the Fuzzy Causal Consistency (FCC) are defined. The FCR establishes logical dependencies based on the precedence of events and by considering some kind of "distance" between their occurrences. With the notion of distance it was possible to establish a cause-effect measure between two events  $a$  and  $b$  that indicates "how long ago" an event  $a$  happened before an event  $b$ . Through the FCC, it was possible to determine "how good" the performance of the system is at a given moment. The usefulness of the FCO, FCR and FCC is shown by applying them to the concrete problem of intermedia synchronization in DMS. In order to overcome the synchronization problem based on these concepts, a distributed multimedia model and a synchronization algorithm were designed. In addition, a fuzzy control system to adjust the delivery time of the messages and to determine if a selective message discard must be carried out was designed. The control is tested in three main cases, hard, regular and soft, according to the network conditions of the system.

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# List of original papers

The main contribution of this dissertation was published in the following two papers:

Luis A. Morales Rosales, Saul E. Pomares Hernandez, and Gustavo Rodriguez Gomez, (2009), “Fuzzy Causal Ordering of Events in Distributed Systems”, *Journal of Applied Sciences*, Eds. Asian Network for Scientific Information, Volume 9, Issue 8, 2009, pp. 1441-1449.

Luis A. Morales Rosales, Saul E. Pomares Hernandez, Gustavo Rodriguez Gomez, “Coordination for Synchronous Cooperative Systems Based on Fuzzy Causal Relations”, *International Journal of Computer Science (IJCS)*, Eds. Waset, Vol. 3 No.4, 2008, pp. 270-276.

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## Index of Acronyms

Acronym or Symbol	Definition
<i>DS</i>	Distributed system
<i>DMS</i>	Distributed multimedia systems
<i>CO</i>	Causal order
<i>FCR</i>	Fuzzy causal relation
<i>FCNR</i>	Fuzzy concurrent relation
<i>FCC</i>	Fuzzy causal consistency
<i>FCO</i>	Fuzzy causal order
<i>QoS</i>	Quality of service
<i>FR</i>	Frame rate
<i>GP</i>	Weighting grade
<i>NC</i>	Network conditions
<i>CS</i>	Current state of the system
<i>RTT</i>	Round trip time of a message
<i>R<sub>S</sub></i>	Spatial relation
<i>R<sub>T</sub></i>	Temporal relation
<i>R<sub>L</sub></i>	Logical relation
<i>DR</i>	Distance relation
<i>R<sub>N</sub></i>	Membership function for the temporal distance
<i>R<sub>D</sub></i>	Membership function for the causal distance
$\rightarrow$	Causal relation
$\parallel$	Concurrent relation
$\xrightarrow{\lambda}$	Fuzzy causal relation
$\underline{\lambda}$	Fuzzy concurrent relation
$\overline{EF}$	Synchronization period
$\rightarrow_I$	Happened before relation for intervals
$\parallel\parallel$	Simultaneous interval relation



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# Chapter 1

*“A problem is a chance for you to do your best.”*  
**Duke Ellington(1899-1974)**

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## Introduction

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The advances of distributed systems over wide area networks have increased the research interest of fields such as mobile system, ubiquitous computing and distributed multimedia systems, among others.

In this dissertation the research is focused on the field of distributed multimedia systems (DMS). The distributed multimedia systems have been defined as the exchange of big volumes of multimedia data in a communication network among a group of participants [20]. The term multimedia is defined as the integration and management of data represented as continuous data (audio and video) and/or discrete data (text and graphics); see figure 1. The management refers to the act of capturing, processing, communicating, storing and/or presentation of continuous and discrete data.

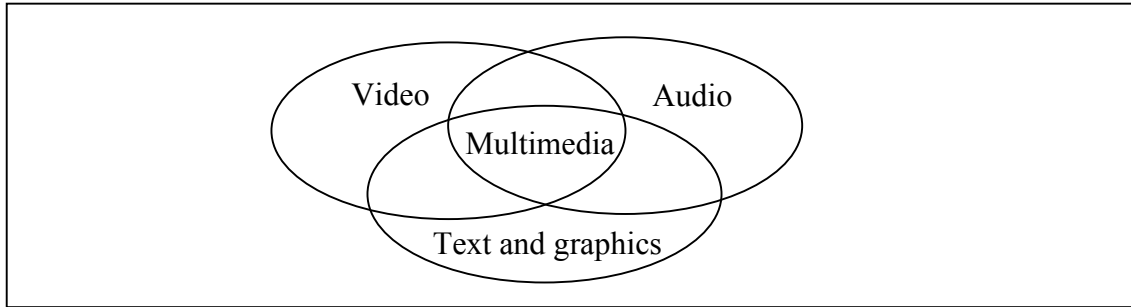


Figure 1. Multimedia information

One of the main problems in DMS is the data synchronization. Synchronization concerns to the preservation of temporal dependencies among the application data from the time of generation to the time of presentation. Among the most important problems in order to carry out the synchronization in DMS, the following ones can be mentioned: the use of heterogeneous data (continuous and discrete), the absence of a global reference and/or shared resources, the geographically dispersed sources, the scalability of the application (support of great number of users) and the quality of services constraints. The *quality of service (QoS)* establishes a set of parameters that must be satisfied for the correct transmission and reproduction of multimedia data. Some of the parameters of the *quality of service* that are considered in this work include: transmission delays, lost of messages and *jitter*<sup>1</sup>.

One example of a distributed multimedia system is a teleconference system, which is depicted in figure 2. In this scenario, we are considering three participants, the participant P<sub>1</sub> sends audio and video; the participant P<sub>2</sub> sends only video while the participant P<sub>3</sub> sends audio, video and slides (still images).

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<sup>1</sup> *Jitter* is the fluctuation of end to end of a message with the next message inside the same stream.



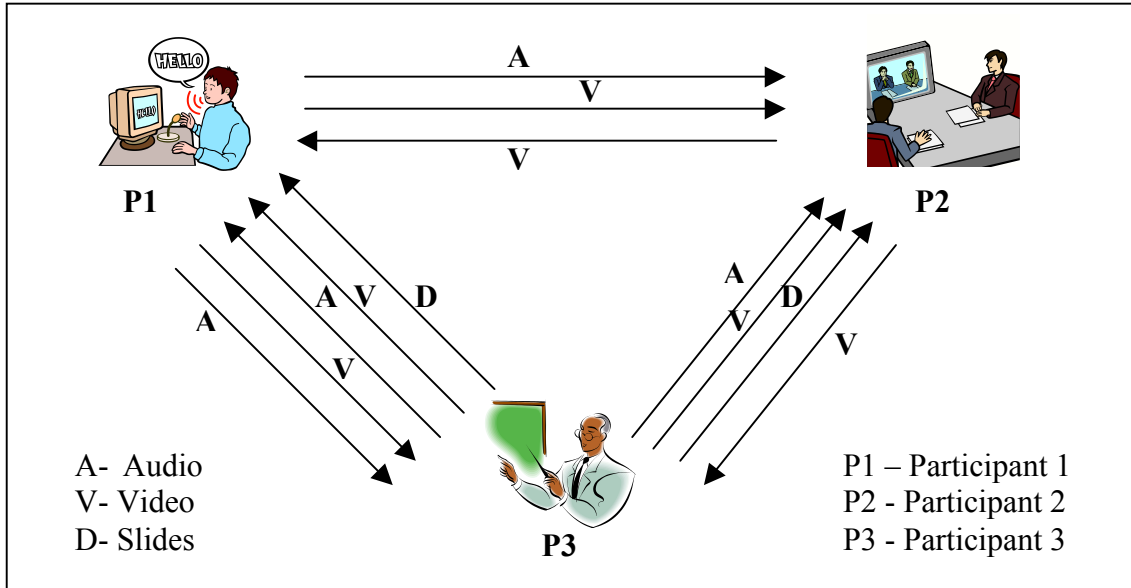


Figure 2. Example of a teleconference in real-time

A formal way to represent the scenario depicted above is presented in figure 3. In this representation the transmission of the data is seen as a stream. Every stream is represented according to the type of data that it transmits. The continuous data (for example, audio and video) is represented as intervals, the discrete data (for example, graphics, text and slides) as timeless points.

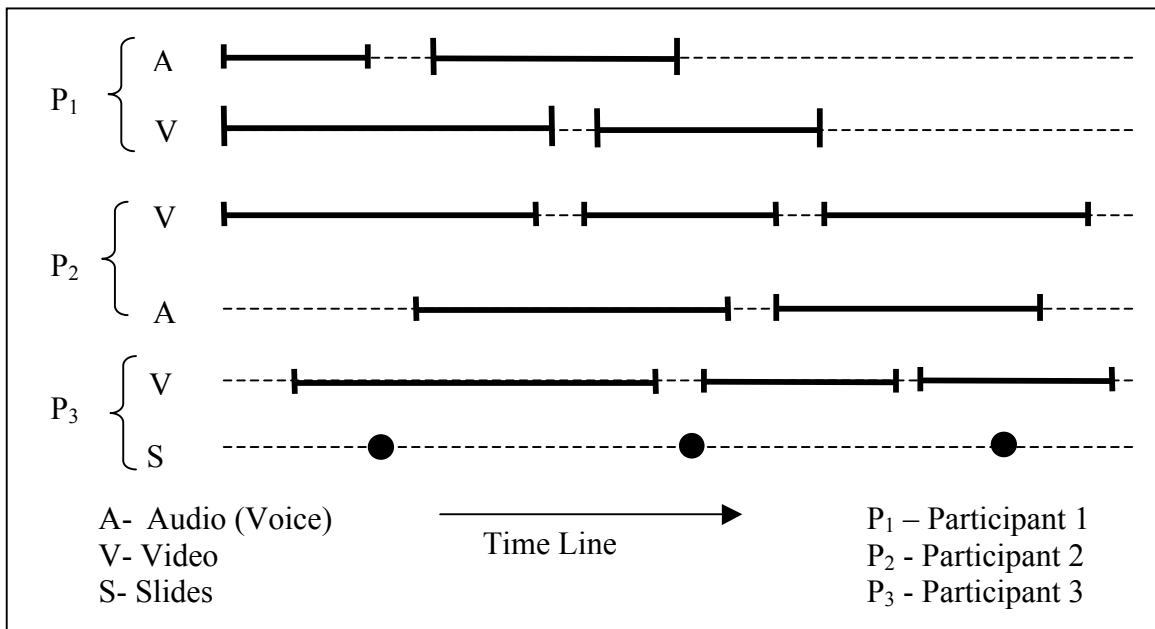


Figure 3. Representation of a multimedia scenario

The works that have been developed to solve the synchronization problem in DMS can be classified into two big branches: *synchronous* and *asynchronous*.

The *synchronous* works use a common reference to assure the synchronization. In this kind of works, the processes or users always have to maintain the same view of the common reference. These works are commonly designed under the paradigm of communication point-to-point. Hence, they present the following problems: bottlenecks, delays in the synchronization, and they are not scalable.

The *asynchronous* works were developed as an alternative proposal with the aim to overcome the disadvantages of the synchronous works. The asynchronous works are focused on assuring the temporal relations between multimedia objects without global references by using logical dependencies (partial order). These works are based on the *happened before relation*, proposed by Lamport in [21], to assure the temporal relations. Some disadvantages of the asynchronous works are: the introduction of random delays at the data delivery and a smaller precision in the synchronization time. On the other hand, works in the asynchronous category that consider constraints for the transmission in real-time are scarce.

## **1.1 Description of the problem**

The area of interest of this research is the achievement of the multimedia data synchronization in a distributed system in real-time. For a better understanding, the context of the synchronization problem has been divided into two parts. In the first one, the system model on which the problem relies is presented. The characteristics showed correspond at the transport level of the communication. In the second part, the problems that arise according to the characteristics of the multimedia data, which correspond to the application level, are described.

### **System model.**

The system model is based on the main characteristics of a distributed system. In our case, the data arrive from asynchronous sources, and the communication is only by message passing. For the communication unreliable channels are assumed; therefore the loss of data

and random delays are considered in the network conditions. In the model a global clock is not used nor are any other shared resources. By achieving the synchronization using the system model described above, diverse questions arise. Two interesting questions that can be remarked are:

- *How can one ensure the temporal dependencies among events arriving from asynchronous sources in the presence of loss data and random delays?*
- *How can one ensure the temporal dependencies among events arriving from asynchronous sources only by message passing without having a common reference like a physical global clock?*

**Multimedia data.** The multimedia synchronization in distributed systems is highly correlated with the data characteristics, which have been divided into two sections for their explanation. In the first section some characteristics according to how the data are generated (in-line or off-line) are presented. In the second section the characteristics regarding to the data heterogeneity (continuous and discrete) are explained.

- **Data generation.** Generally, the synchronization of multimedia data can be classified in two categories according to the way the data are generated. The first category refers to the synchronization on demand, where the data are previously stored and labeled (off-line). The second category is known as synchronization in real-time, where the data are generated in-line (they are neither stored nor pre-labeled). The latter is the focus of our study. An interesting challenge to carry out the synchronization in real-time is:
  - *How it is possible to generate and label the data, without previous knowledge of the system behavior, to assure the synchronization without degrading the quality of the service?*
- **Heterogeneous data.** The multimedia synchronization in distributed scenarios handles heterogeneous data, which have been classified as discrete and continuous. The characteristics of transmission of the continuous and discrete data are not compatible. For example, the continuous data (audio and video) support certain losses but they are sensitive to delays; on the other hand the discrete data (graphics and text) support certain delays but are sensitive to losses. Establishing a balance for

the delivery time among both types of data in a distributed scenario is not an easy task, so the next question that arises is the following:

- *How is a balance in the delivery time among heterogeneous data without degrading the quality of service determined?*

## 1.2 Proposal of solution

As hypothesis in this dissertation, it is claimed that for certain domains where some degradation of the system is allowed, for example, as in the case of scheduling, and intermedia synchronization, ensuring the causal order strictly based on Lamport's relation is still rigid, which can render negative affects to the performance of the system. In this dissertation the research is focused on the domain of intermedia synchronization in distributed multimedia systems. Specifically, in this domain the degradation can refer to the synchronization error allowed among the multimedia data. The synchronization error allowed is correlated with the type of media involved (continuous and/or discrete) and the transmission mode (on-demand or real-time). In order to assure the synchronization and allow an asynchronous execution of the system, some works have used the strict causal order proposed by Lamport. Nevertheless, the use of this order can introduce the halt of the system, discarded data and/or delivery delay of the data, which can result in a negative system performance.

In order to demonstrate the hypothesis established above and carry out the intermedia synchronization in DMS, a new event ordering for distributed systems is introduced, which allows a more asynchronous execution than the causal order proposed by Lamport; this new ordering is called Fuzzy Causal Order (FCO). The FCO is based on two new concepts, the Fuzzy Causal Relation (FCR) and the Fuzzy Causal Consistency (FCC) for distributed systems, which are defined in Chapter 3. The fuzzy causal relation establishes *cause-effect* dependencies among events based not only on their precedence dependencies but also by considering some kind of “*distance*” between the occurrences of the events. By using the notion of “*distance*”, it aims to establish a cause-effect degree that indicates “*how long*

ago” an event  $a$  happened before an event  $b$ . Besides, the Fuzzy Causal Consistency is based on the FCR. By considering some attributes of the addressed problem, it gives information about “*how good*” the performance of the system is at a given moment. There are two hypotheses behind this: first, according to the addressed problem, it is established that “*closer*” events have a stronger *cause-effect* relation; and secondly, events with a stronger *cause-effect* relation have a greater impact (negative or positive) on the performance of the system. While the FCR is directly concerned with the first hypothesis, the FCC deals with the second one.

As a direct result of the application of the FCO to the synchronization problem, a synchronization mechanism for distributed multimedia systems in real-time is presented, which is described in Chapter 4. In this research, a DMS is said to be in *real-time* if the data processing time and its transmission are sufficiently small so that the data reception seems instantaneous to a user; some examples of applications in real-time include: teleconference, tele-immersion and videoconference. The mechanism is classified in the asynchronous category, and it is designed for group communication preserving the main characteristics of a distributed system. The mechanism is based on a distributed synchronization model, which is constructed using the fuzzy casual relation and the fuzzy causal consistency. In order to adjust the delivery time of the data and to overcome the synchronization error, a fuzzy control system is included as part of the mechanism.

### 1.3 Goals

The research presented in this dissertation had the following goals in order to provide a direction to answer each question established at the description of the problem and to demonstrate the hypothesis claimed.

#### General goal

To develop an intermedia synchronization mechanism in real-time for distributed multimedia systems.

### Specific goals

- To define the concepts of fuzzy causal relation, fuzzy causal consistency and fuzzy causal ordering for distributed systems.
- To define a distributed synchronization model based on the concepts of fuzzy causal relation and fuzzy causal consistency.
- To develop a synchronization mechanism based on the model previously defined, considering the following:
  - Transmission in real-time, considering arriving data from different sources, heterogeneous data, and network conditions, such as loss of messages, *jitter* and transmission random delays.
  - Data transmission using the paradigm of group communication (two or more participants) preserving the main characteristics of a distributed system.

## 1.4 Main contributions

The main contribution of this dissertation is the introduction of the following concepts: fuzzy causal relation, fuzzy causal consistency and fuzzy causal ordering for distributed systems. These concepts allow the establishment of a more asynchronous order than the causal relation proposed by Lamport, as explained in Chapter 3.

As a result of the concepts proposed, a new synchronization model for distributed multimedia systems was developed. This model showed the usefulness of the concepts in order to solve problems where certain degradation of the system is allowed.

In addition, a new synchronization mechanism that carries out the synchronization model was designed, which overcomes the main problems identified in most of the works designed for this end, including the halt of the system until the causal delivery is satisfied (strict causal delivery), the discard of some messages that still can be useful for the application ( $\Delta$ -causal delivery condition), and transmission random delays to deliver messages. A fuzzy control system also was proposed to overcome the synchronization error for distributed multimedia systems. This is showed in the simulation of the mechanism in

three main cases, hard, regular and soft, according to the network conditions of the system, which is explained in Chapter 5.

## **1.5 Thesis organization**

Chapter 2 explains the state of the art, which is presented in two parts. The first part includes the related work of multimedia synchronization; the works are classified according to the way the data are generated, the type of synchronization, and the temporal and/or logical dependencies used to carry out the synchronization. The second part presents how fuzzy concepts have been used to solve the synchronization problem.

The main contribution of the research is presented in Chapter 3. This chapter contains the definitions of Fuzzy Causal Relation (FCR) and Fuzzy Causal Consistency (FCC) for distributed systems. Moreover, it introduces a new event ordering for distributed systems based on the FCR and the FCC, which allows a more asynchronous execution than the causal order proposed by Lamport; this new ordering has been called Fuzzy Causal Order (FCO).

Chapter 4 presents the theoretical aspects of the distributed multimedia mechanism. The mechanism is composed of four main components. First, the multimedia synchronization model is presented, which establishes synchronization periods from the endpoints of the intervals. Then, the component of the input variables used by the fuzzy causal consistency and the fuzzy control system is described. After that, the fuzzy causal component shows the application of the fuzzy causal relation and the fuzzy causal consistency to the intermedia synchronization. The last component is the fuzzy control system, which adjusts the messages delivery time and determines if a selective message discard must be carried out.

Chapter 5 describes the distributed multimedia mechanism. In addition, an algorithm that carries out the model and the fuzzy control system is presented to show the usefulness of the FCR and the FCC when applied to the intermedia synchronization problem. On the

other hand, some simulations and results of the behavior of the mechanism under several conditions are presented.

Chapter 6 summarizes the main points of the dissertation and gives future directions of research.



# Chapter 2

*“Study the past if you would define the future.”*  
Confucius(551a.c.-479a.c.)

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## State of the Art

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### 2.1 Introduction

Recently, some Internet applications (e.g. videoconferences and teleconference) involve multimedia data and require enhancements in the performance of the data synchronization. Several works have been developed to satisfy the data presentation in the same way that they were sent from others participants (data synchronization). In this chapter, we give the main differences of how the data synchronization is carried out according to the data generation, on demand or in real-time. In addition, we describe how the temporal dependencies, physical or logical, have been used to solve the synchronization problem. The tendencies are focused on the use of logical dependencies. Hence, we describe the main works based on logical dependencies, namely, causal and  $\Delta$ -causal algorithms. Finally, we explain the key works in which fuzzy concepts have been applied trying to solve the multimedia synchronization problem.

## 2.2 Related work of multimedia synchronization

In this section, we describe the different approaches and mechanism that are used to solve the synchronization. The synchronization works are divided based on how the data are generated, on demand and real-time. In this research, we are mainly interested in the real-time category. Inside this branch, there are two categories: the intra-stream, which is carried out inside one stream, and the inter-stream, which is carried out among several streams in order to maintain the coherence of the applications. Next, we are going to describe in detail each one of the branches of the multimedia classification shown in figure 4.

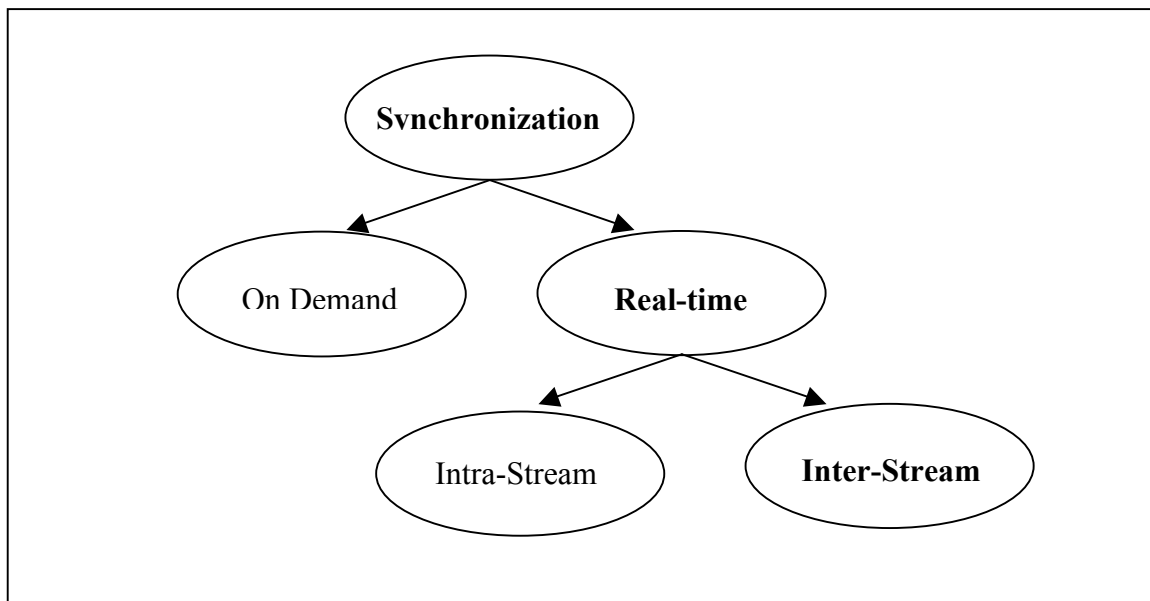


Figure 4. Multimedia classification

### 2.2.1 Synchronization on demand

The synchronization on demand is designed to satisfy temporal dependencies on multimedia data that have been previously stored and labeled. With the synchronization on demand, it is possible to previously establish the behavior of the continuous data (audio and video) and/or discrete data (text, images) that will be presented, using information as the duration and the data sequence. Examples of this type of synchronization can be found in applications such as, on demand request of news or movies [7, 10, 17, 23]. The synchronization on demand principally is carried out by programming languages. The most important of these will be described next.

### **Programming languages**

One of the most common forms to carry out the synchronization on demand is by programming languages. These languages are based on standards for multimedia documents. The standards describe the form in which the data must be synchronized. The languages need to specify in advance the times of synchronization for all the cases that can occur inside the system in order to obtain a good synchronization of the data. Among the most outstanding languages are HyTime, MHEG, and SMIL. Next we will explain each one of them.

The standard HyTime allows the structure description of multimedia documents. It is based on SGML (Standard Generalized Markup Language [15]). HyTime contemplates series of primitives to connect multimedia objects without specifying their type of codification. The primitives are declared in the form of architectures (AF), and they are organized in modules. The AFs are elements with predefined semantics and multimedia attributes. The modules that define the basic concepts of HyTime are: Location-Address-Module, Finite-Coordinate-Space-Module, Event-Projection-Module and Object-Modification-Module [15, 24].

MHEG is a standard oriented to multimedia documents. In MHEG a number of classes is defined when the objects are created in order to design their presentation. There exist several classes that are used to describe the form in which the video is opened, the audio reproduction, the presentation and the grouping of the objects, the way of exchanging information between machines, and the way the user can interact during the presentation. The relations that are created between the instances of the classes determine the structure of the presentation [41, 47].

SMIL (*Synchronization Multimedia Language*) is a standard to make synchronization of multimedia presentations in Internet. SMIL is defined by XML-DTD (*Extensive Markup Language Document Type Definitions* [42]). It defines the schedule of elements to describe the temporal synchronization between multimedia elements. Likewise, it defines an element

of change to choose between the current alternative models and the quality of presentation desired [30, 42].

### **2.2.2 Synchronization in real-time**

The synchronization in real-time is characterized by the in-line data generation, which implies that the data are neither previously stored nor pre-labeled. Among its main characteristics, it can be mentioned that it does not have a previously established time of transmission and has not determined in advance the sequence of events that will be presented along the transmission. In this category, we can find applications such as videoconferences, distributed applications, cooperative work without tolerance delays, etc. The synchronization in real-time can be divided into two categories, intra-stream and inter-stream. The intra-stream synchronization refers principally to the preservation of physical dependencies inside one stream. Some of the main works that have focused on solving the synchronization intra-streams were proposed by Biersack et al. in [7], Haining et al. [10], Hua et al. [13], and Tachikawa et al. [43].

In this dissertation the research is focused on the inter-stream synchronization. The next sections present in detail which are its main characteristics as well as the way in which it is carried out.

#### ***Inter-streams***

The synchronization inter-streams, as opposed to the intra-streams synchronization, is carried out to support logical and physical dependencies between different streams. This type of synchronization becomes difficult to carry out when the streams come from different sources. One of the open problems in this kind of synchronization relies on the distributed environment, where there is neither shared resource nor a global clock. Some of the mechanisms that have been developed to solve the problems of the inter-stream synchronization are based on temporal dependencies (physical time) and logical dependencies (logical time). Sections 2.3 includes detailed descriptions of some works that have been developed using these kinds of dependencies. Due to the importance that this category represents for the present dissertation, we dedicate the following section to present its most important characteristics.

## 2.3 Synchronization Inter-streams

The inter-stream synchronization is concerned with maintaining the temporal and/or logical dependencies among several streams in order to present the data in the same view as they were generated. There are two main approaches that try to solve the inter-stream synchronization; these are called synchronous and asynchronous. The difference among these two approaches involves the asynchrony allowed for the system in order to maintain a good performance of the system. We show in figure 5 the classification of the inter-stream synchronization based on the temporal relations used and the grade of asynchrony of the system.

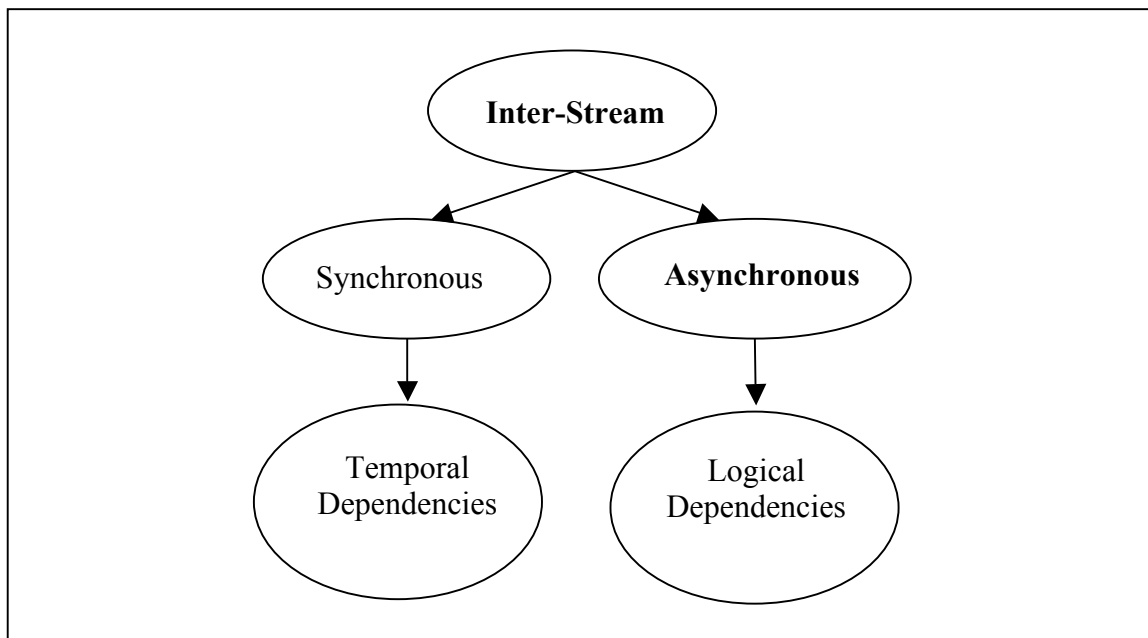


Figure 5. Classification of the inter-stream synchronization

In order to explain the differences between the synchronous and asynchronous works, we will first explain the temporal dependencies used by these works in order to solve the inter-stream synchronization problem.

### **Temporal dependencies**

The temporal dependencies are associated with physical time clocks to determine the event ordering. The use of physical clocks facilitates the synchronization because the exact time

in which the events happen is known. Nevertheless, synchronizing the clocks of the involved sources is not an easy task, especially when this task wants to be established in a distributed system. There are two main ways to synchronize physical clocks, either in a centralized or in a distributed way. In the centralized way the synchronization task is delegated to a server; all the participants send their events to the server and only the clocks between the server and each of the participants are synchronized in order to establish the correct event delivery. We can find another example of this type of synchronization when a multiplexor is used in the transmission of audio and video, resulting in only one stream, labeling the resultant stream with a mark of a physical clock. The centralized mechanism, although very simple, is not efficient since it introduces the bottleneck effect and delays at the rebroadcasting of the events. On the other hand, in a distributed environment it is difficult to support this type of clock synchronization because, in this environment every clock is independent, and they do not work exactly at the same speed. A way of carrying out the synchronization in distributed environments is using a physical virtual time in order to allow all the participants to have the same time reference.

### **Logical dependencies**

The temporal logical dependencies are associated with a logical time clock to label each one of the events that occur in the system. In other words, they use a numerical labeling to know the order in which the events occur in time. With the logical dependencies, the bottleneck effect is avoided, but the random delays at the event delivery still remains. To guarantee the delivery order of events, using logical dependencies, the most used mechanisms are the causal and the  $\Delta$ -causal algorithms. These algorithms are used when it is desirable to carry out the synchronization in a distributed environment.

Next, we will describe the *synchronous* and *asynchronous* works that use the temporal dependencies presented above to solve the distributed multimedia synchronization.

#### **2.3.1 Synchronous works**

The *synchronous* works commonly use temporal physical dependencies and a common reference to assure the synchronization. Some of the common references used for the data

labeling, resulting in the correct order of delivery (process of synchronization), are the global clocks (physical or virtual), shared memory, synchronization out of line, etc. [48, 51] In this type of works, a view of the common reference is always maintained. These works are commonly designed under the concept of communication point-to-point hence they have the following problems: bottlenecks, delays in the synchronization and in addition they are not scalable. The principal mechanisms developed under this characteristic are based on centralized schemes, retransmission of information and pre-labeled data.

Some of the most important synchronous works that use a physical clock time to carry out the task of synchronization are described next.

Haindl et al. in [25] proposed levels of hierarchy to achieve different levels of granularity at the moment to carry out the synchronization. Also, physical time clocks are used to label every group of packets sent in intervals, so it is possible to know the duration time of the intervals to carry out the synchronization. The packet that delimits the beginning of every interval is used to synchronize them. The form of synchronization follows the master-slave scheme, where if several streams exist, one of them works as master while the rest work as slaves who must be synchronized with the master stream.

Agarwal et al. in [28] developed a mechanism to make the synchronization of multimedia data. In this work, they used a server of multimedia data (synchronization server) based on the normalization of physical time clocks. First, they gather the data to transmit at the server, which normalizes the clocks of all the participants. Once it is synchronized by the server the information is re-transmitted to every participant involved. The model used is based on Petri nets proposed by Wahl et al. in [48], (OCPN, Object Composition Petri Net).

A mechanism to synchronize continuous data using physical time dependencies for the reproduction of the packets was developed by Cameron et al. in [12]. The synchronization algorithm is called VTR (virtual time rendering). The form in which the proposed mechanism works is exemplified in [17]. The algorithm VTR established an inter-stream and intra-stream synchronization. It uses a physical clock for labeling the packets and

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calculates the time in which the packets must be reproduced based on the obtained information from the sending time and the arrival time of the packets. This is done by using established equations. The algorithm uses the concept master-slave, where a master stream is used to synchronize the rest of the streams. An extension of these works was presented by Zhu et al. in [13], where a  $\Delta$ -causal algorithm is included to determine the life time of the packets in order to assure the packet delivery order. Nevertheless, Cameron assumed that the clocks used are globally synchronized.

A protocol to synchronize multimedia streams is presented by Dommel et al. in [9]. This work proposes a multipoint synchronization protocol (MSP). The mechanism is coordinated by means of the physical time. Besides, it works for several groups and for several network conditions by using multicast communication if it is available. MSP operates as a covering service using a backbone to reference the nodes. The protocol is adaptable according to the network conditions, and it uses the concept of virtual global clock.

Several standards have been proposed for the synchronization of multimedia data. Among the most out-standing of these, we can mention the standard MPEG [50] and the standard H.323 [29]. The main characteristic of both works is the use of a multiplexer to guarantee the data synchronization. Therefore, both works present the disadvantage of introducing the bottleneck effect and delays in the sending and reception time of the data.

Liu et al. in [10] developed a mechanism to carry out the data synchronization using a virtual clock. They define equations for calculating the synchronization error in real-time between the sender and receiver in order to indicate the adjustment of clocks to minimize the error. Basically, the scheme of master-slave is used, where a master stream exists and the rest of the streams are synchronized to the master.

Duda et al. in [4] presented a model that introduces the idea of a virtual observer considering as hypothesis bounded delays in the network. The virtual observer defines the temporal relations that must be preserved, whether these are inter-stream and intra-stream.

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In this work the concept of “*multimedia presence*” is introduced to synchronize streams from different sources. The multimedia presence refers to the set of streams produced or controlled by a participant in a meeting. The algorithms proposed are adaptable and are based upon the labeling of physical time to synchronize the streams. A global clock synchronization of the participants is not assumed. Nevertheless, it is considered that all the clocks advance at the same time. The model satisfies the intra-stream and inter-stream synchronization for interactive applications in the Internet.

Another interesting protocol was proposed by Abouaissa et al. in [1]. In this work, a real-time causal protocol that works in a distributed environment is presented. The  $\Delta$ -causal algorithm is used to do the synchronization, which takes into account the lifetime of the information. A characteristic of the protocol in order to assure the restrictions of real-time is that it uses a main virtual physical time. At the beginning of the meeting all the clocks are synchronized with the main clock; later the time of the main clock is sent periodically to all the participants to continue with the synchrony of the clocks.

### **2.3.2 Asynchronous works**

The *asynchronous* works arose as an alternative proposal that reduces the disadvantages of the synchronous works. The asynchronous works are focused on assuring the temporal relations between multimedia objects without global references by using logical dependencies (partial order). Some disadvantages of the asynchronous works are: the introduction of random delays at the data delivery and less precision in the synchronization time. On the other hand, works in the asynchronous category that consider restrictions for the transmission in real-time are scarce.

Next, we describe the main works based on logical dependencies (causal and  $\Delta$ -causal algorithms) to solve the synchronization problem.

A mechanism to identify causal relations between streams of information (audio, video, text and images) was proposed by Courtiat in [16]. The mechanism is designed to assure the

causal relations expressed at a user level in order to guarantee which relations must be preserved at the data delivery. The mechanism uses a global time and considers a master stream, to which the other streams will have to be synchronized. The specification of the mechanism is an extension of the formal description technique RT-LOTOS.

A causal algorithm for multimedia synchronization in real-time was presented by Baldoni et al. in [34-37]. These works use a  $\Delta$ -causal algorithm to satisfy time constraints. Among the principal characteristics of these works is the use of a global clock to label the data in order to determine the occurrence of the events. The  $\Delta$ -causal algorithm used to assure the delivery order labels the events with regard to a global time, which known how the events occurred in the system and how the algorithm can determine a deadline for the delivery of the events.

Tachikawa et al. defined a type of causality called  $\Delta^*$ -causality in [44]. This work is focused on group communication for WAN environments. The  $\Delta^*$ -causality considers the delay in the network, the data deadline and the order of occurrence of the events to determine their precedence. In this work, every participant of the group needs to know the delay and the loss rate of the events of all the participants; this is needed in order to calculate the deadline of the data. Another characteristic is the retransmission of the data to assure that they are received by all participants, which is possible to support the data loss.

A group communication protocol to synchronize continuous data in real-time was presented by Tachikawa et al. in [45]. In this work, the protocol makes a segment delivery based on their causal dependencies determining a deadline for the delivery of the segments. In this work a segment is composed of a sequence of packets. The synchronization is focused in assuring the delivery according to the dependency between segments and not between packets. A segment can be delivered at the application only until it has been completely received. Nevertheless, Tachikawa considered the loss of some packets of a segment. A characteristic of the protocol is that all the participants have the same time in its physical clock, which is viewed as a global clock to determine if a segment can be delivered

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according to its deadline constraints.

Shimamura et. al. in [38, 39] proposed some precedence relations called *O- precedent*, which were designed on the object concept. In these works an object is represented as a sequence of messages. Shimamura defined six *O-precedent* relations: *top - precede*, *tail - precede*, *partially - precede*, *fully - precede*, *inclusive, precede* and *exclusively precede*. These relations contemplate the send and receive events of the objects as well as their beginning and end to determine each one of the relations. Shimamura proposed a protocol to synchronize multimedia objects among a group of participants, called COM (*causally ordered multimedia*). The protocol is based on the *O-precedent* relations. In the protocol, the objects are delivered to the application until they have received all the messages that compose them and their delivery order is established. The order of delivery is established by the relations *O- precedent*. The extension to these works was developed by Enokido in [49]. In this case, the extension includes relations for the cases: *multicast* (a message is sent to multiple sources), *parallel-cast* (different messages are sent at the same time to different sources), *conjunctive-receipt* (the destination will be blocked until all the messages are received from all the sources) and *disjunctive-receipt* (the destination will be blocked until a message is received from at least a source of objects). Another extension to the work of Shimamura was proposed by Timura in [52]. The extension introduces a synchronization message to segment an object. This message can be sent periodically or in any moment to make the segmentation. With the synchronization message, the object segmented is delivered to the application without waiting until the object is completely received.

Morales et al. in [26, 27] proposed an algorithm to synchronize continuous data in real time. The algorithm was designed using a synchronization model, which is based on an extension to Lamport's *happened-before* relation applied on interval level. The synchronization is achieved based on their logical dependencies among intervals. In order to reach the continuous media synchronization Morales worked at two levels. At a higher level, a stream was represented as an interval. At a lower level, an interval is defined as a finite set of sequential discrete events. The work is focused on the lower level, where it was shown that it is sufficient to ensure a partial order between some single events (endpoint intervals) to ensure the causal order on interval level. In order to minimize the control

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overhead, they proposed an extension of the Immediate Dependency Relation applied on interval level. Some of the characteristics of the algorithm include the absence of a global clock and assumption of reliable communication channels. Nevertheless, Morales considered random delays at the data transmission. Some disadvantages of Morales's work are the introduction of delays at the data delivery and the halt of their system if there is loss of messages.

## **2.4 Fuzzy distributed multimedia synchronization**

This section is presented in two parts. In the first one, the main works that have included the concept of fuzzy relation are explained. The second one includes the works that have used some concepts of fuzzy logic in order to solve the problem of inter-stream synchronization.

### **2.4.1 Fuzzy relation**

The fuzzy relation is widely used in the fuzzy logic area. This relation indicates in a broad sense the degree of compatibility among two concepts. The first work to introduce the concept of fuzzy causal relation deals with the Fuzzy Cognitive Maps to establish a fuzzy causal relation, and a degree of affectation among events or concepts of a system. Fuzzy cognitive maps (FCM) are fuzzy weighted directed graphs with feedback that create models for emulating the behavior of complex process using fuzzy causal relations, see Aguilar [2]. However, the concept of fuzzy causal relation used for the FCM cannot be applied for the event ordering in distributed systems because to construct the fuzzy weighted directed graph for a system, the degree of affectation of all events in the system must be known. It should be observed that the FCMs are constructed off-line.

Badaloni and Giacomini in [40] integrate ideas of flexibility and uncertainty into Allen's interval-based temporal logic and define an interval fuzzy algebra  $IA^{\text{fuzz}}$ . This work deals with the qualitative aspect of temporal knowledge for the solution of planning problems and prioritized constraints to express the degree of satisfaction needed. Badaloni and Giacomini just label the different relations among intervals with a degree of satisfaction that the search of the solution must satisfy. In addition, they must also know in advance the

behavior and the relations of the system, so the interval fuzzy algebra cannot be applied for the event ordering in distributed systems.

### **2.4.2 Inter-stream synchronization using fuzzy logic concepts**

Some of the main works that have included concepts of fuzzy logic in distributed systems are focused on trying to solve the multimedia synchronization problem on demand, which consists in assuring the temporal appearance order of the data at the reception of every participant as they were sent. This problem is in essence an event ordering problem. It is important to remark that none one of these works have developed the concepts of fuzzy causal relation neither the fuzzy causal consistency for distributed systems, nor a solution that can be applied for the synchronization in real time using fuzzy concepts in a DMS as it is presented in this work. On the other hand, these works can be classified as synchronous; therefore, they present the same disadvantages mentioned in section 2.3.1.

Zhou and Murata in [54] presented a temporal petri-net model called Extended Fuzzy Timing Net for distributed multimedia synchronization. Among its main characteristics, the authors take into account temporal uncertain requirements, making a measurement of the quality of services parameters required by the application in order to check if they are satisfied. This work use a trapezoidal membership function to calculate and to know if the data are synchronized (*e.g.* audio and video). The model is based on the concept of master-slave to carry out the synchronization. Extended Fuzzy Timing Net model needs a set of forward relations between multimedia objects, which are specified by the designer of the application.

Janakiraman et al. in [32, 33] give algorithms for the broadcasting of video on demand. In this work, the *fuzzycast* concept is introduced it consists in determining the delivery order of data based on the technique of the nearest neighbor taking into account the generation time of data. The authors use parameters such as available bandwidth, transmission delay, buffer space and a server for the data transmission to all the participants of the group.

Coelho et al. in [3] presented a methodology for the high level specification and decentralized coordination of temporal interdependences among objects of multimedia documents. In this work, it is introduced the use of the causality to establish fuzzy rules to carry out the multimedia synchronization. Nevertheless, the authors did not propose a fuzzy causal relation for event ordering events in distributed systems; they used the causal relation proposed by Lamport, which halt the system if a message is lost. The main characteristics of their work are: the specification is made by the user using *fuzzy scripts*, indicating how the events will have to be synchronized. In addition, Coelho et al. in [3] classify the entities that compose the scenes to verify the consistency of their temporal relations and have to indicate explicitly the synchronization mechanism that will be associated with every multimedia entity. The fuzzy parameters for the synchronization are also explicitly defined by the designer of the application. The researchers use a global reference to determine the synchronization time, as well as a producer-consumer scheme to establish synchronization points, which introduce bottlenecks at the data delivery. The specification is made offline, so the desirable behavior of the objects reproduction has to be defined in advance.

# Chapter 3

*“The significant problems we have cannot be solved at the same level of thinking with which we created them.”*  
Albert Einstein(1879-1995)

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## Fuzzy Causal Ordering for Distributed Systems

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### 3.1 Introduction

In a distributed system (DS), it is not always feasible in practice to synchronize physical time across different processes within the system in order to make the event ordering. Hence, the processes can use the concept of a logical clock based on the events through which they communicate to establish the events ordering. A *logical clock* is a mechanism for capturing chronological and causal relationships between events in a distributed system.

In DS there are three kinds of events: *internal*, *send* and *receive* events. The internal events occur inside a process, and they are never known by the rest of the processes. On the other hand, the *send* and *receive* events are those through which the processes communicate and

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cooperate. In this dissertation, only the *send* and *receive* events are considered since they modify the global state of a system.

The event ordering in a DS consists in establishing a certain order among the events that occurs regarding to some particular criteria. According to the chosen criteria, the resulting event ordering allows a greater or smaller degree of asynchronous execution. There are two broad categories for event ordering used in distributed systems: total ordering and partial ordering.

For total ordering, there are two variants: total-causal order and total order. The *total-causal order* is the strictest ordering in a distributed system; it establishes only one linearization for all the participants, consistent with the causal ordering, among all the events that occur in the system, even those that occur concurrently. For that reason, the execution of the system is considered as synchronous. On the other hand, the *total order* establishes a sequential order for all the events that occur in the system without ensuring the causal order.

The partial ordering presents two variants: the causal order proposed by Birman [5] and the  $\Delta$ -causal order proposed by Baldoni [34-37]. Both of them are exclusively based on the *happened-before* relation defined by Lamport [21]; the main difference is that the  $\Delta$ -causal considers that the events have an associated *lifetime*. The *causal order* establishes that for each participant in the system the events must be seen in the *cause-effect* order as they have occurred, whereas the  $\Delta$ -causal order establishes that the events must be seen in the *cause-effect* order only if the *cause* has been seen before its lifetime expires. Otherwise, the *cause-effect* is considered to be broken, and therefore inexistent.

Partial ordering is important since it allows that the *ordering view* concerning the set of events  $E$  of a system to differ among the participants; however, it does ensure that for a subset of events  $E' \in E$ , all participants will have the same consistent view according to the chosen criteria. The smaller is  $E'$ , and the fewer ordering constraints are required, the more asynchronous is the system since there are less events to order and less constraints between



the events to accomplish. It is important to note that no type of event ordering is better than another. Each event ordering is meant to be used in a particular type of problem, where it ensures the necessary ordering so as to satisfy its consistency constraints.

In this dissertation, it is claimed as hypothesis that for certain domains, such as scheduling, planning, and intermedia synchronization, where some degradation of the system is allowed, ensuring the causal order strictly based on Lamport's relation is still rigid, which can render negative affects to the performance of the system (e.g. the halt of the system, discarded data and delivery delay of the event). The allowed degradation differs in each domain according to the problem to solve. For example, in the scheduling domain for complex problems, optimal schedulers are computationally heavy, and in some cases it is practically impossible to construct them. In these cases, it is preferable to use a near-optimal scheduling, which ensures a minimum of application requirements, such as bandwidth, access time, and lost rate. In the planning domain, sometimes it is not possible to carry out the entire set of tasks since they have some conflict among them. Therefore a planner can identify what tasks must be executed in order to satisfy the maximum number of constraints, and therefore, maximize the performance of the system. In the domain of intermedia synchronization, the degradation can refer to the synchronization error allowed among the multimedia data. For example, the synchronization error for a dialogue among participants (audio-audio streams in real time) is acceptable if it is within  $\pm 120ms$ .

In this chapter, a new event ordering for distributed systems is introduced that allows a more asynchronous execution than the causal order proposed by Lamport; this new ordering is called Fuzzy Causal Order (FCO). The FCO is based on the fuzzy causal relation (FCR) and the fuzzy causal consistency (FCC) that will be defined in the following sections. The fuzzy causal relation establishes cause-effect dependencies among events based not only on their precedence dependencies but also by considering some kind of "*distance*" between the occurrences of the events. By using the notion of "*distance*", it aims to establish a cause-effect degree that indicates "*how long ago*" an event *a* happened before an event *b*. Besides, the fuzzy causal consistency is based on the FCR, by considering some attributes of the addressed problem, it gives information about "*how good*" the performance

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of the system is at a given moment. There are two hypotheses behind this: first, according to the addressed problem, it is established that “closer” events have a stronger cause-effect relation; and secondly, events with a stronger cause-effect relation have a greater impact (negative or positive) on the performance of the system. While the FCR is directly concerned with the first hypothesis, the FCC deals with the second one.

The usefulness of the fuzzy causal order is showed in chapter 4 by applying it to the concrete problem of intermedia synchronization in a distributed multimedia system (DMS), where a certain synchronization error in the system is allowed according to the type of media involved whether it is continuous and/or discrete, as well as the transmission mode (on-demand, or real-time).

### 3.2 The system model

**Processes.** The application under consideration is composed of a set of processes  $P=\{i, j, \dots\}$  organized into a group that communicate by broadcasting asynchronous message passing. In this case, the members of the group  $g$  are defined as  $Memb(g)=P$ .

**Messages.** The system considers a finite set of messages  $M$ , where each message  $m \in M$  is identified by a 2-tuple (*participant, integer*),  $m=(p,x)$  where  $p \in P$  is the sender of  $m$ , denoted by  $Src(m)$ ,  $x$  is the local logical clock for messages of  $p$ , when  $m$  is broadcasted. The set of destinations  $Dest(m)$  of message  $m$  is composed of the participants connected to the  $Group(Dest(m)=Memb(g))$ . The messages sent by the process  $p$  are denoted by  $M_p = \{ m \in M : Src(m) = p \}$ .

**Events.** Let  $m$  be a message, it is denoted by  $send(m)$  the emission event of  $m$  by  $Src(m)$ , and by  $delivery(p,m)$  the delivery event of  $m$  to participant  $p$  connected to  $Group(m)$ . The set of events associated to  $M$  is then the set:

$$E = \{send(m) : m \in M\} \cup \{delivery(p,m) : m \in M \wedge p \in Dest(m)\}.$$

An emission event,  $send(m)$ , where  $m=(p,x)$  may also be denoted by  $send(p,m)$  or  $send(m)$  without ambiguity. The subset  $E_p \subseteq E$  of events involving  $p$  is:

$$E_p = \{send(m) : k = Src(m)\} \cup \{delivery(p, m) : p \in Dest(m)\}.$$

**Intervals.** Let  $I$  be a finite set of intervals, where each interval  $A \in I$  is a set of messages  $A \subseteq M$  sent by a participant  $p = Part(A)$  defined by the mapping  $Part: I \rightarrow P$ . Formally,  $m \in A \Rightarrow Src(m) = Part(A)$ . Owing to the sequential order of  $Part(A)$  for all  $m, m' \in A$ ,  $m \rightarrow m'$  or  $m' \rightarrow m$ . Let  $a^-$  and  $a^+$  be the endpoint messages of  $A$ , such that for all  $m \in A : a^- \neq m$  and  $a^+ \neq m$  implies that  $a^- \rightarrow m \rightarrow a^+$ .

### 3.3 Background and definitions

Some basic definitions are described in this section in order to understand the fuzzy causal relation. In addition, these definitions are used to clarify the main differences between the strict causal relation, the  $\Delta$ -causal relation and the fuzzy causal relation.

#### Happened-before relation proposed by Lamport

Lamport in [21] proposed the *happened-before relation* for events ordering in DS. With the introduction of the *happened-before relation* was possible to maintain the synchronization, coordination and/or consistency between events in a fully distributed manner. Some of the important hypotheses of Lamport's work are: the delivery time of the events is considered finite but unbounded and there is not message loss. The happened-before relation also known as causal relation was defined as follows:

**Definition 1.** The causal relation " $\rightarrow$ " is the least partial order relation on the set  $E$  that satisfies the three following conditions:

- If  $a$  and  $b$  are events belonging to the same process and  $a$  was originated before  $b$  then  $a \rightarrow b$ .
- If  $a$  is the *send* message of a process and  $b$  is the reception of the same message in another process, then  $a \rightarrow b$ .
- If  $a \rightarrow b$  and  $b \rightarrow c$  then  $a \rightarrow c$ .

By using " $\rightarrow$ ", Lamport defines that two events are concurrent denoted by " $a \parallel b$ " as follows:

$$a \parallel b \text{ if } \neg (a \rightarrow b \vee b \rightarrow a)$$

In order to illustrate the properties of the causal relation let us consider the example of the figure 6. The horizontal lines represent the physical time. Each point represents the events that occur during an interval time. In figure 6 can be observed that the event  $b$  precedes the event  $c$ , denoted by  $b \rightarrow c$ . In other words, the event  $b$  is causally related with the event  $c$ .

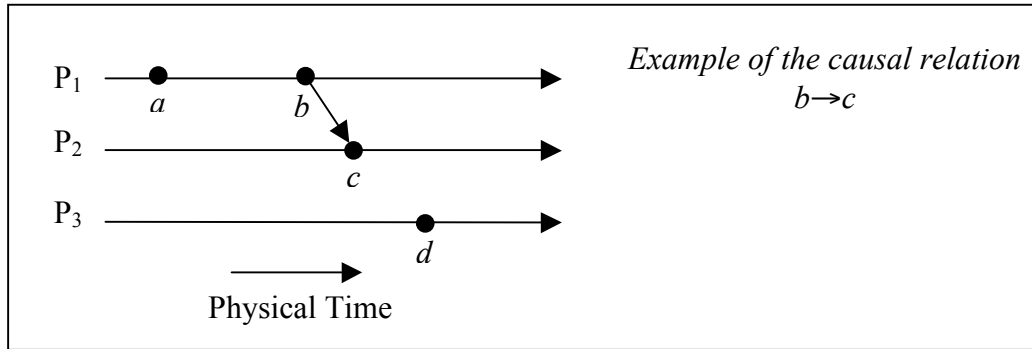


Figure 6. Example to visualize the properties of the causal relation

An important contribution derived from Lamport's work is that it allows to carry out the event ordering using logical clocks without the need for a common reference or a global clock. For more details, see the works of Kshemkalyani [19], Fidge [8], and Lamport [21].

### Causal order delivery proposed by Birman

Birman in [5] defined for group communications the causal delivery order that fully satisfies the properties of the causal relation proposed by Lamport. Formally, it was defined as follows:

**Definition 2.** The causal order delivery must satisfy the following condition:

$$\text{If } \text{send}(m) \rightarrow \text{send}(m') \Rightarrow \forall p \in \text{dests}(m) \cap \text{dests}(m') : \text{delivery}(m) \rightarrow \text{delivery}(m')$$

In general terms Birman's definition established for group communication that a behavior or set of behaviors satisfies the causal order delivery if the diffusion of a message  $m$  causally precedes the diffusion of a message  $m'$ , and the delivery of  $m$  causally precedes the delivery of  $m'$  for all participants that belong to the destinations of  $m$  and  $m'$ .

### $\Delta$ -Causal order delivery proposed by Baldoni

The  $\Delta$ - causal relation was introduced by Baldoni in [34-37] as an extension to Birman's work. The  $\Delta$ - causal relation assigns a lifetime to the events, which allows supporting loss of messages, by preserving the order of precedence established by Lamport. The  $\Delta$ -causal delivery is formally defined as:

**Definition 3.** A distributed computation  $\hat{E}$  satisfy a  $\Delta$ -causal order if:

- All the messages  $M(\hat{E})$  that arrive in  $\Delta$  are delivered in  $\Delta$ , all others are never delivered (they are considered to be lost or discarded);
- All the events of delivery satisfy a causal order.

Where  $\hat{E}=(E, \rightarrow)$  is a set of events partially ordered (*send* and *delivery*) and  $M(\hat{E})$  is the set of all the messages exchanged in  $\hat{E}$ .

### 3.4 Fuzzy causal relation and fuzzy causal consistency

In this section, the fuzzy causal relation (FCR) and the fuzzy causal consistency (FCC) for distributed systems are introduced. These can allow a more asynchronous execution than the causal order proposed by Lamport; this new ordering is called Fuzzy Causal Ordering and will be defined in the following section.

#### 3.4.1 Fuzzy causal relation

The fuzzy causal relation (FCR) is denoted by " $a \xrightarrow{\lambda} b$ ". The FCR is based on a notion of "*distance*" among the events. The *distance*, according to the addressed problem, can be established considering three main domains: *spatial*, *temporal* and/or *logical*. The reference for the logical domain is the event ordering based on Lamport's relation. Using the notion of *distance*, the FCR establishes a *cause-effect* degree that indicates "*how long ago*" an event  $a$  happened before an event  $b$ .

The *distance* between events is determined by the fuzzy relation  $DR: E \times E \rightarrow [0, 1]$ , which is established from the union of sets of membership functions,  $R_S$  (spatial),  $R_T$  (temporal), and  $R_L$  (logical), one set for each domain. It is formally defined as follows:

$$DR(a,b) = R_S \cup R_T \cup R_L$$

Where:

$$R_S = R_1 \cup R_2 \cup \dots \cup R_o$$

$$R_T = R_1 \cup R_2 \cup \dots \cup R_r$$

$$R_L = R_1 \cup R_2 \cup \dots \cup R_s$$

The number of membership functions,  $R_i$ , by each domain is determined according to the problem to solve. The fuzzy union operator chosen for intra and inter domains is the *max* operator  $\max(R_1, \dots, R_k)$ . The union and the maximum operator were chosen because we need to determine the maximum *cause-effect* relation that exists among the events. This means, the operator reflects the maximum *distance* among the events according to the chosen domains. An example of how the  $DR(a,b)$  can be calculated is showed in section 4.4.1.

In this dissertation, one assumption considered for the FCR is that “*closer*” events have a stronger *cause-effect* relation, according to the addressed problem. For this reason, it is established that the  $DR$  grows monotonically and it is directly proportional to the *spatial*, *temporal* and/or *logical distances* between a pair of events. This means, for example, that a  $DR(a,b)$  with a value tending to zero indicates that the events  $a$  and  $b$  are “*closer*”.

It is important to remark that the  $DR$  cannot determine precedence dependencies among events, it only indicates certain *distance* among them. For example, the value of the distance between the events  $a$  and  $b$  gives an equal value for  $DR(a,b)$  or  $DR(b,a)$  because the distance relation is not considering the precedence among them. Hence, in order to establish a *cause-effect* degree (fuzzy precedence) among events, the Fuzzy Causal Relation is formally defined by using the values of the  $DR$  as follows:

**Definition 4.** The fuzzy causal relation “  $\xrightarrow{\lambda}$  ” on a set of events  $E$  satisfies the two following conditions:

$$a \xrightarrow{\lambda} b \text{ If } a \rightarrow b \wedge 0 \leq DR(a,b) < 1$$

$$a \xrightarrow{\lambda} c \text{ If } \exists b \mid a \rightarrow b \rightarrow c \wedge DR(a,b) \leq DR(a,c) : DR(a,b), DR(a,c) < 1$$

The first condition establishes that two events  $(a, b)$  are fuzzy causal related if  $a$  happened before  $b$  and the value of the  $DR(a,b)$  is smaller than one. The second condition is the transitive property. This condition establishes that two events  $(a, c)$  are fuzzy causal related if there exists an event  $b$  such that  $a$  happened before  $b$ , and  $b$  happened before  $c$ . Moreover, the values for  $DR(a,b)$ ,  $DR(a, c)$  monotonically grow and they are smaller than one. If any of these conditions are satisfied, the value of the  $DR(a,b)$  determines the *cause-effect* degree between the present pair, and it is represented by  $FCR(a,b)$ . In any case when the value of the  $DR(a, b)$  is equal one, this means that the events do not have a *cause-effect* relation.

By using Lamport’s relation, a pair of events are concurrent if  $\neg (a \rightarrow b \vee b \rightarrow a)$ , expressed as “ $a \parallel b$ ”. In this work, based on the value of the  $DR$ , the concept of Fuzzy Concurrent Relation ( $FCNR$ ) is formally defined as:

**Definition 5.** Two events are *fuzzy concurrent* “  $a \underline{\underline{\lambda}} b$  ”, if the following condition is satisfied:

$$a \underline{\underline{\lambda}} b \text{ If } \neg (a \rightarrow b \vee b \rightarrow a) \wedge ( (DR(a, b) = DR(b, a)) < 1)$$

A fuzzy concurrent relation among two events exists if the events are concurrent and the values of their  $DR$  are equal and less than the unit, which is represented as  $FCNR(a, b)$ . This means, that spatial and/or temporal relation(s) can be established among the events even when a logical precedence relation cannot be determined. It is observed that when the  $DR$  for a pair of concurrent events  $(a, b)$  is equal and less than one, this means that the event  $a$  has some effect on the event  $b$  and *viceversa*. Hence, for fuzzy concurrent events,  $a$  and  $b$ , the order  $(a, b)$  or  $(b, a)$  are indistinct for the system.

To illustrate the use of the FCR and the FCNR, consider the example given in Figure 7, which shows a scenario to determine the fuzzy precedence and the fuzzy concurrency between events. For example, for the case of the relation among the events  $a$  and  $e$ , the  $FCR(a, e)$  determine if a *cause-effect* relation exists that must be taken into account for the event ordering. For the fuzzy concurrent events  $e$  and  $b$ , the  $FCNR(c, e)$  identifies that there is certain spatial and/or temporal relation between them.

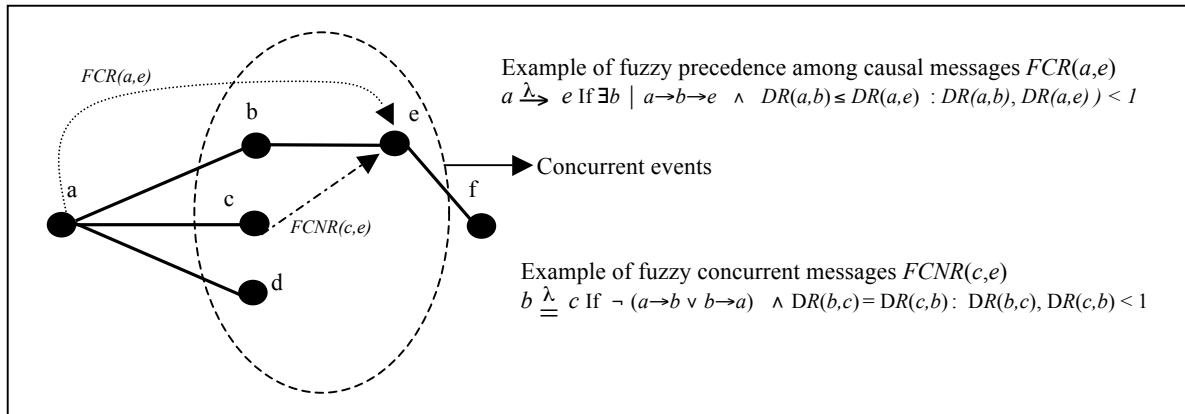


Figure 7. Example of fuzzy precedence in a distributed system

### 3.4.2 Fuzzy causal consistency

The Fuzzy Causal Consistency (FCC) is based on the FCR. The goal of the FCC is to indicate “*how good*” the performance of the system is in a certain time. The meaning of the performance can be indicated according to the problem to resolve. It is by calculating the value of the FCC that it can be determined if the performance of the system is good enough to continue.

The FCC is calculated by the average weight of the fuzzy causal relations for every event contained in the causal history  $H(a)$  of the event  $a$  from which the performance of the system wants to be known. The FCC consider only the events with an immediate dependency with the event  $a$  because those events have a direct affectation with this event. The values of the fuzzy causal consistency in this case are normalized in the interval  $[0,1]$ .



Figure 8 shows the strategy to obtain the fuzzy causal consistency for an event  $a$  at a process  $p$ . The set  $H(a)$  contains the events that are causally related to the event  $a$  which is the event from which the FCC will be calculated.

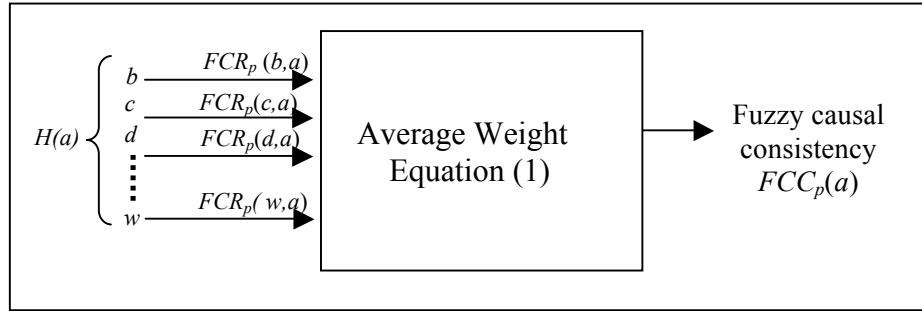


Figure 8. Fuzzy causal consistency

$$FCC_p(a) = \frac{\sum_{b \in H(a)} FCR_p(a, b) * GP(b)}{\sum_{b \in H(a)} GP(b)} \quad (1)$$

Where:

$GP(b)$  is a weighting degree used to determine priorities or weight for every fuzzy causal relation when it is needed.

$FCR_p(a, b)$  is the fuzzy causal relation of a pair of events  $(a, b)$  at a process  $p$ .

An example of how to calculate the value of the  $GP(b)$  and the  $FCR(a, b)$  are showed in sections 4.3.4 and 4.41 respectively.

### 3.5 Fuzzy causal delivery for event ordering

The Fuzzy Causal Delivery Order (FCO) is based on the concepts of FCR and FCC. The goal of the FCO is to allow a more asynchronous delivery of events compared with the causal delivery order. The FCO establishes that if for a pair of messages  $(m, m')$  the *send* of  $m$  fuzzy causally precedes the *send* of  $m'$ , then for all destinations of  $m$  and  $m'$  the delivery of  $m$  precedes  $m'$  or viceversa, if and only if the performance of the system determined by

the fuzzy causal consistency of  $m$  is inside the maximum FCC allowed by the system ( $FCC_{max}$ ). Formally, the FCO is defined as follows:

**Definition 6.** The fuzzy causal delivery order must satisfy the following condition:

If  $send(m) \xrightarrow{\lambda} send(m')$  then

$$\forall p \in dests(m) \cap dests(m'), FCC_p(m') \leq FCC_{max} \begin{cases} - delivery_p(m) \rightarrow delivery_p(m') \text{ or} \\ - delivery_p(m') \rightarrow delivery_p(m) \end{cases}$$

Where:

$FCC_p(m)$  is the fuzzy causal consistency for the event  $m$  at its reception by the participant  $p$ , and

$FCC_{max}$  is the maximum FCC allowed according to the performance required by the system.

The FCO establishes that if the value of the fuzzy causal consistency (performance of the system) for the event  $m'$ ,  $FCC_p(m')$ , is equal or lower than the maximum fuzzy casual consistency tolerated by the system,  $FCC_{max}$ , then the delivery of a pair of events can be carried out in the form,  $(m, m')$  or  $(m', m)$  allowing the interchange of events. As a direct consequence of this property, it can be observed that the FCO can make a more asynchronous events delivery.

### 3.6 Fuzzy causal order versus causal order

In this section, the usefulness of the FRC and the FCC will be shown, as well as how to use them in distributed systems. First, the main differences and advantages among *fuzzy causal relation* versus the *happened before relation* proposed by Lamport will be presented. Next, the way in which the FCR and the FCC can be applied for the concrete problem of intermedia synchronization will be described.

Let us consider the distributed multimedia scenario depicted in Figure 9. In this case, the participant  $Part(X)$  sends video and the participant  $Part(Y)$  sends audio, these continuous data must be synchronized at their delivery by the participant  $k$ . The continuous media are

widely represented by intervals. The intermedia synchronization problem is commonly solved by synchronizing the interval endpoints, which are causal dependency messages. For more details, see Morales and Pomares [26, 27] and Pomares et al. [31].

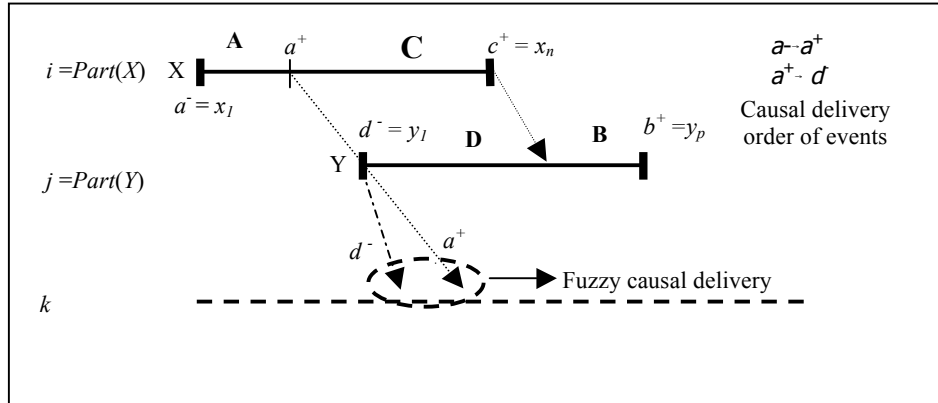


Figure 9. Example of the fuzzy causal delivery

For the strict causal algorithms based on Lamport's relation, the delivery of the event  $d$  implies that the event  $a^+$  has been delivered. Owing to delays in the network or loss of the event  $a^+$ , the delivery time of  $d$  can be infinite, which could cause a halt in the performance of the system.

For the  $\Delta$ -causal algorithms, the  $\Delta$ -causal order ensures that the delivery of the event  $d$  is carried out if it fulfills the following conditions:

- the event  $d$  has been received in its lifetime ( $\Delta$ ), and
- the events that precede  $d$  have been delivered in a causal order or have been discarded because their lifetime has expired.

In this case, the delivery of  $d$  will be carried out only if  $a^+$  has been delivered or discarded. These algorithms maintain the strict causal order proposed by Lamport and their main advantage is that the maximum delivery waiting time for the events is determined according to the lifetime established. For multimedia synchronization its lifetime ( $\Delta$ ) is established by using the values of table 3, appendix C. Nevertheless, a problem detected when this relation is applied in applications that allow certain degradation of the system is that, due to the properties of the relation, some events can be discarded even if they can be useful for the application.

In this dissertation, based on the fuzzy causal order, the event  $d$  can be delivered immediately before the event  $a^+$ , if and only if the fuzzy causal consistency is within the parameters established by the performance of the system. In the case of the intermedia synchronization problem, the performance is linked to the maximum synchronization error allowed.

Figure 10 shows a comparison between the different criteria used to carry out the events ordering in distributed systems. The figure shows that the level of asynchronous execution is correlated with the criteria chosen for events ordering. As can be observed, when there is not an order for the events delivery, the grade of asynchronous execution is the highest for the system. The FCO introduced in this dissertation allows, for a certain set of applications where a certain degradation of the system is permitted, a more asynchronous execution than the rest of the criteria traditionally used. It is important to remark that no type of event ordering is better than another. Each event ordering is meant to be used in a particular type of problem where it ensures the necessary ordering so as to satisfy its consistency constraints.

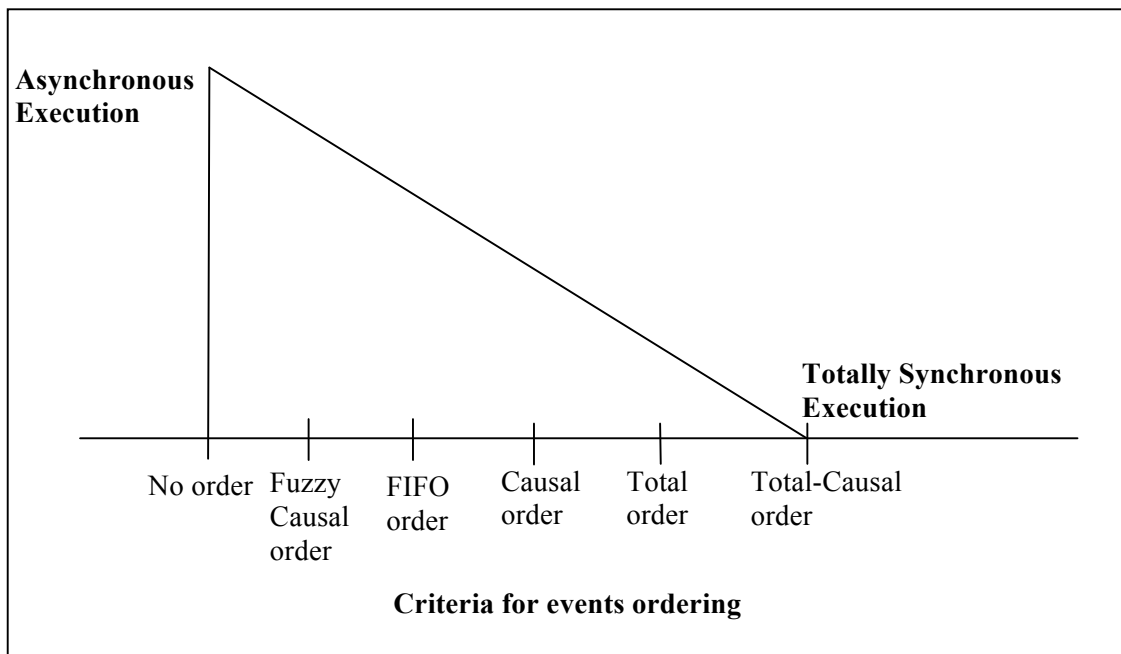


Figure. 10. Grade of asynchronous execution allowed for each event ordering in DS.

# Chapter 4

*“Get a good idea and stay with it. Dog it,  
and work at it until it's done right.”*  
**Walt Disney(1901-1966)**

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## Synchronization Model and Fuzzy Control for Multimedia Systems

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### 4.1 Introduction

This chapter presents the theoretical aspects needed to implement the distributed multimedia synchronization mechanism, which will be presented in Chapter 5. The mechanism is composed of four main components, illustrated in figure 11. The first component is the multimedia synchronization model, which is an extension of the model proposed by Pomares et al. in [31]. The extension establishes synchronization periods from synchronization points, which are identified by using the endpoints of the intervals. The second component is the component of input variables, which includes the main variables used by the fuzzy causal consistency and the fuzzy control system. The third is the fuzzy causal component, which includes the FCR and the FCC applying them to the multimedia synchronization problem. The last component is the fuzzy control system, which carries out the multimedia synchronization for distributed systems, adjusting the delivery time of the

messages and determining if a selective message discard is carried out. Next, a detailed description of each component is presented.

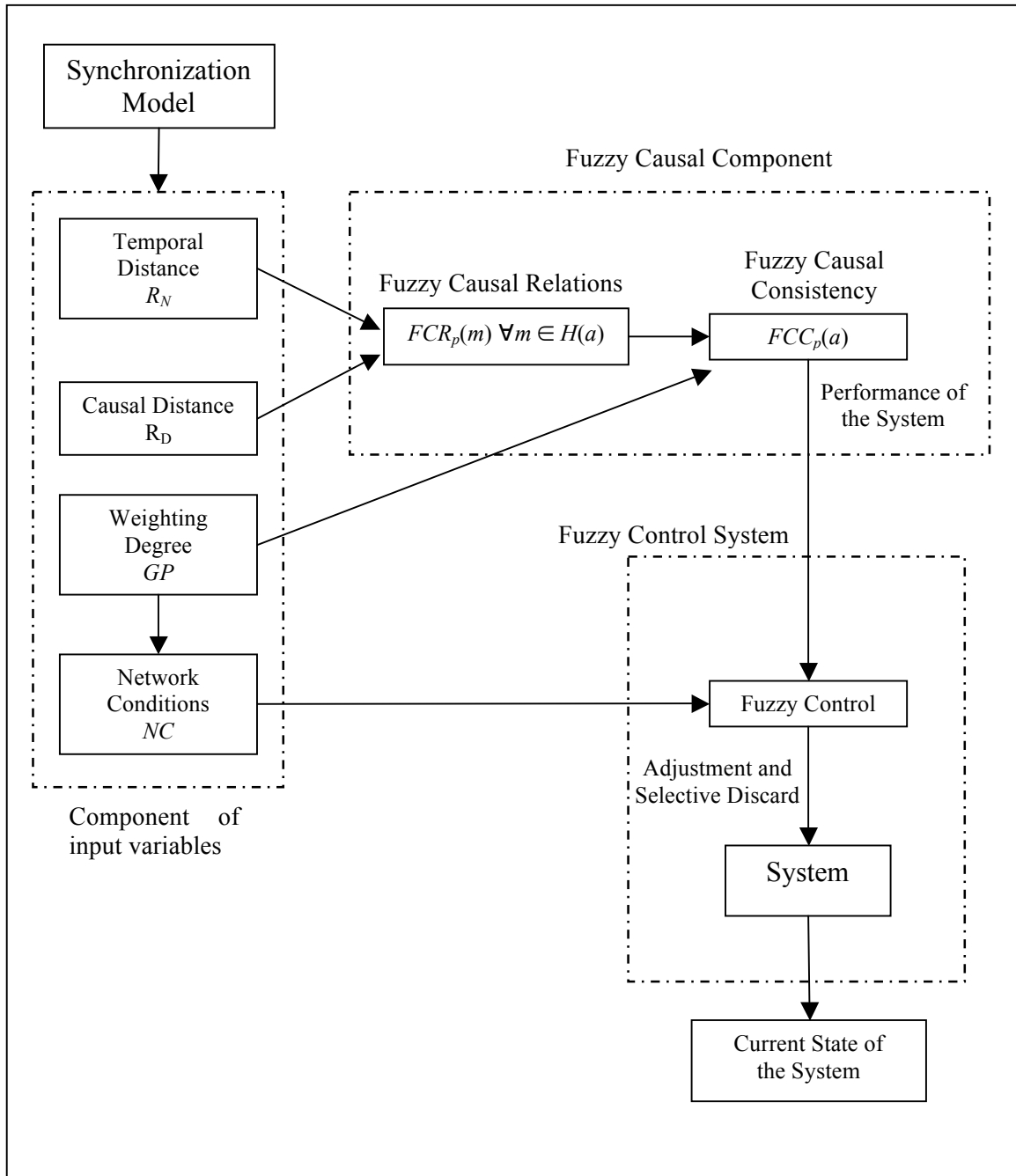


Figure 11. Scheme of the Distributed Multimedia Mechanism

## 4.2 Multimedia synchronization model

As a starting point, the work set as reference is the synchronization model proposed by Pomares et al. in [31]. This model uses the strict causal relation to identify synchronization points, which are the endpoints of the intervals, see section 3.2.1. Figure 12 shows an example of a scenario based on Pomares' model. In his work each interval is labeled as X or Y such that for every pair,  $x^- \rightarrow y^-$  or  $x^- \rightarrow y^-$ . Once the X and Y intervals are identified, they are segmented into four subintervals: A(X, Y), C(X, Y), D(X, Y), and B(X, Y). These data segments, are considered as intervals. Finally, Pomares' model construct the general causal structure  $S(X, Y) = A(X, Y) \rightarrow_1 W(X, Y) \rightarrow_1 B(X, Y)$ , where  $W(X, Y)$  determines if overlaps exist between the present pair. See the Appendix A for the definition of the happened-before relation for intervals " $\rightarrow_1$ ". We note that the data segments can be constructed at runtime as the events occur in the system, based on the causal-effect relation of the endpoints.

Among the main problems identified in this model are the halt of the system by using the strict causal delivery at the endpoints if a causal message is lost, the discard of useful messages by using the  $\Delta$ -causal delivery condition if the lifetime of the message expires, and random delays at the delivery of messages.

In order to avoid the problems of Pomares's work [32] an extension to his model has been made. The extension consists in establishing synchronization periods from the synchronization points (endpoints of the intervals), see figure 13.

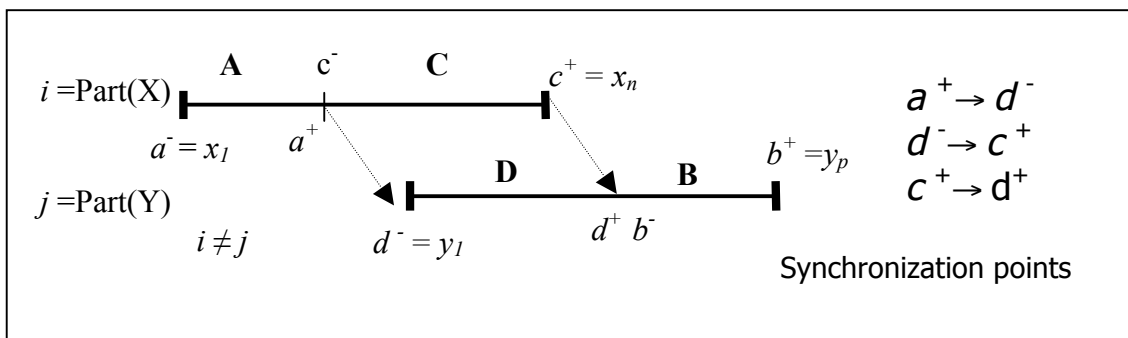


Figure 12. Synchronization scenario based on strict causal delivery

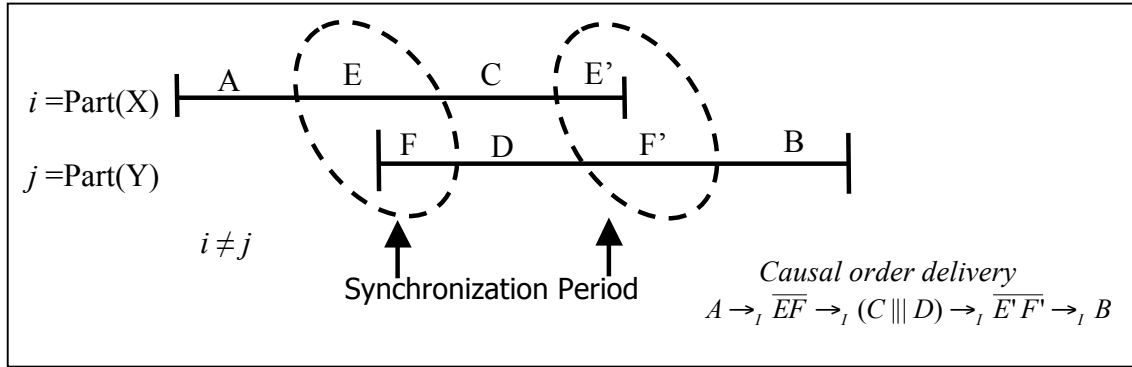


Figure 13. Synchronization scenario based on the FCR

The duration of the periods is established based on the value of the FCR between pairs of events  $FCR(e,f)$ . Formally, a synchronization period is defined as follows:

**Definition 7.** A synchronization period denoted by “ $\overline{EF}$ ” is formally defined as:

$$\overline{EF} \Rightarrow \forall (e,f) \in (E \times F), e \xrightarrow{\lambda} f \vee e \underline{\lambda} f$$

A synchronization period among two intervals exists if there is a fuzzy causal relation among the events of both sets, and the  $FCR(e,f)$  is in the range  $0 \leq FCR(e,f) < 1$ , or there is a fuzzy concurrent relation among the events of both sets.

For example, in figure 13, the synchronization periods are denoted by  $\overline{EF}$  and  $\overline{E'F'}$ . Applying these periods to the logical mapping,  $A \rightarrow_i \overline{EF} \rightarrow_i (C \parallel D) \rightarrow_i \overline{E'F'} \rightarrow_i B$ , is obtained. By interpreting the synchronization specification, all the events of the interval  $A$  should be reproduced before the synchronization period  $\overline{EF}$ . The events inside the period  $\overline{EF}$  are reproduced according to the fuzzy causal relation, which allows a more asynchronous and relaxed delivery. This is carried out because with the use of the FCR we give priority to the conditions of the system, instead the causal delivery order that have been used by the works explained in Chapter 2. All the events of  $\overline{EF}$  should be reproduced before the intervals  $C$  and  $D$ . The events of the intervals  $C$  and  $D$  should be reproduced in any way among them, but before the period  $\overline{E'F'}$ . All the events of interval  $B$  should be reproduced after the delivery of all the events of the period  $\overline{E'F'}$ .



Next, the synchronization model is presented in the table 2. The model considers all the possible relations between a pair of intervals to establish synchronization periods. A synchronization period is identified in the model by dotted lines. As part of the model it is assumed that an interval can only be constructed by one element. The model includes the *logical mapping*, which is used to assure the delivery order of the intervals and the synchronization periods. For more details regarding the logical mapping, see Pomares et.al in [31]. The logical mapping in this case includes the fuzzy causal relation to assure the delivery of events within a synchronization period and the interval causal relation (see Appendix A, definition 9) to carry out the delivery of the rest of the intervals.

#### **Allen's model vs. fuzzy logical mapping**

The work developed by Allen use a global reference to establish the interval relations. In our case we do not have a global reference to establish the synchronization; we carry out the logical mapping in a distributed way. On the other hand, the Allen's interval relations consider only temporal relations among intervals. Our synchronization model establishes a logical mapping by using the fuzzy causal relation (logical and temporal domains) to assure the order delivery of the intervals and periods.

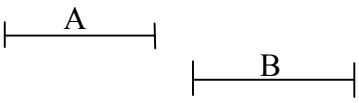
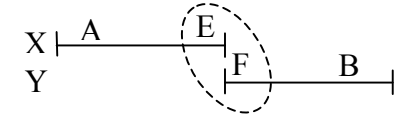
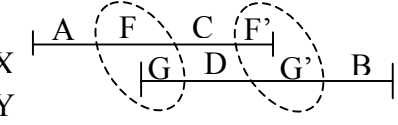
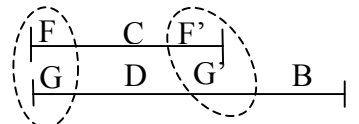
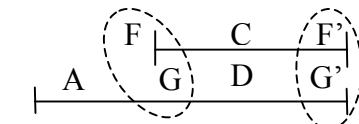
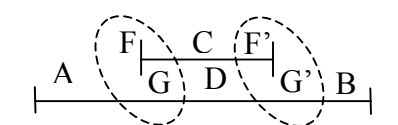
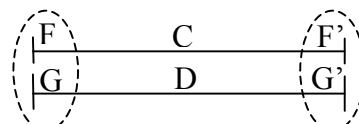
Relations	Example	Logical mapping
After		$A \rightarrow_l B$
Meet		$A \rightarrow_l \overline{EF} \rightarrow_l B$
Overlaps		$A \rightarrow_l \overline{FG} \rightarrow_l (C \parallel D) \rightarrow_l \overline{F'G'} \rightarrow_l B$
Starts		$\overline{FG} \rightarrow_l (C \parallel D) \rightarrow_l \overline{F'G'} \rightarrow_l B$
Finishes		$A \rightarrow_l \overline{FG} \rightarrow_l (C \parallel D) \rightarrow_l \overline{F'G'}$
During		$A \rightarrow_l \overline{FG} \rightarrow_l (C \parallel D) \rightarrow_l \overline{F'G'} \rightarrow_l B$
Equals		$\overline{FG} \rightarrow_l (C \parallel D) \rightarrow_l \overline{F'G'}$

Table 2. Synchronization model

### 4.3 Component of input variables

Next, the main input variables used by the fuzzy causal component and the fuzzy control system of the mechanism are presented in order to know the way in which they are calculated.

#### 4.3.1 Causal distance

The *causal distance* is used as an input variable of the membership function  $R_D$  and it is calculated at the reception of each message included in the synchronization period. The  $R_d(m)$  measures the local causal distance between each causal message contained in the causal history of  $m$  and last message received from each participant contained in its causal history (*last\_message<sub>p</sub>*). The causal distance, defined by Lopez et al. in [22], between two causally dependent messages is the greatest number of pairwise dependent messages sent between them plus one. Formally, it is defined as follows:

**Definition 8.** The distance  $d(m, m')$  is defined for any pair of messages  $m$  and  $m' \in M$  such that  $m \rightarrow m'$ :  $d(m, m')$  is the greatest integer  $n$  such that for some sequence of messages  $(m_i, i = 0 \dots n)$  with  $m = m_0$  and  $m' = m_n$ , we have  $m_i \downarrow m_{i+1}$  for all  $i = 0 \dots n-1$ . We denote the immediate dependency relation (IDR) by “ $\downarrow$ ”, see Appendix A definition 11.

In order to know the value of the causal distance among two events, it has been made an algorithm for the broadcast case for distributed systems with Dr. Saúl E. Pomares Hernández. The algorithm is shown in appendix B. In a general way the algorithm stores each linearization among the causal messages in order to represent the immediate dependency relation (IDR) graph.

#### 4.3.2 Temporal distance

The *temporal distance* is used as an input variable of the membership function  $R_N$  and it is also calculated at the reception of each message inside the synchronization period. The temporal distance between two events is calculated at their reception by any participant without having a global reference of time. In other words, it can be measured using only

independent local physical clocks for every participant. The  $\Delta(m)$  measures the difference in physical time between the arrival time of a message  $m$  and the arrival of the message  $m'$  at every participant (temporal distance), see figure 14. These values are the input for the calculation of the membership function  $R_N$ , which will be described subsequently. The calculation of  $R_N$  is carried out for the last message received from each participant contained in the causal history of the synchronization point using the equation 2.

$$\Delta(m) = \text{time\_arrival}(m) - \text{time\_arrival}(m') \quad \forall p \in H(m) \wedge m = \text{last\_message}_p \quad (2)$$

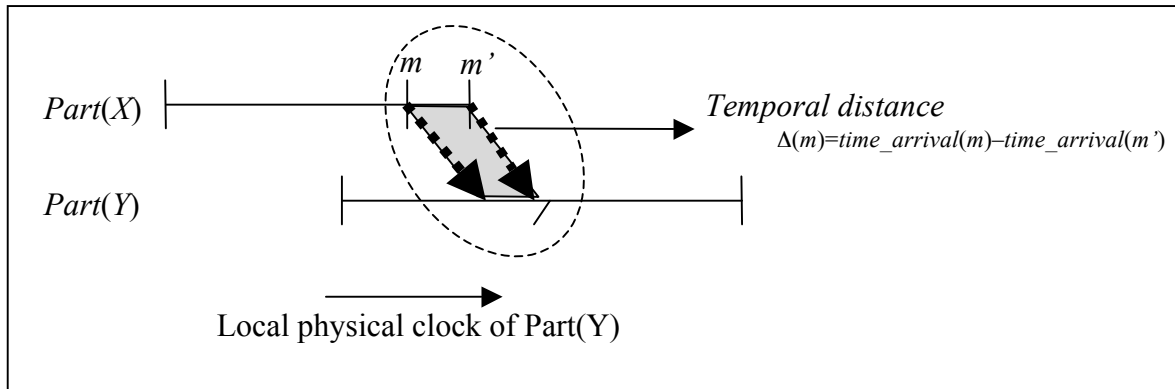


Figure 14. Example to calculate the temporal distance by the  $Part(Y)$  to calculate its FCR for the events  $m$  and  $m'$

### 4.3.3 Duration of the synchronization period

The period is established at the reception of any endpoint  $m$  of the interval (*begin* or *end*) to each participant. The quantity of events included in every period is determined by the number of events that must be delivered during the maximum synchronization error ( $QoS$ ), see Appendix C, for the delivery of an event  $m$  in accordance to the *frame rate* ( $FR$ ) of the application. The period is established for every participant contained in the causal history of endpoint  $m$ . These participants are included inside the synchronization period because they have a direct cause-effect relation with the synchronization point. Therefore, the number of elements included by period for every type of relation between data pairs (participants)

according to table 3 of appendix C is calculated by the formula:  $\frac{QoS}{FR}$ .

### 4.3.4 Establishing the weighting grade (GP)

The GP variable is the weighting grade that determines the degradation of a channel (participant) according to the best channel of the system, see equation 4. The GP is used by the formulas that determine the network condition and the fuzzy causal consistency as an input variable. This variable is obtained without a global reference of the system. In this case only the partial view of the system to each participant is used. The variable  $GP_i$  establishes the weight that the channel  $i$  has in a certain time in order to calculate the synchronization error with regard to the network conditions. With the GP, several problems that arise when the messages are sent across the network have been considered. Such problems include: traffic congestion, changes in the routing of the messages, which increase the amount of time of the RTT, loss of messages, and message delivery delays.

In order to calculate the GP, see equation 3, for the messages causally related to  $a$ , first the channel with the best network conditions,  $Bchannel$ , must be chosen, see equation 4.

$$GP_i = \left( \frac{(RTT_i + jitter_i) + PP_i}{Bchannel} \right) \quad (3)$$

$$Bchannel = \min_{i=1}^n [(RTT_i + jitter_i) + PP_i] \quad (4)$$

The meaning of the variables used in equations 3 and 4 is the following:

- $RTT$  is the Round trip time of a message.
- $Jitter$  is the fluctuation of end to end of a message with the next message inside the same stream.
- $PP$  is the number of lost messages in a synchronization period.
- $n$  is the number of channels (participants) which are causally related to the event  $a$ .

The meanings of the values of the  $GP_i$  are the following:

- When the value of  $GP_i$  is near to zero, means that the channel  $i$  has a *small* degradation with regard to the best channel.

- When  $GP_i$  tends to one, means that the channel  $i$  has a *big* degradation with regard to the best channel.

### 4.3.5 Determining the network conditions

The variable  $NC$  determines in an indirect way the network conditions. The  $NC$  gives a qualitative measurement (small, medium or big) of the changes in the network conditions, for example, transmission delays, *jitter* among messages, loss of messages, network congestion and bandwidth available. The values of the  $NC$  are normalized in the interval  $[0,1]$ , see figure 15. For the fuzzyfication value of  $NC$ , the triangular membership function of the equation 5 is also used.

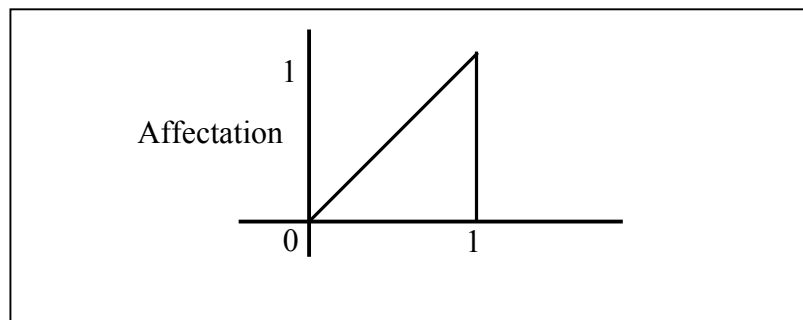


Figure 15. Membership function of the  $NC$

The network conditions are calculated when a message  $a$  is received within the synchronization period without the need to add control information at the sending time of the parameters. This factor is calculated without a global reference. The  $NC(a)$  is calculated by the weighted average of the network condition of each channel (participant) contained in the causal history of the message  $a$ . The value of the  $GP_i$  for each channel indicates its degradation with regard to the best channel. Using the weighted average the value of the network conditions for the whole system is obtained, where the channels with worse conditions have a major effect on the system. The value of the  $NC(a)$  is normalized in the interval  $[0,1]$ .

The meanings of the values of the  $NC(a)$  are the following:

- When the value of  $NC(a)$  is near to zero, means that the network conditions are *good*, this means that the behaviour of the network is inside the acceptable quality

of service parameters, for example, there is barely transmission delay, and the loss of messages is not present in the system. Hence, the  $NC(a)$  is labeled as *good*

- When  $NC(a)$  tends to one, represents that the network conditions are *bad*, for example, the random delays are almost outside of the quality of service parameter allowed, loss of messages, and/or network congestion. Therefore, the  $NC(a)$  is labeled as *bad*. For the intermediate values of  $NC(a)$ , it has to be labelled as *regular*.

The variable NC is calculated using the equation 5.

$$NC(a) = \frac{\sum_{i=1}^n \left[ \left( \frac{2B_i}{RTT_i} \right) + \frac{(PE_i - PR_i)}{PE_i} \right] * GP_i}{S_{GP}} \quad (5)$$

The meanings of the variables used in the equation 5 are the following:

- $B$  is the bandwidth available in the network.
- $RTT$  is the round trip time of a message  $a$  across the network.
- $PE$  is the number of expected messages inside the synchronization period.
- $PR$  is the number of received messages inside the synchronization period.
- $S_{GP}$  is the sum of the weighted grades of the channels.
- $n$  is number of channels(participants) which are causally related with the message  $a$ , known as the causal history of  $a$ .

In order to understand each factor of the equation 5 the following description is presented:

- The first factor  $\frac{2B_i}{RTT_i}$  is included to measure the transmission delay across the network.
- The second factor  $\frac{PE_i - PR_i}{PE_i}$  obtains the rate of lost messages caused by possible problems in network conditions, for example, network congestion, and routing of messages.

- The third factor  $GP_i$  determines the weighted grade that the channel has according to the behaviour of the system.
- The factor  $S_{GP}$  determines the weighted grade.

#### 4.4 Fuzzy causal component

In order to show the situation of unphased media data (synchronization error) figure 16 presents a scenario that represents a multimedia scenario among three participants. The maximum waiting time for the pair video-audio is established at  $\Delta=80ms$ , which is the maximum synchronization error established for its reproduction in real time according to Haj and Xue [11]. The maximum waiting time for the pair video-animation is established at  $\Delta=120ms$ , which is the maximum synchronization error established for its reproduction according to Haj and Xue [11].

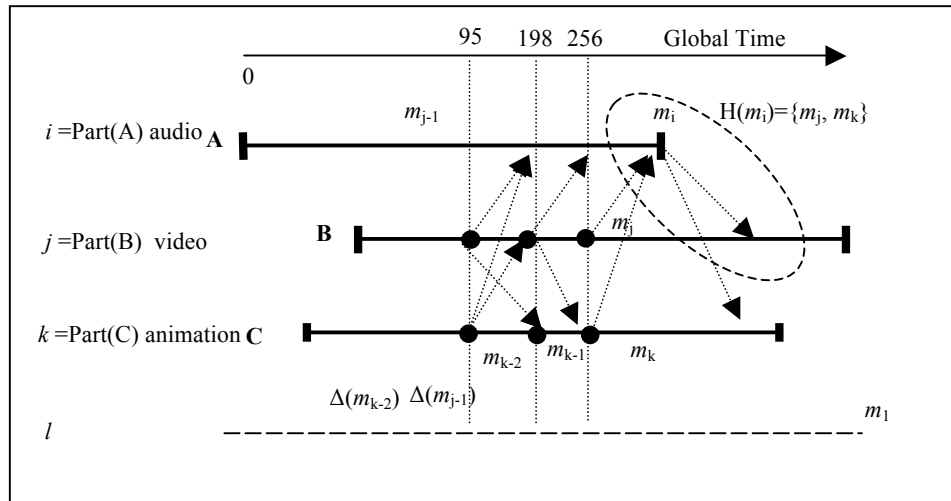


Figure 16. Example of a distributed multimedia scenario

##### 4.4.1 The FCR applied to the intermedia synchronization

In this dissertation, only the logical and temporal domains for the fuzzy causal relation are considered in order to resolve the intermedia synchronization problem. As a recall, these domains are used as the input distances for the  $DR(a,b)$ . For each domain, one membership function is defined,  $R_D$  and  $R_N$ , respectively. The spatial domain is not included since the data do not consider it. In addition, the spatial domain is not included because we do not



need to establish precedences according to the position of multimedia objects, which is carried out for intramedia synchronization. On the other hand, the logical domain is considered because, as it was previously shown, the synchronization is based on the causal interval endpoints of the media involved. The temporal domain is also included because the synchronization error among the media involved is measured in physical time units (milliseconds). These domains give us useful information to determine the data delivery order in the synchronization problem according to the performance desired. As *distances* for the logical domain the separation among the events according to the event ordering chosen the following can be used: local causal distance (*fifo*), causal distance introduced by Lopez et al. in [22] (causal order), total distance (total order) and the total-causal distance (total causal order). In this chapter, the local causal distance was chosen because the interest for the synchronization problem is focused on measuring the separation among each media data. For the temporal domain as *distance* the physical time is used.

For the intermedia synchronization problem, the value of the FCR for a pair of messages  $FCR(g,h)$  is determined from the union of two membership functions,  $R_D \cup R_N$ , logical and temporal domain, respectively. The fuzzy operator chosen as union operator is the maximum. The FCR is formally defined by equation 6 as:

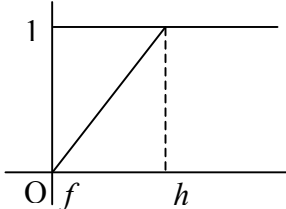
$$FCR(g,h) = DR(g,h) \text{ if } g \xrightarrow{\lambda} h \quad (6)$$
$$DR(g,h) = \max(R_D, R_N)$$

The membership functions are normalized in the interval [0,1]. The meaning of the values obtained by the  $FCR(g, h)$  is as follows:

- When  $FCR(g, h)$  tends to zero indicates that the messages have been delivered with acceptable network conditions. In other words, the delay and the causal distance between the messages are inside the quality of service parameters, which indicate that there are no considerable changes with the ideal network conditions at the messages delivery time (e.g. no data is lost).
- When  $FCR(g, h)$  tends to the unit, this indicates that the network conditions are deplorable. This means that there is loss of message and/or delays in the network

are above the quality of service parameters, which indicate that the network conditions and the causal distance are far from the ideal conditions.

The normalization in the interval [0,1] for the values of the membership functions, “ $R_N$ ” and “ $R_D$ ” can be calculated by a triangular function in equation 7.

$$R(x) \begin{cases} 0 & \text{if } x < f \\ \frac{x-f}{h-f} & \text{if } f \leq x < h \\ 1 & \text{if } x \geq h \end{cases} \quad (7)$$


In figures 17a and 17b examples for the triangular membership functions used for the temporal distance and the causal distance are shown, respectively, in order to show the *cause-effect* relation of the FCR. In the case of the temporal distance, the value of  $d_{max}$  is assigned according to the maximum error synchronization allowed to each pair of media synchronization. The possible values are shown in Appendix C.

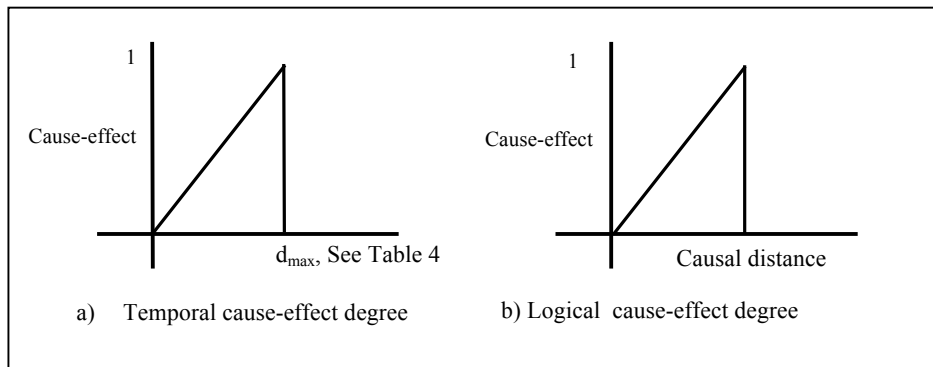


Figure 17. a) Example of the membership function for the temporal cause-effect degree

b) Example of the membership function for the temporal cause-effect degree

The temporal distance among the events is determined according to the maximum delay allowed by the application, also known as synchronization error. These values are related to the type of media involved in the synchronization process (e.g. audio-audio, video-audio, image-audio). For the scenario presented in Figure 16, a maximum delay of  $\pm 120ms$  is used

for the temporal distance; according to Haj and Xue in [11], this is the maximum delay for a dialogue among some participants.

The logical distance is bounded to four events; this is because it has been shown that in the RTP protocol, the probability of the loss of four events of the same process or participant is minimal according to the information provided by Perkins in a study performed in 2003 [7]. In figures 18a and 18b examples of the triangular membership functions  $R_N$  and  $R_D$  are shown for the intermedia synchronization problem, where the *cause-effect* relation between the temporal distance and the causal distance is illustrated, respectively.

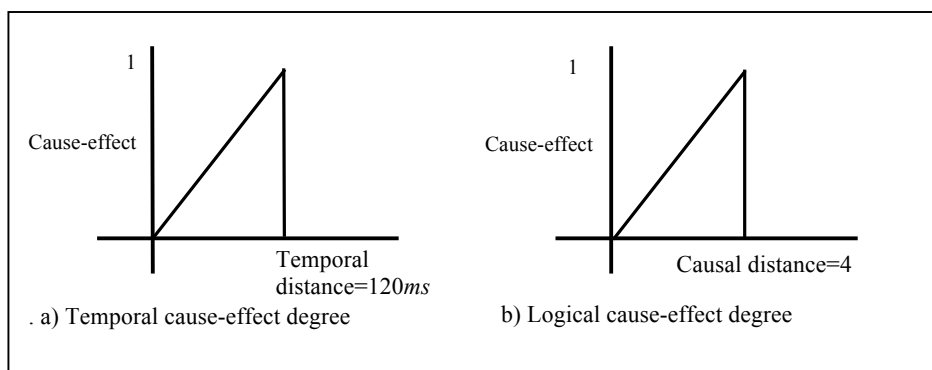


Figure 18. a) Example of membership functions for the temporal cause-effect degree to the intermedia synchronization

b) Example of membership functions for the logical cause-effect degree to the intermedia synchronization

#### 4.4.2 The FCC applied to the intermedia synchronization

Applying the FCC to solve the intermedia synchronization problem gives a qualitative measure of the synchronization error, according to the temporal and logical dependencies in the whole system, in a certain time with regard to the partial view that every participant has. The value of the FCC is used to assign linguistic labels to the performance of the system. In order to assign the labels in the fuzzyfication stage the triangular membership function of the equation 4 is used; this is represented in figure 19. The values of the FCC are normalized in the interval  $[0,1]$ . The labels for the FCC are *good*, *regular* or *bad*, to qualify

the performance of the system according to the conditions of the events sent across the network.

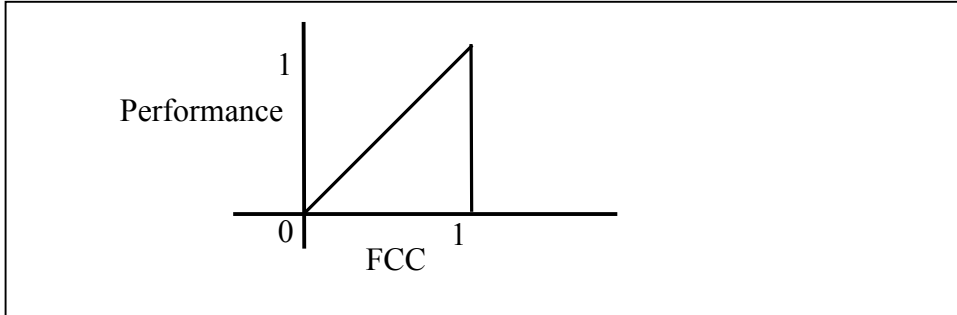


Figure 19. Membership function to FCC

In order to know “*how good*” the performance of the system is, the equation 1 is used. This equation has been previously defined in Section 3.3.2. The FCC for the synchronization problem is calculated by the weighting average of the fuzzy causal relations for every event contained in the causal history  $H(a)$  of the event  $a$  from which it is desired to carry out the synchronization. The GP factor used for the  $FCC_p$  was already described in Section 4.3.5.

$$FCC_p(a) = \frac{\sum_{b \in H(a)} FCR_p(a,b) * GP(b)}{\sum_{b \in H(a)} GP(b)}$$

The meanings of the values obtained by the  $FCC_p(a)$  for the synchronization problem are the following:

- When  $FCC_p(a)$  tends to zero, indicates that the performance of the system is *good*, which means that the temporal and logical dependencies between the messages are satisfied.
- When  $FCC_p(a)$  tends to the unit, indicates that the system performance is *regular* or *bad*. In this case, the temporal and/or logical dependencies between the messages are not totally assured, but the system can still deliver the messages.

## 4.5 Fuzzy control system

The goal of the fuzzy control is to reduce the synchronization error of the system. The fuzzy control design is depicted in figure 20. The input values of the fuzzy control are the network conditions ( $NC$ ) and the Fuzzy Causal Consistency ( $FCC$ ), see Sections 4.3.4 and 4.4.2 respectively. The output of the control ( $\mu$ ) is used to adjust the delivery time of the messages and to determine if a selective messages discard is made. The control is carried out at the reception of any message  $a$  inside a period of synchronization.

As it was established before, the output of the fuzzy control determines the delivery time of the data and the action that the system will carry out. Some of the actions that the control will be able to execute include: the immediate delivery of the received message  $a$  or its delay, and the determination whether a selective discard of the messages contained in the causal history of the message  $a$  is carried out. The messages discarded are those messages that cannot be delivered due to anomalous network conditions, for example, network congestion, loss of messages, and/or transmission delays.

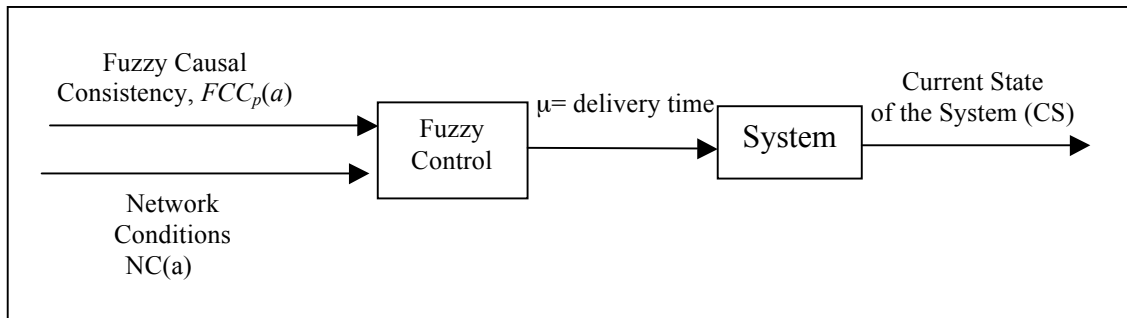


Figure 20. Diagram of the fuzzy control system

The current state of the system (CS) is a factor that represents the value of the system after applying the output of the fuzzy control that adjust the delivery time of the message  $a$ . The CS is calculated using the equation 8.

$$\text{Current State of the System (CS)} = 1 - (NC(a) + \mu) \quad (8)$$

The set of rules used by the fuzzy control to adjust the delivery time of the message  $a$  has the form:

$$\text{If } NC(a) \in A_i \text{ y } FCC_p(a) \in B_i \text{ then } \mu \in C_i$$

Where:

- $NC(a)$ ,  $FCC_p(a)$  and  $\mu$  are the input parameters of the fuzzy control system.
- $A_i = \{good, regular, bad\}$  are the linguistic labels for  $NC(a)$ , which represents the synchronization error with regard to the network conditions.
- $B_i = \{good, regular, bad\}$  are the linguistic labels for the  $FCC_p(a)$ , Fuzzy Causal Consistency of the message  $a$ , which represents the performance of the system according to the logical and temporal dependencies.
- $C_i = \{big, medium, small\}$  are the linguistic labels for the output  $\mu$  to adjust the delivery time of the messages and determine if a selective discard of the message contained in the causal history of  $a$  is made.

The description of the set of rules that the fuzzy control system considers to reduce the synchronization error is the following:

- If  $NC(a)= bad$  and  $FCC_p(a)= good$ , then  $\mu= medium$  (delivery without discard)
- If  $NC(a)= bad$  and  $FCC_p(a) = regular$ , then  $\mu= small$  (delivery with discard)
- If  $NC(a)= bad$  and  $FCC_p(a) = bad$ , then  $\mu= small$  (delivery with discard)
- If  $NC(a)= regular$  and  $FCC_p(a) = good$ , then  $\mu= medium$  (delivery without discard)
- If  $NC(a)= regular$  and  $FCC_p(a) = regular$ , then  $\mu= medium$  (delivery without discard)
- If  $NC(a)= regular$  and  $FCC_p(a) = bad$ , then  $\mu= small$  (delivery with discard)
- If  $NC(a)= good$  and  $FCC_p(a) = good$ , then  $\mu= big$  (delivery without discard)
- If  $NC(a)= good$  and  $FCC_p(a) = regular$ , then  $\mu= big$  (delivery without discard)
- If  $NC(a)= good$  and  $FCC_p(a) = bad$ , then  $\mu= medium$  (delivery without discard)

The Mamdani model has been selected as the inference mechanism of the fuzzy control system to choose the action that it will carry out. The Mamdani inference mechanism is defined by the following formula:

$$R(NC(a), FCC_p(a), \mu) = \max_{i=1}^9 (\min(A_i(NC(a)), B_i(FCC_p(a)), C_i(\mu))) \quad (9)$$

For the stage of defuzzification at the output of the fuzzy control system the *centroide* function has been chosen and it has been defined as:

$$\mu = \frac{\sum_{i=1}^n \mu_i R(\mu_i)}{\sum_{i=1}^n R(\mu_i)} \quad (10)$$

Where:

- $\mu_i$  is the output value for the rules determined by the values assigned to  $\mu$ , according to the values of the sets: small, medium and big.
- $R(\mu_i)$  is the output value of the fuzzy control obtained after combining the rules of the fuzzy control by the Mamdani model.
- $n$  is the number of possible values that can be obtained at the exit of the fuzzy control; in our case there are three for the possible values that can be assigned to  $\mu$ .

Next, in Chapter 5, the viability of the distributed multimedia mechanism is presented showing some simulation results.

# Chapter 5

*“Everything should be made as simple as possible,  
but not simpler.”*  
Albert Einstein(1879-1995)

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## Distributed Multimedia Synchronization Mechanism

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### 5.1 Introduction

The proposed mechanism to carry out the multimedia synchronization in a distributed system in this chapter is presented. The mechanism consists of an algorithm that implements the four main components described in Chapter 4. In addition, a simulation of the mechanism is presented in order to show its usefulness by the simulation of three main cases of the network conditions.

### 5.2 Distributed multimedia synchronization algorithm

First, the algorithm performs the logical mapping translation of a temporal scenario according to the model presented in section 4.2 by establishing the synchronization periods



from the synchronizations points (interval endpoints). Secondly, the algorithm calculates the input variables used by the fuzzy control system and the fuzzy causal consistency. Next, it determines the fuzzy causal relations and the fuzzy causal consistency to each message received in the synchronization period. Finally, the algorithm carries out the fuzzy control mechanism to establish the delivery time of the continuous media and takes corrective actions in order to reduce the possible synchronization error among the media data. Next, the formal codification of the algorithm is presented.

### 5.2.1 Algorithm codification

Internally, the algorithm has two classes of messages: *causal* and *fifo*. There are two types of causal messages, *begin* and *end*, which are used to label the left and right endpoints of an interval, respectively. The *fifo* message is used to label the data transmitted during an interval.

First, the main data structures used by the algorithm are presented. Later, a general description of the algorithm is presented. In addition, the complete codification of the algorithm is shown in Appendix D.

#### Main data structures

**Structure of messages.** Formally, a message  $m$  in the algorithm is a tuple  $m = (k, t, TP, H(m), data)$ , where:

- $k$  is the identifier of sender  $k = Src(m)$ .
- $t = VT(p)[k]$  is the local process clock value with the identifier  $k$  when a causal message  $m$  (*begin*, *end* or *discrete*) is sent. The value of  $t$  indicates the sequential number labeled to the causal message.
- $H(m)$  is the causal information of message  $m$ . It contains message identifiers  $(k,t)$ , which causally precede the causal message  $m$ . The information in  $H(m)$  ensures the causal delivery of the message  $m$ . The  $H(m)$  structure is built before a causal message is sent, and it is attached to the causal message. For *fifo* messages, the structure  $H(m)$  is always  $H(m) = \emptyset$ .

- $TP$  is the type of message (*begin*, *end*, or *fifo*).
- $data$  is the structure that carries the media data.

**Causal data structures.** There are four main causal structures:  $VT(p)$ ,  $VRCD(p)$ ,  $CI(p)$  and  $last\_fifo(p)$ . The size of each structure is equal to the number of processes in the group.

- $VT(p)$  is the vector time. Each process  $p$  has an element  $VT(p)[j]$  where  $j$  is a process identifier. The  $VT(p)[j]$  represents the greatest number of messages that the identifier  $j$  has “viewed” in a causal order. The  $VT(p)$  structure contains the local view of the causal history of the system for the process  $p$ .
- $CI(p)$  is the control information structure.  $CI(p)$  is a set composed by entries  $(k,t)$ , which are message identifiers (the message diffused by the process identifier  $k$  with the local clock value  $t$ ). The  $CI(p)$  structure also contains information about the causal history of  $p$ . Each entry in  $CI(p)$  denotes a message that is not ensured by process  $p$  of being delivered in causal order.
- $last\_fifo(p)$  is the fifo control information structure. It is created in the same manner as the  $CI(p)$ . The  $last\_fifo(p)$  has information about the last *fifo* messages received by  $p$ . This structure is important because it represents potential causal messages.
- $VRCD(p)$  is the vector which contains the fuzzy causal relation. Each process  $p$  has an element  $VRCD(p)[j]$  where  $j$  is a process identifier. The  $VRCD(p)$  structure is used in the calculation of the FCC to determine the delivery order of the events inside a synchronization period.

**Auxiliary data structures.** There are nine auxiliary data structures that store the parameters used to implement the synchronization model. The size of each structure is equal to the number of participants in the group. The function of each one is described next.

- $VQoS(p)$  contains the maximum error allowed to synchronize the multimedia data, see appendix C. It is used to calculate the duration of the synchronization period.
- $VFR(p)$  contains the *frame rate* for each type of data transmitted by each participant.
- $VPeriod(p)$  contains for each participant the number of elements included by period to each type of relation between media data according to table 3 appendix C. The

$VPeriod(p)[i]$  is calculated by the formula:  $\frac{VQoS(p)[i]}{VFR(p)[i]}$ .

- $VTemp\_Period(p)$  contains the last element of the period established.
- $VRTT(p)$  stores the last RTT for each participant at the reception of a causal message.
- $VBw(p)$  stores the available bandwidth to each participant at the reception of a causal message.
- $Vjitter(p)$  stores the *jitter* among messages obtained for every participant.
- $VTime(p)$  contains the time in which the last message was received in a synchronization period for every participant.
- $Vdc(p)$  stores the maximum causal distance of the last causal message received from every participant.
- $VPR(p)$  contains the number of messages received in a period for every participant.
- $GP(p)$  stores the weighting grade for every participant.
- $Vdc(p)[k]$  contains the causal distance for every participant at the reception of its last causal message.

**Fuzzy control structures.** These structures are the input variable for the fuzzy control system.

- $tN$  stores the temporal distance at the reception of any message inside a period
- $N$  stores the value of the membership function used to calculate the temporal distance for the FCR.
- $D$  contains the value of the membership function used to calculate the causal distance for the FCR.
- $FCC$  stores the logical state of the system used as input parameter for the fuzzy control.
- $NC$  stores the network conditions used as input parameters for the fuzzy control.

### 5.3 General description of the algorithm

At the sending of any message, the  $VT(p)[i]$  is increased by one in order to know all the events that the participant  $p$  has sent, where  $i$  is the participant identifier of the message, which is represented by  $VT(p)[i] = VT(p)[i] + 1$ .

The data contained in  $CI(p)$  are potential identifiers of every participant with an immediate dependency relation with the causal messages *end*, or *begin* of an interval sent by  $p$ .

```

If not (  $TP = begin$  ) then //construction of the  $H(m)$  to messages end
   $H(m) \leftarrow CI(p)$ 
Else
  //construction of the  $H(m)$  to messages begin
   $\forall (s,r) \in CI(p)$ 
    If  $\exists (x,f) \in last\_fifo(p) \mid s=x$  then //Adding fifo information to  $CI(p)$ 
      If not (  $(s,r) = \max \{ (x,f), (s,r) \}$  ) then
         $CI(p) \leftarrow CI(p) \cup (x,f)$ 
      Endif
    endif
   $H(m) \leftarrow CI(p)$ 
   $last\_fifo(p) \leftarrow \emptyset$ 
Endif

```

The  $CI(p)$  is updated at the reception of any causal message, and it is locally empty when a new causal message is sent by  $p$ .

```

//Updating the  $CI(p)$ 
 $CI(p) \leftarrow CI(p) \cup \{ (k, t) \}$ 
 $\forall (l, t') \in H(m)$  //Depura  $CI(p)$  y  $last\_fifo(p)$ 
  If  $\exists (s, r) \in CI(p) \mid l=s$  and  $r \leq t'$  then
     $CI(p) \leftarrow CI(p) \setminus (s, r)$ 
  Endif
  If  $\exists (x, f) \in last\_fifo(p) \mid l=x$  and  $f \leq t'$  then
     $last\_fifo(p) \leftarrow last\_fifo(p) \setminus (x, f)$ 
  Endif

```

At the reception of any causal message  $m$ , the duration of the synchronization period is calculated. Then, the input parameters to determine the network conditions of the participant who sent message  $m$  and to each participant contained in its causal history are obtained: the *RTT*, the available bandwidth (*Bw*) and the *jitter* among messages.

```
// Establishig of the period and the necessary parameter to calculate the GP
VTemp_Periodo(p)[k]=VT(p)[k] + round(VPeriodo(p)[k]/2)
VRTT(p)[k]=get_RTT()
VBw(p)[k]=get_Bw()
Vjitter(p)[k]=get_jitter()
```

For any message received during a synchronization period, the FCR is calculated. Then, in order to establish the fuzzy causal relation among the messages, it is necessary to obtain the temporal distance “ $R_N$ ” and the logical distance “ $R_D$ ” (causal distance).

```
If TP=fifo
  dc_max=d
Else
  dc_max=0
   $\forall (l,t') \in H'(m)$ 
    If dc_max<d
      dc_max=d
      d=t'-VT(p)[l]
    Endif
```

Later, the average weight ( $GP$ ) is calculated according to the network parameters previously obtained.

```
 $\forall (l,t') \in H(m)$ 
  GP(p)[l]=[VRTT(p)[l]+Vjitter(p)[l]]+((VPeriodo(p)[l]-VPR(p)[l])
GP(p)[k]=[VRTT(p)[k]+Vjitter(p)[k]]+((VPeriodo(p)[k]-VPR(p)[k])
```

Next, the fuzzy causal consistency and the network conditions are calculated. These parameters are used as input variables for the fuzzy control in order to overcome the synchronization error. Moreover, the control adjusts the delivery time of the message determining if a selective discard of the messages contained in the causal history of  $m$  is carried out.

```
FCC=0
 $\forall (l,t') \in H(m)$ 
  FCC= FCC+(VRCD(p)[l]* VGP(p)[l])
  CS=CS+[((2*VBw(p)[l])/VRTT(p)[l])+((VPeriodo(p)[l]-
  VPR(p)[l])/VPE(p)[l])]*(GP(p)[l]/BChannel)
  FCC= FCC+(VRCD(p)[k]* VGP(p)[k])
  NC=NC+[((2*VBw(p)[k])/VRTT(p)[k])+((VPeriodo(p)[k]-
```

---

```

     $VPR(p)[k]/VPE(p)[k]]*(GP(p)[k]/BChannel)$ 
    //Calculate the fuzzy causal consistency
     $FCC = FCC / ngp$ 
    //Calculate the Network conditions
     $NC = NC / nGP$ 

```

When a *fifo* message is received outside of a synchronization period, the FIFO order of delivery is verified. In addition, the information of the last message received by this participant is updated.

```

If  $t = VT(p)[k] + 1$ 
    delivery( $m$ )
     $VT(p)[k] = VT(p)[k] + 1$ 
    If  $\exists (x, f) \in last\_fifo(p) \mid k=x$  then
         $Last\_fifo(p) \leftarrow last\_fifo(p) \setminus (x, f)$ 
    endif
    //Update the last_fifo(p) with the last message
     $last\_fifo(p) \leftarrow last\_fifo(p) \cup (k, t)$ 
Else
    Wait()
Endif

```

## 5.4 Simulation

This section presents the simulations of the synchronization mechanism. The input variables used by the fuzzy control and the output of the control are described. The number of tests developed was 100,000.

In order to illustrate the situation of unphased media data (synchronization error) a scenario that consists of a group of four hosts is presented; three of them transmitting live media data (W, X, and Y hosts), while the other function only serves as a *Client* (Host Z); see Figure 21. We compare our synchronization mechanism with a  $\Delta$ -causal algorithm because it is the only asynchronous solution for multimedia synchronization.

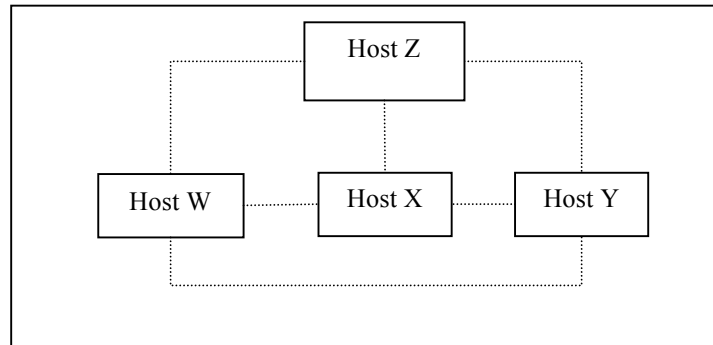


Figure 21. Example of a distributed multimedia scenario

This scenario represents a dialogue among some participants. Each host has six inputs and three outputs communication channels. The sending hosts transmit video, audio and animation. In this scenario, each host has the synchronization mechanism running. The maximum waiting time for the pair audio-video is established at  $\Delta=80ms$ , which is the maximum synchronization error established for lyp synchronization in real time according to Haj and Xue in [11]. For the pair video-animation is established at  $\Delta=120ms$ .

The simulation considers three main scenarios. The first scenario is called the soft case, where the mechanism is carried out with ideal conditions. The second scenario is named the medium case, where the conditions of the systems are regular. The third scenario is called the hard case, where the conditions of the system are the hardest to synchronize.

In this section a window of 120 tests is presented in order to be illustrative. In addition, the results of the 100,000 simulations according to the number of messages delivered, with and without discard, and their adjustment of the delivery time are presented. Besides, it is included a comparison among the fuzzy causal delivery order and the  $\Delta$ -causal delivery to measure the loss of message of both orders. We not include a solution that use only the happened-before relation proposed by Lamport in the multimedia synchronization because the system halts if a message is lost. Hence, it was carried out the comparison with the  $\Delta$ -causal delivery order, which support the loss of messages. Besides, the  $\Delta$ -causal order is included because is the only work that had tried solve the synchronization multimedia in an asynchronous manner.

### 5.4.1 Variables of the fuzzy control system

Before describing the simulation results of the mechanism, a description of the input variables and the output variable used by the fuzzy control system is presented.

#### Network condition

The input variable  $NC$  uses three labels to denote the network conditions, *good*, *regular* and *bad*, see figure 22. The label *good* is used for values in the interval  $[0,0.3]$ ; this means that the network conditions are ideal. The *regular* label is assigned when the input value is in the interval  $[0.31,0.7]$ ; this means that the network conditions are normal. The label *bad* is for the interval  $[0.71,1]$ , which is used for deplorable network conditions.

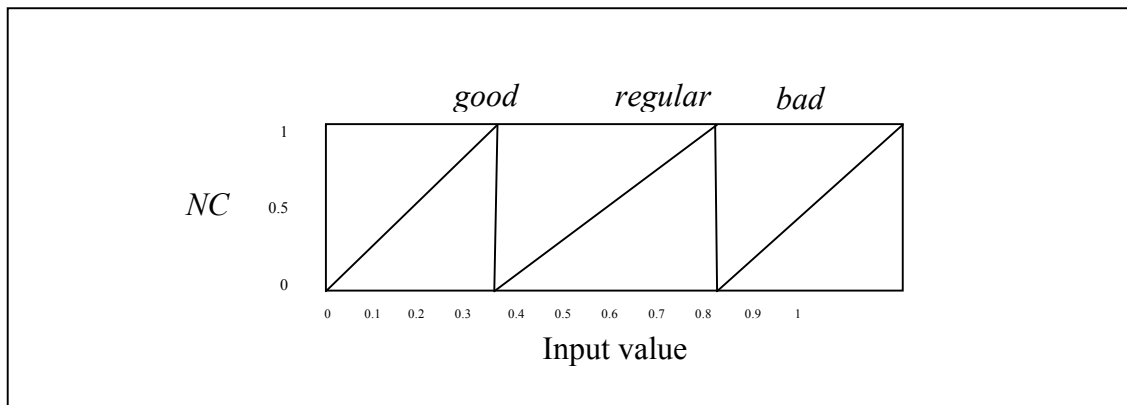


Figure 22. Values of the membership function  $NC$

#### Fuzzy causal consistency

The input variable  $FCC$  uses three labels to denote the fuzzy causal consistency of the system, *good*, *regular* and *bad*, see figure 23. The label *good* is used for values in the interval  $[0, 0.3]$ , which means that the message has been delivered in ideal conditions according to the logical and temporal distances. The *regular* label is assigned when the input value is in the interval  $[0.31, 0.7]$ ; this means that the distances are in regular conditions. The label *bad* is used for the interval  $[0.71, 1]$  and represents that the distances among the events are big.



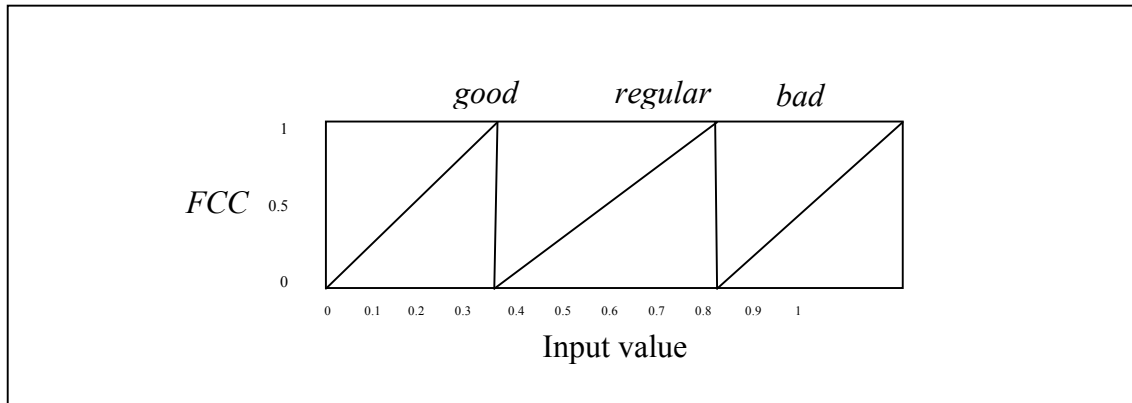


Figure 23. Values of the membership function FCC

### Output value of the fuzzy control

The output value of the fuzzy control is used to determine if a selective discard of messages must be carried out and to establish the adjustment of the delivery time of the message. The delivery time is linked to the maximum error allowed to deliver a message according to the type of media involved, see table 3 Appendix C. The interval  $[0, 0.5]$  denotes that the message has a *small* time of delivery and should *discard* the messages contained in its causal history; this means that the message is immediately delivered. The interval  $[0.4, 0.7]$  establishes as *medium* time of delivery and does not *discard* the messages of the causal history. The interval  $[0.7, 1]$  denotes that the message waits a *big* time to be delivered *without discarding* the messages contained in its causal history.

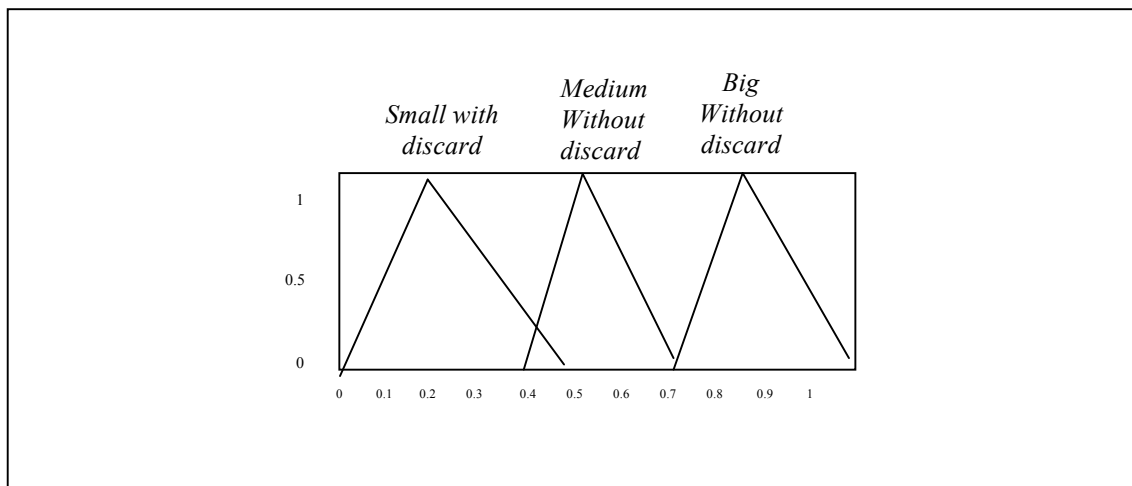


Figure 24. Values of the output for the fuzzy control

## 5.5 Results

The tests performed to each scenario proposed are presented in the following sections.

### 5.5.1 Soft case

In the soft case the ideal conditions of the system are considered. The figure 25 denotes that the network condition of the system is ideal. On the other hand, the logical and causal distances are small among the events. These conditions mean that there is only a causal distance of 1, and the delay is practically inexistent. This is reflected in the value obtained by the FCC, see figure 26. Hence, the output value of the fuzzy control according to the rule base established in section 4.5 is above 0.6, which implies that the messages are delivered without a discard of the messages contained in their causal history, see figure 27. The current state of the system depicted in figure 28 represents that the execution of the system is good, for more details see section 4.5. The number of messages delivered with medium or big time of delivery is shown in figure 29. These messages do not carry out a selective discard of messages contained in their causal history.

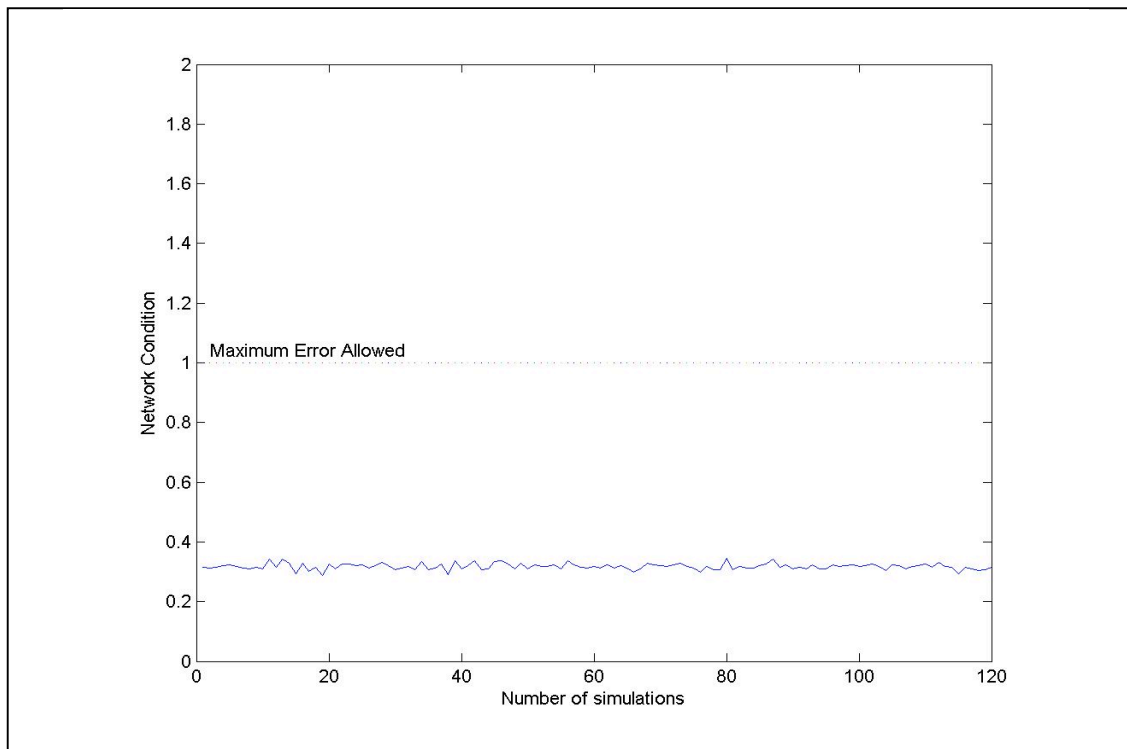


Figure 25. Media of the input network condition

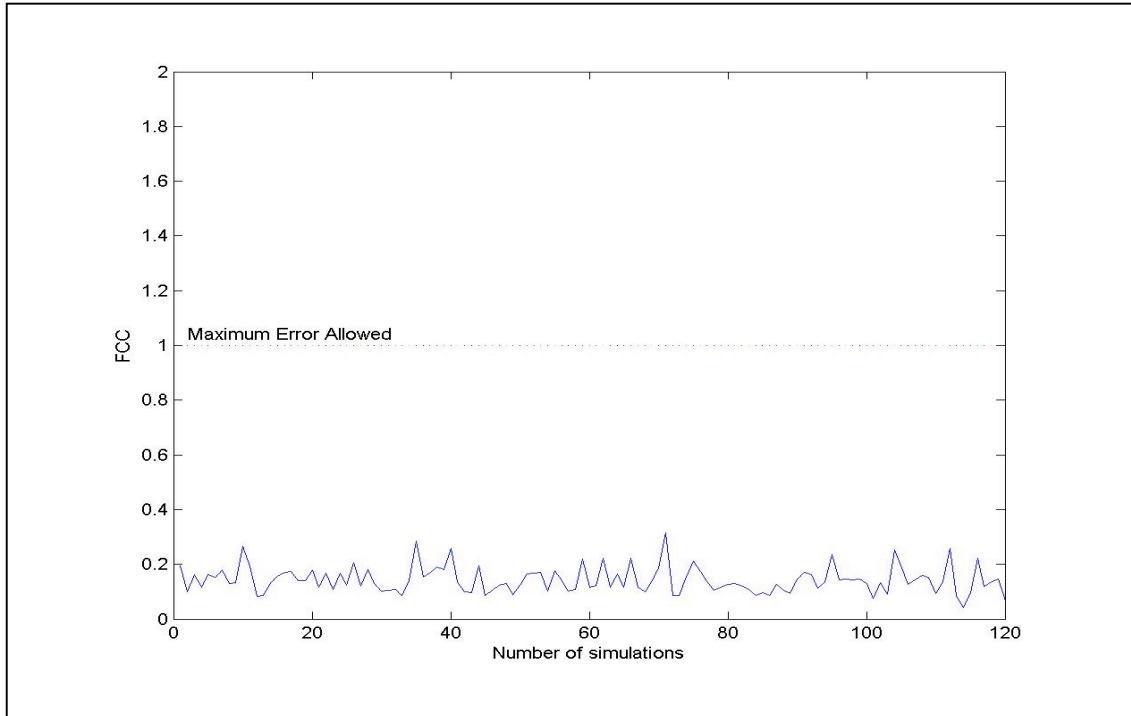


Figure 26. Media of the FCC input value

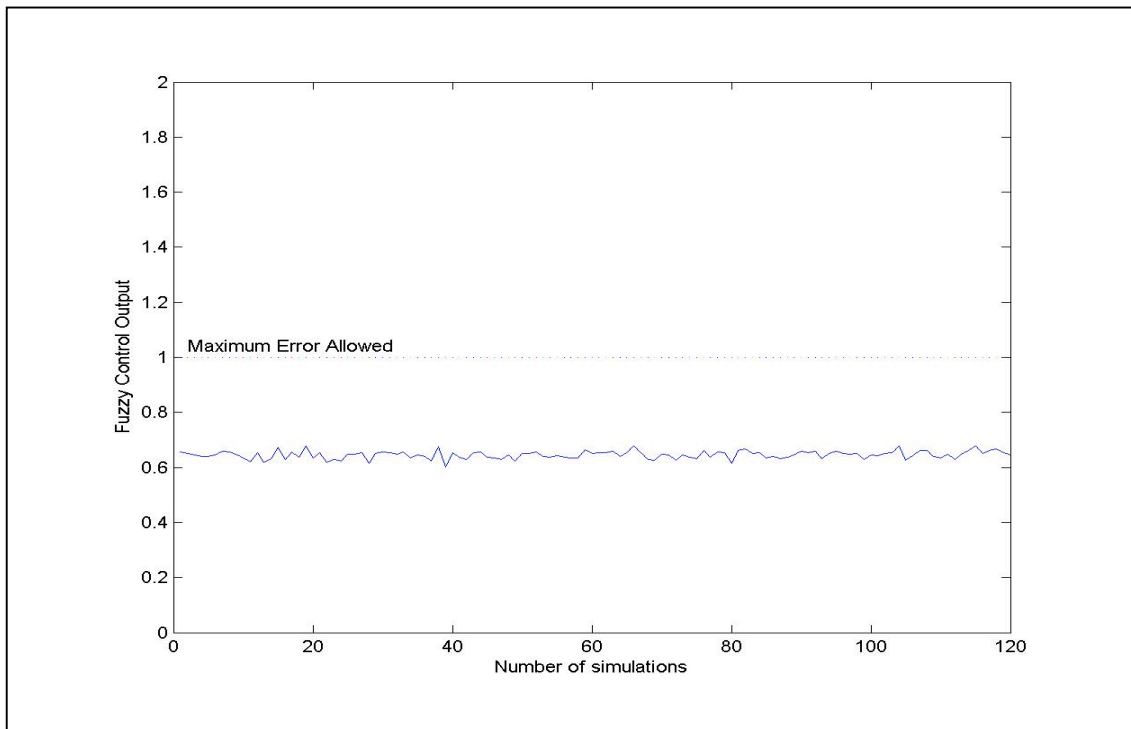


Figure 27. Media of the output of the fuzzy control system

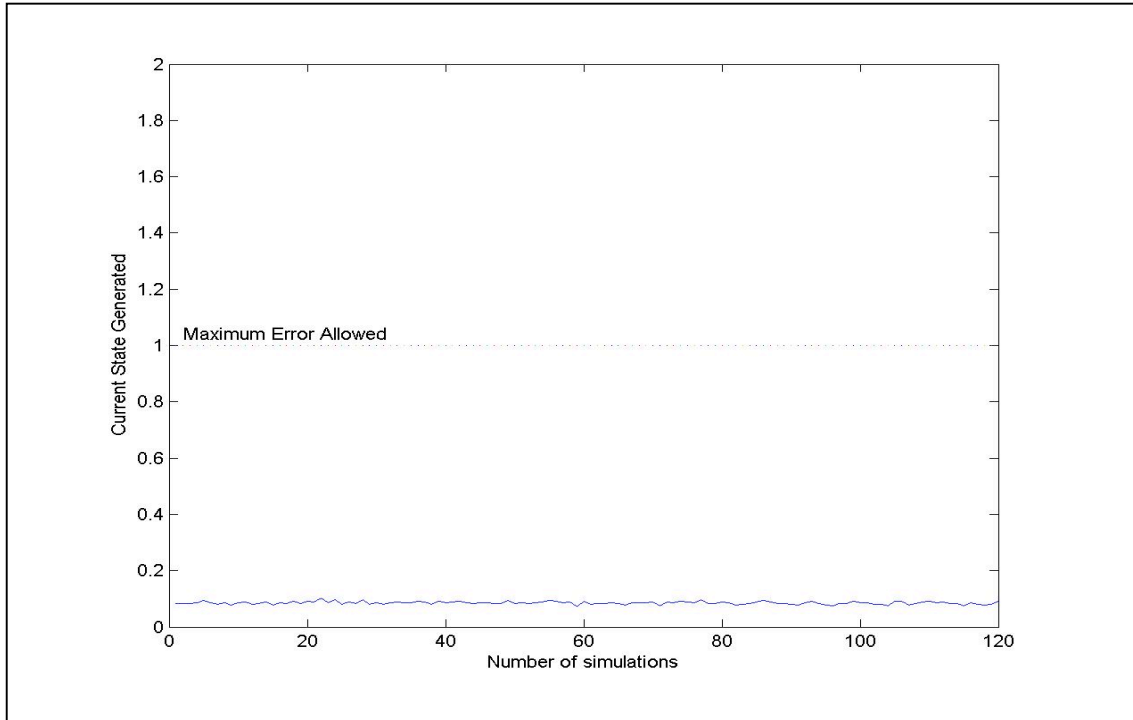


Figure 28. Media of the Current State Generated

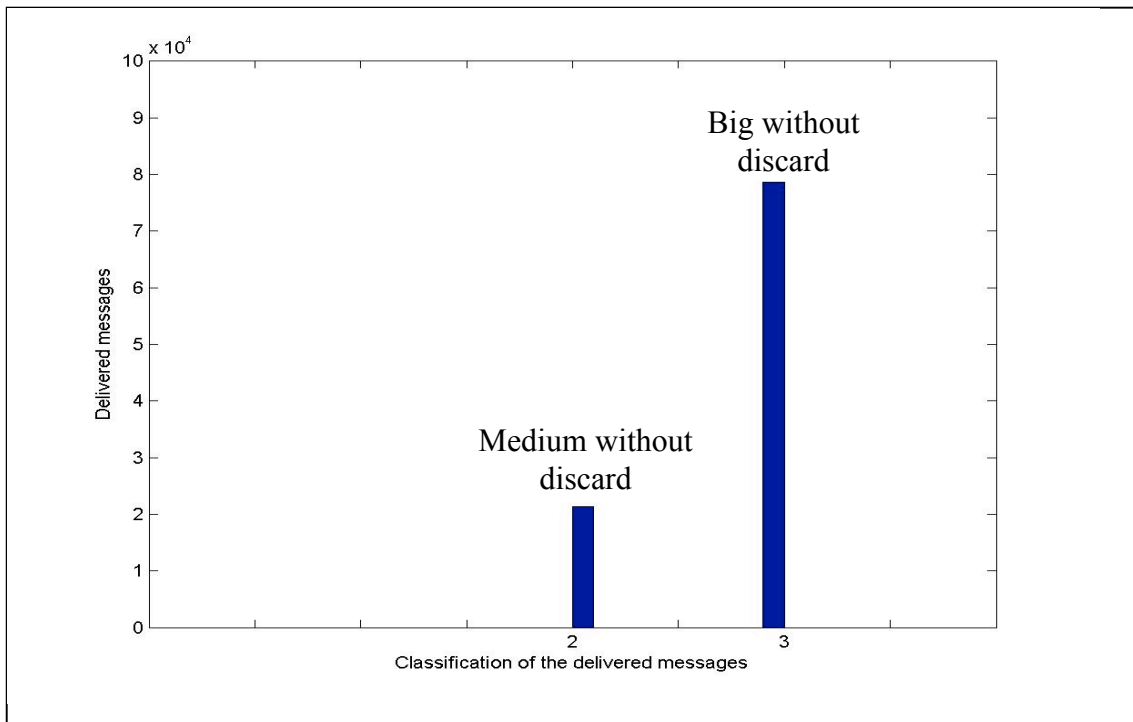


Figure 29. Classification of the delivered messages

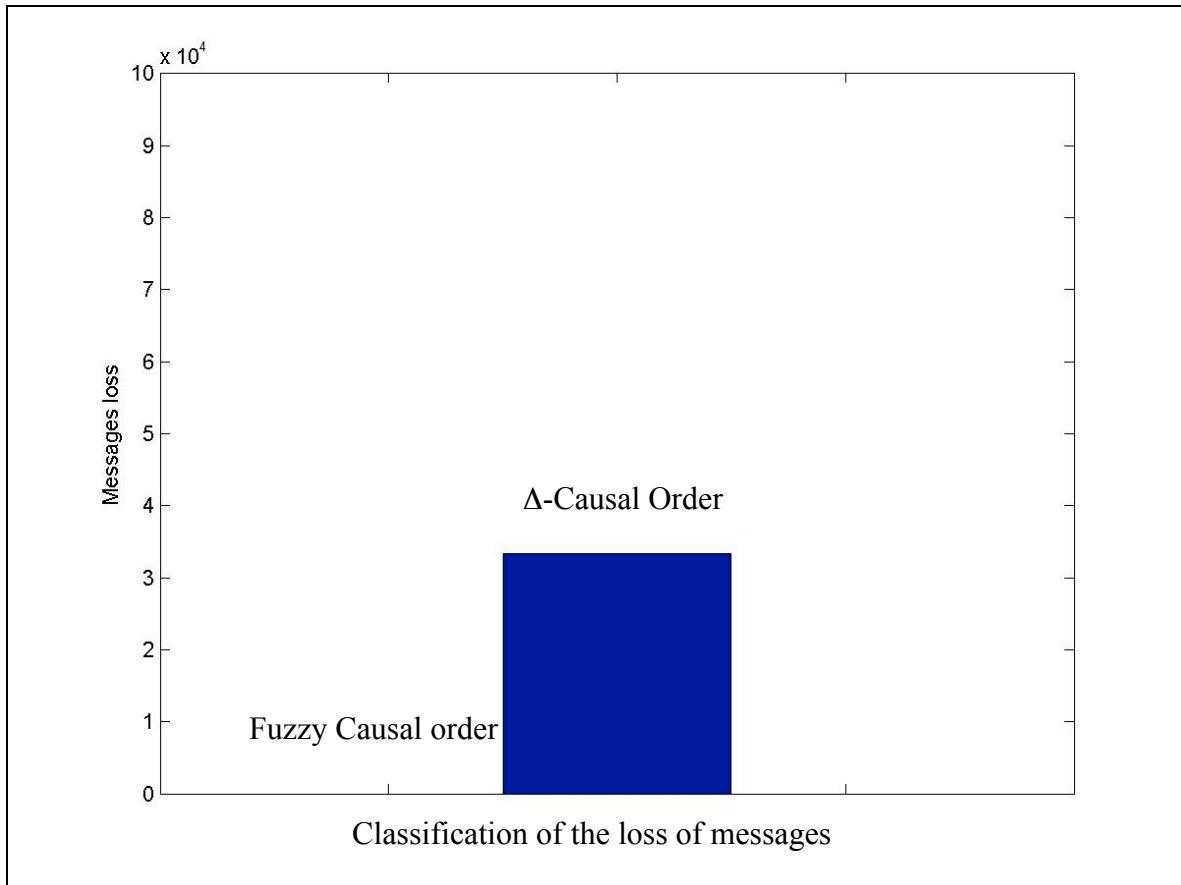


Figure 30. Comparison of loss of message among the fuzzy causal order vs.  $\Delta$ -causal order in the soft case

As we can observe in figure 30, the number of messages loss by using the  $\Delta$ -causal order when there are small delays in the network is bigger than the fuzzy causal order. The FCO deliver all the messages by adjusting their delivery time.

### 5.5.2 Medium case

In the medium case the regular conditions of the system are considered. In this case, there is a loss of messages, and there is transmission random delay; but these are inside the allowed quality of service parameters; figure 31 depicts these conditions. Moreover, the causal distances have a medium value among the events; this means that the value oscillates between 1 and 3. This is reflected in the value obtained by the FCC, see figure 32. Hence, the output value of the fuzzy control is below 0.6, which implies that some messages are

delivered with a selective discard of the messages contained in their causal history, see figure 33. The current state of the system is shown in figure 34, which represents that the execution of the system is regular; for more details see section 4.5. The number of messages with a *medium* time of delivery and *small* time of delivery *with selective discard* are shown in figure 35.

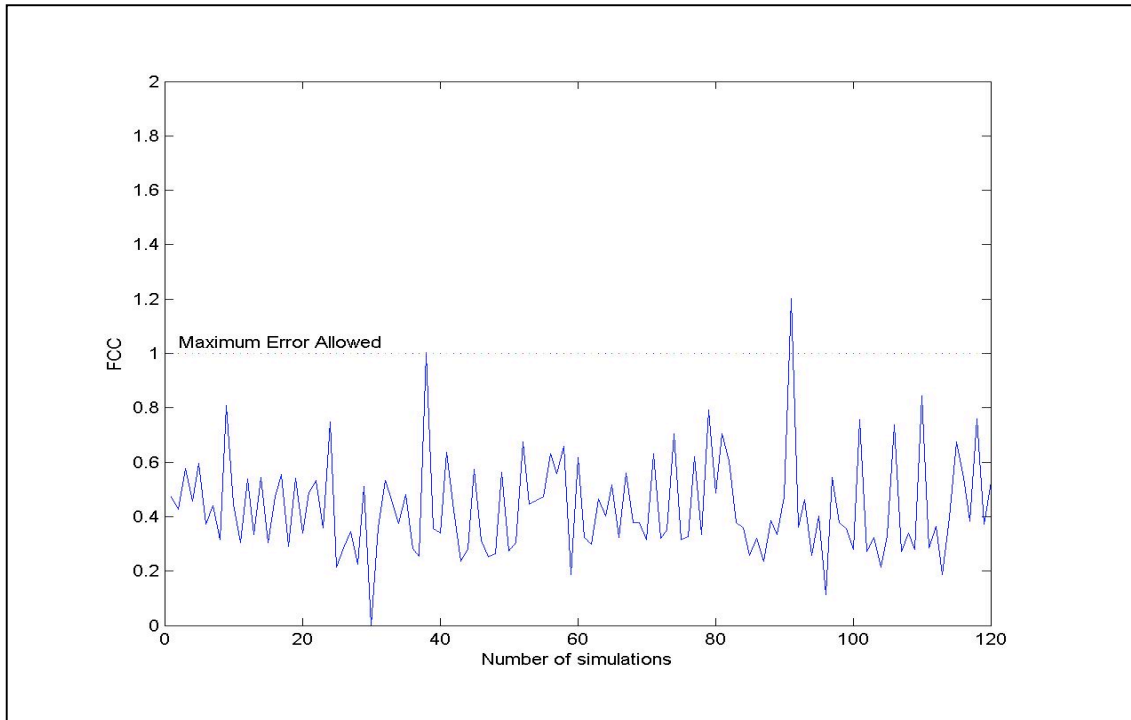


Figure 31. Input value of the FCC

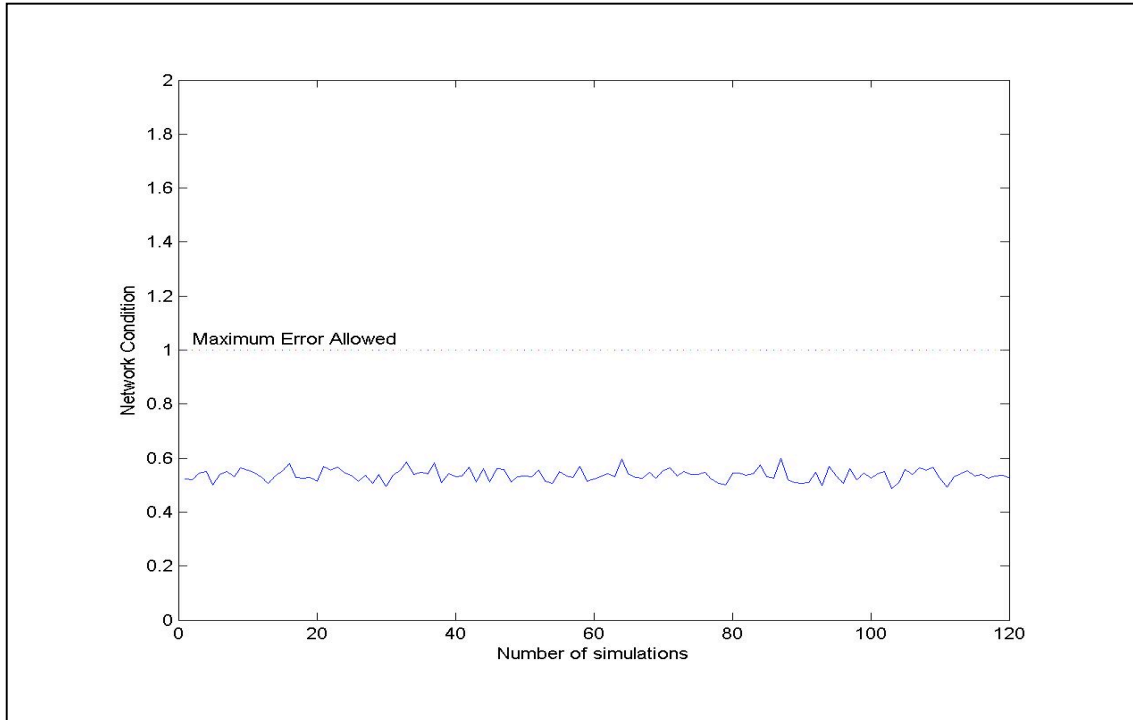


Figure 32. Input value of the Network Conditions

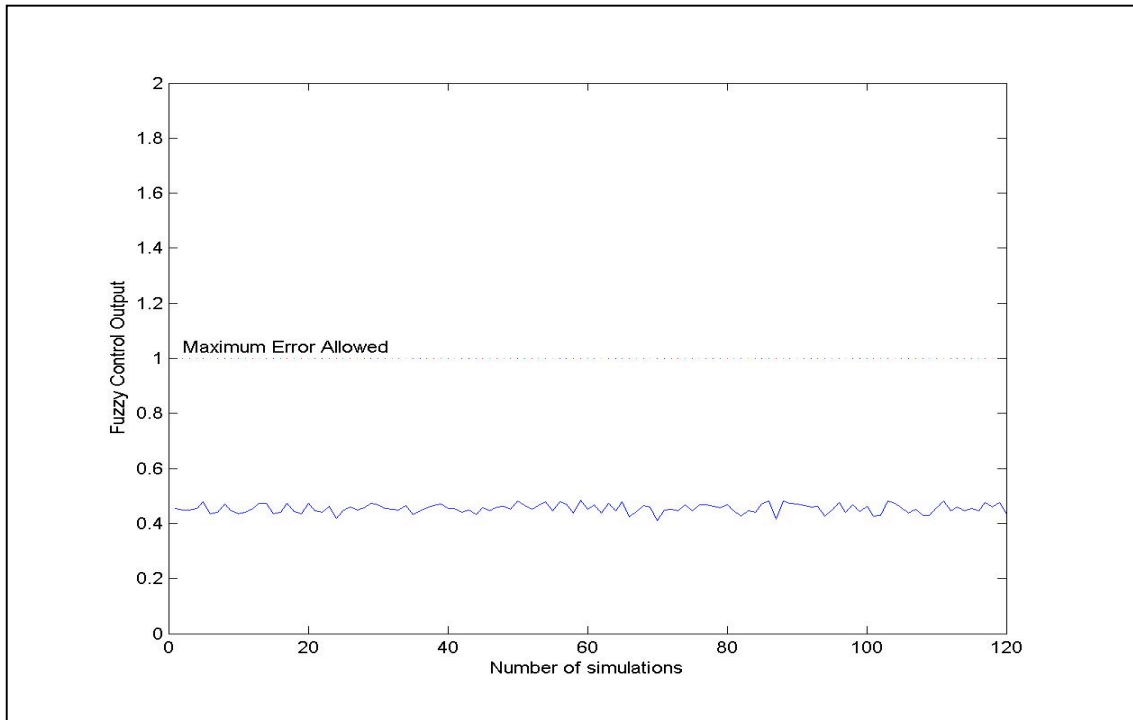


Figure 33. Output value of the fuzzy control system

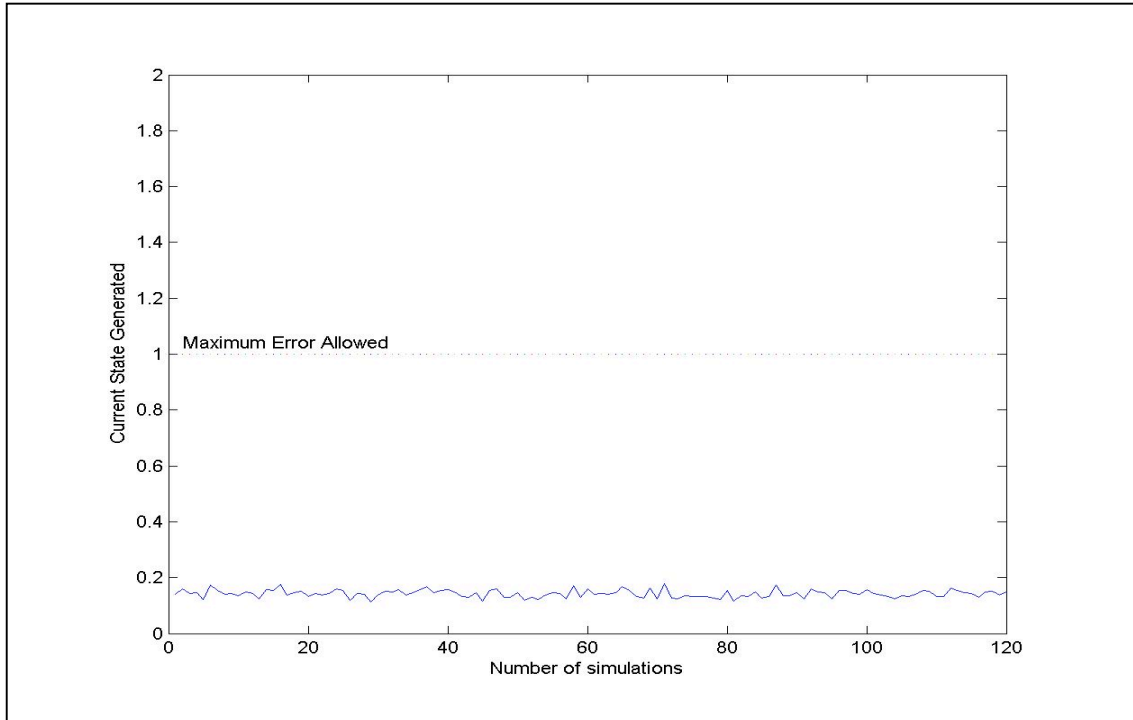


Figure 34. Current state generated

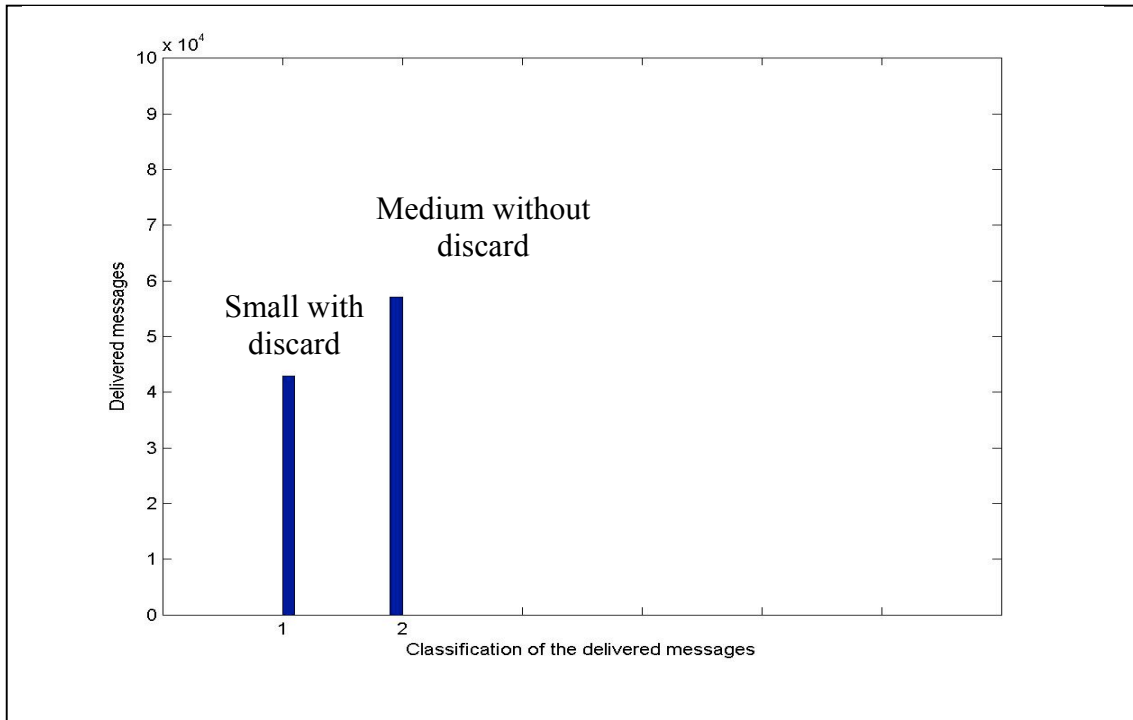


Figure 35. Classification of the delivered messages



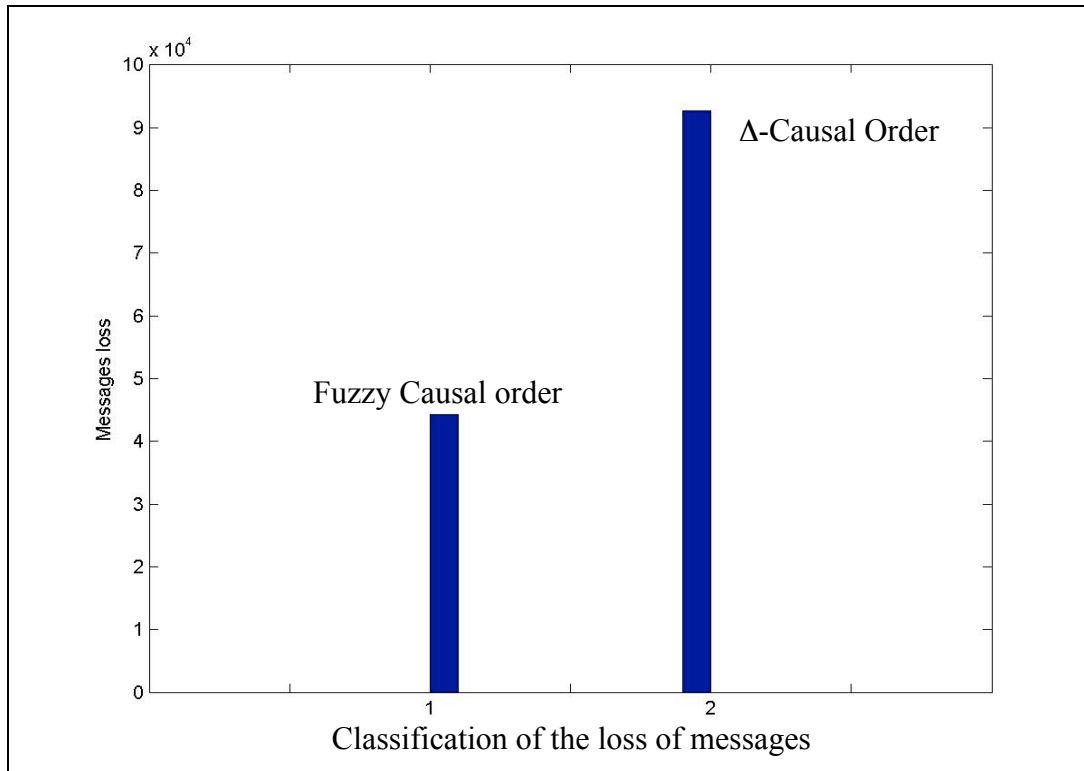


Figure 36. Comparison of loss of message fuzzy causal order vs.  $\Delta$ -causal order in the medium case

As we can observe in figure 36, the number of messages loss by using the  $\Delta$ -causal order is bigger than the fuzzy causal order. Even when the FCO carried out the discard of messages, the number of messages discarded is almost the half of the  $\Delta$ -causal order, which represent fewer interruptions when the data are reproduced by the users.

### 5.5.3 Hard Case

For the hard case deplorable conditions of the system are considered. In this case, the loss of messages and the transmission random delays are at the limit or overpass the allowed quality of service parameters for the network conditions; figure 37 shows this behavior. Moreover, the causal distance is big among the events; this means that the value of the causal distance oscillates between 3 and 4. This is denoted in the value obtained by the FCC, see figure 38. Hence, the output value of the fuzzy control is below 0.45, which implies that some of the messages are delivered with a selective discard of the messages contained in their causal history, see figure 39. The current state of the system depicted in figure 40 represents that the execution of the system is bad; for more details see section 4.5.

In this case, the number of messages delivered with a *small* time of delivery and a *selective discard* prevail, which is shown in figure 41.

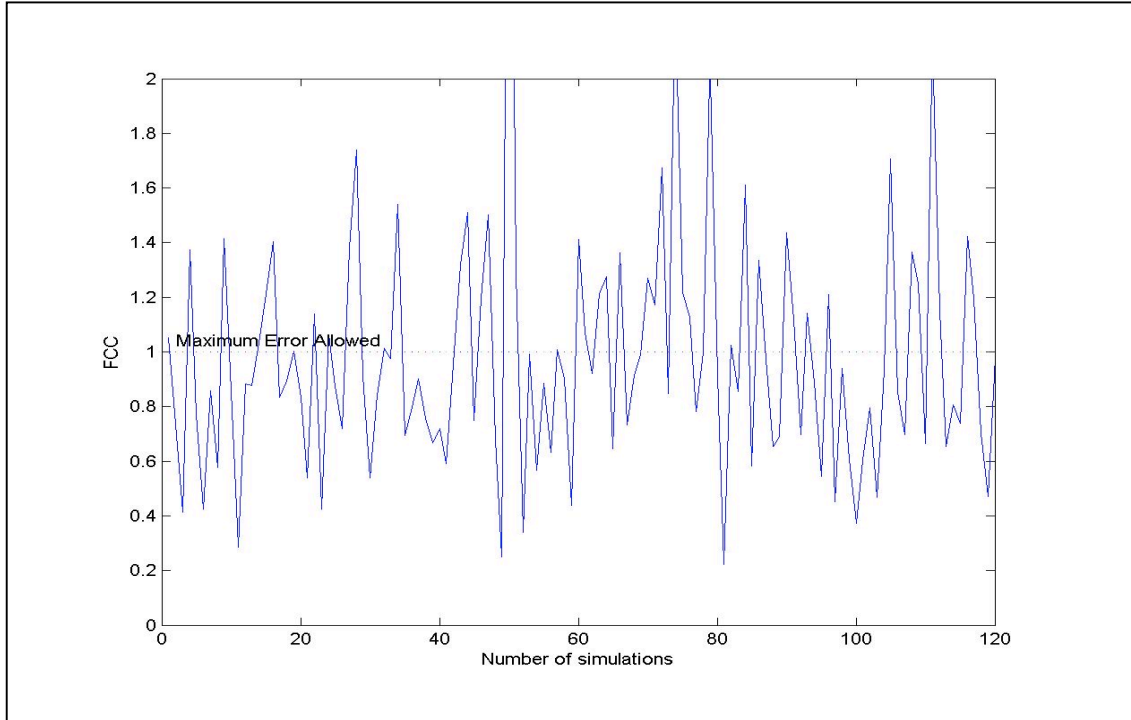


Figure 37. Input value of the FCC

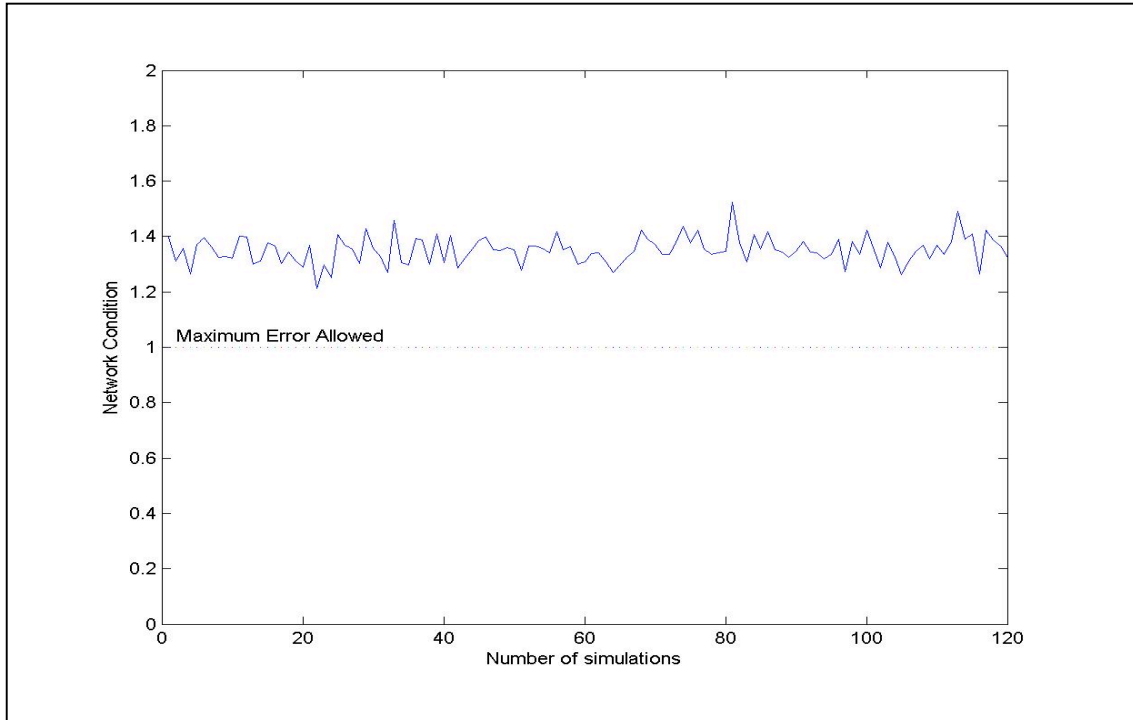


Figure 38. Input value of the Network Conditions

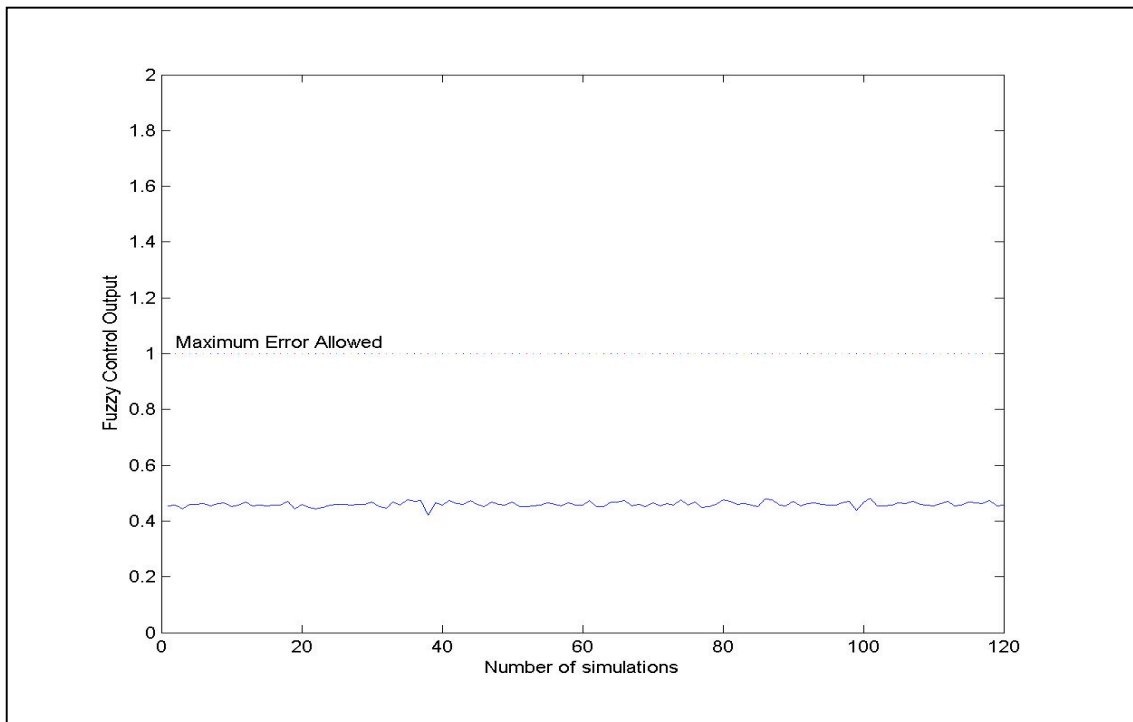


Figure 39. Output value of the fuzzy control system

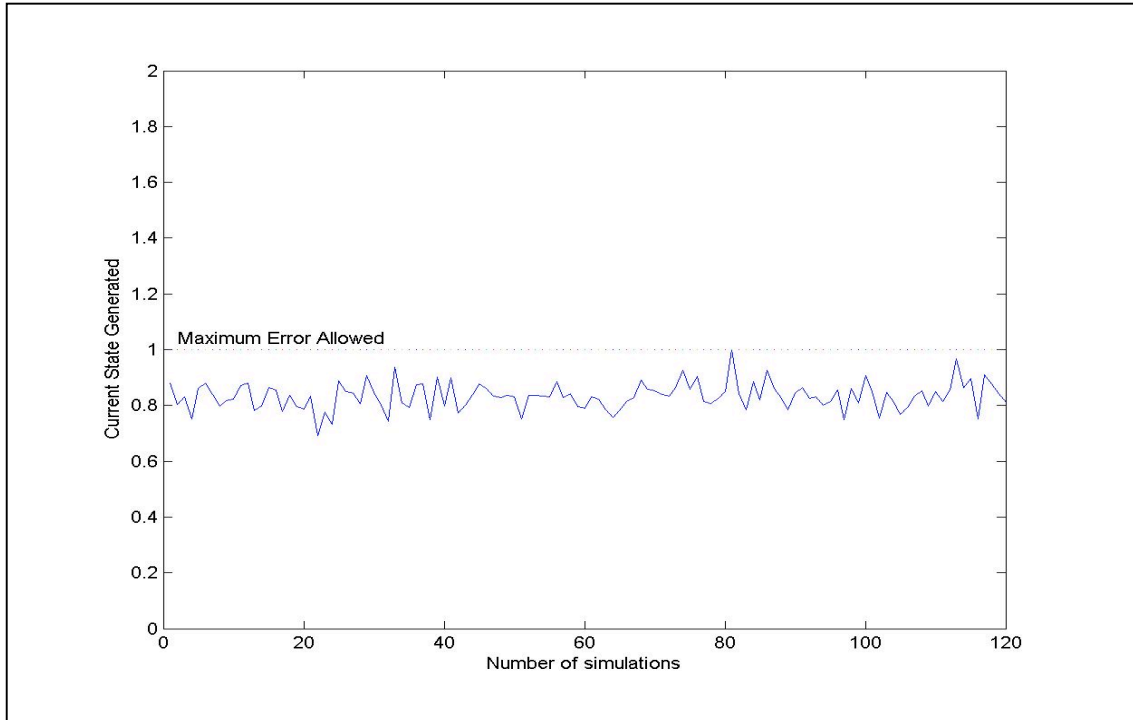


Figure 40. Current state generated

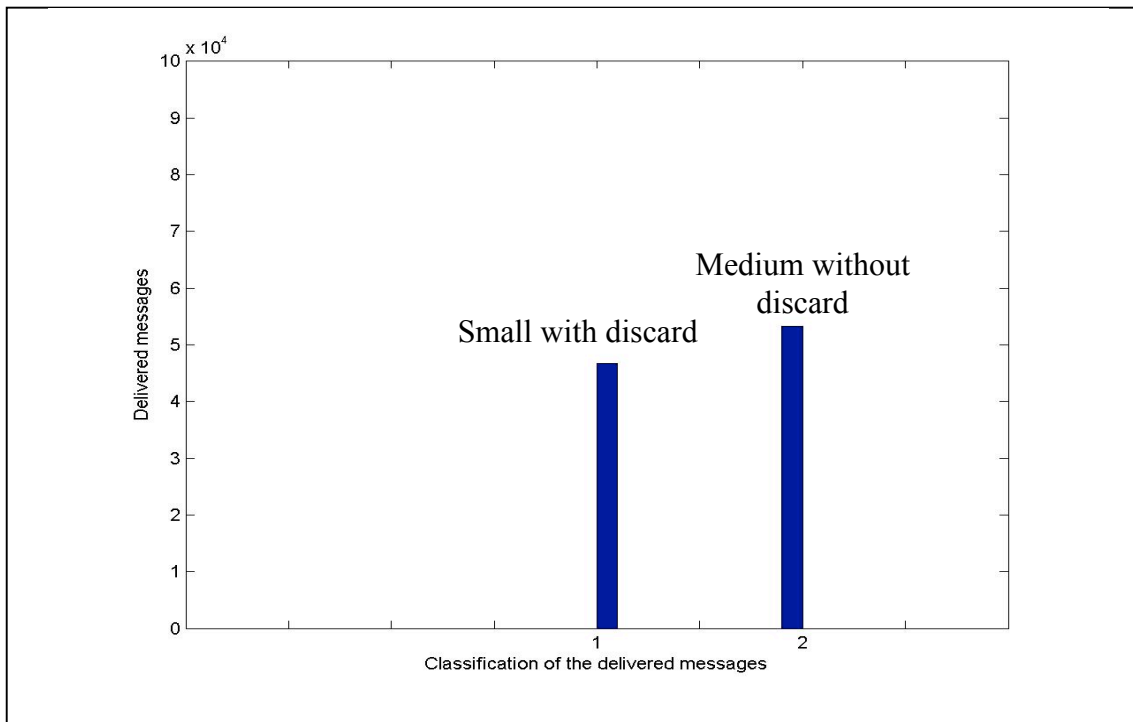


Figure 41. Classification of the delivered messages

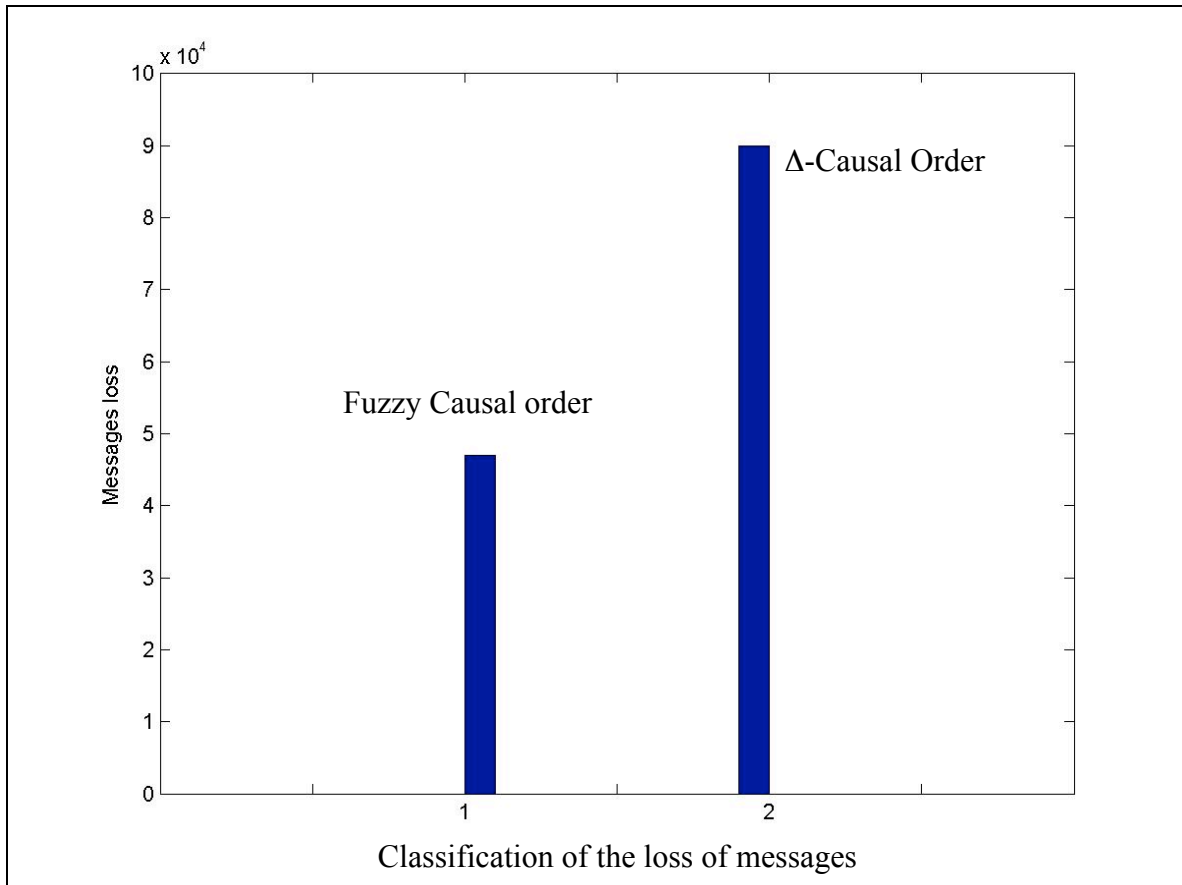


Figure 42. Comparison of loss of message fuzzy causal order vs.  $\Delta$ -causal order in the hard case

As we can observe in figure 42, the number of messages loss by the FCO is less than the  $\Delta$ -causal order. This represents that even when the network conditions are deplorable the FCO allows the deliver of more messages than the  $\Delta$ -causal order reproducing the data in a more continuous manner.

# Chapter 6

*“When you know a thing, to hold that you know it; and when you do not know a thing, to allow that you do not know it—this is knowledge.”*  
Confucius(551a.c.-479a.c.)

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## Conclusions and Future Work

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### 6.1 Conclusions

The main contribution of this dissertation is the definition of the fuzzy causal relation and fuzzy causal consistency for distributed systems. These definitions permit establishing a more asynchronous ordering for application where certain degradation of the system is allowed. The fuzzy causal relation establishes a *cause-effect* degree between events by considering *distances* of the spatial, temporal, and/or logical domain. The fuzzy causal relation indicates “*how long ago*” an event *a* happened before an event *b*. On the other hand, the fuzzy causal consistency indicates “*how good*” the performance of the system is in a certain time. The meaning of the fuzzy causal relation and the fuzzy causal consistency can be addressed according to the problem to be solved. These definitions can be used to solve problems in different areas, such as planning, scheduling, and cooperative work. The

FCR and FCC allow measure the performance of the application by a participant at runtime without halt the system.

Another contribution of this dissertation is a new event ordering for distributed systems, called fuzzy causal order. This fuzzy order is based on the concepts of fuzzy causal relation and fuzzy causal consistency. The FCO allow a more asynchronous delivery of events compared with the causal delivery order based on the happened-before relation introduced by Lamport.

The usefulness of the fuzzy causal relation and the fuzzy causal consistency was demonstrated by applying them to the concrete problem of intermedia synchronization in distributed multimedia systems. A distributed multimedia mechanism was designed based on these concepts.

The mechanism is composed of four main components. The first component is the multimedia synchronization model, which establishes synchronization periods from synchronization points, which are identified by using the endpoints of the intervals. The second component is the component of input variables, which includes the main variables used by the fuzzy causal consistency and the fuzzy control system. The third is the fuzzy causal component, which includes the FCR and the FCC, applying them to the multimedia synchronization problem. The last component is the fuzzy control system, which carries out the multimedia synchronization for distributed systems, adjusting the delivery time of the messages and determining if a selected message discard is carried out. Besides, the fuzzy control works in a distributed manner which is a novel solution for multimedia synchronization.

In order to show the viability of the mechanism an algorithm that carries the four components of the mechanism was developed. The functionality of the algorithm was verified in three different scenarios, where different conditions of the system were considered, such as ideal, regular, and deplorable conditions. Based on the simulation results we observe that the FCO reduce the number of loss messages compared with the  $\Delta$ -

causal order, which gives for the intermedia synchronization a more continuous reproduction of the data.

## 6.2 Future Work

The fuzzy causal theory presented has been developed in an abstract way in order to be applied to other domains that also are characterized for tolerating some kind of degradation. Therefore, the future directions of this work includes proposing and developing novel solutions to classical problems in distributed systems, to problems in emerging areas, such as ubiquitous computing and sensor networks, and proposing and developing novel solutions for the emerging area of multimedia sensor networks. Next, a general description of these problems is presented.

As immediate work, the fuzzy causal relation, the fuzzy causal consistency, and the fuzzy causal order can be considered to resolve classical problems of distributed systems, such as the followings:

- Detection of concurrent messages and establishing their delivery order. The research could be focused on how the fuzzy precedence can be used to determine certain order among the concurrent messages according to their temporal and logical dependencies by using the FCR.
- Establishment of checkpoints by using the fuzzy causal consistency without blocking the execution of parallel programs while checkpointing. If the checkpoints are carried out in a loose manner, certain advantages in terms of low overhead in failure-free execution, simplicity of recovery, and garbage collection, could be obtained.

In a future stage, the fuzzy causal theory could be applied in the ubiquitous computing environments and sensor networks.

- Ubiquitous computing environments are typically based upon ad hoc networks of mobile computing devices. These devices may be equipped with sensor hardware to sense the physical environment and may be attached to real world artifacts to form



so-called smart things. The data sensed by various smart things can then be combined to derive knowledge about the environment, which in turn enables the smart things to “react” intelligently to their environment. For this so-called sensor fusion, temporal relationships (X happened before Y) and real-time issues (X and Y happened within a certain time interval) play an important role. Thus physical time and clock synchronization are crucial in such environments. However, due to the characteristics of sparse ad hoc networks, classical clock synchronization algorithms are not applicable in this setting. Hence, the synchronization of the temporal dependencies could be carried out based on the fuzzy causal theory developed in this dissertation.

A long term research focus is to apply the fuzzy theory to multimedia sensor networks.

- Multimedia sensor networks are a new and emerging type of sensor networks that contain sensor nodes equipped with cameras, microphones, and other sensors, producing multimedia content. These interconnected devices are able to ubiquitously retrieve multimedia content, such as video and audio streams, still images, and scalar sensor data from the environment. The multimedia sensor networks have the potential to enable a large class of applications, ranging from assisting the elderly in public spaces to border protection, which benefit from the use of numerous sensor nodes that deliver multimedia content. Hence, in order to determine relations between the data recollected from the sensors to reproduce and monitor these scenarios, the fuzzy causal theory introduced in this dissertation could be useful.

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# Appendixes

## Appendix A. Happened-before relation for Intervals

The happened-before relation proposed by Morales and Pomares in [26, 27] establish that: if the elements of an interval are sequentially ordered, then ensuring partial causal order on the interval endpoints is sufficient to ensure causal ordering at an interval level. This relation was formally defined as follows:

**Definition 9.** The relation “ $\rightarrow_I$ ” is accomplished if it satisfies the following two conditions:

- 1)  $A \rightarrow_I B$  if  $a^+ \rightarrow_{M'} b^-$
- 2)  $A \rightarrow_I B$  if  $\exists C \mid (a^+ \rightarrow_{M'} c^- \wedge c^+ \rightarrow_{M'} b^-)$

Where  $a^+$  and  $b^-$  are the final and initial send events (or messages) of  $A$  and  $B$  respectively,  $c^-$  and  $c^+$  are the endpoints of  $C$ , and  $\rightarrow_{M'}$  is the partial causal order (Definition 2) induced on  $M' \subseteq M$ , where  $M'$ , in this case, is the subset composed by the endpoint messages of the intervals in  $I$ .

The simultaneous relation to be applied to intervals is defined as follows:

**Definition 10.** Two intervals  $A, B$  are said to be simultaneous “ $\parallel$ ” if the following condition is satisfied:

$$A \parallel B \Rightarrow a^- \parallel b^- \wedge a^+ \parallel b^+$$

The definition above means that one interval  $A$  can take place at the “same time” as another interval  $B$ .

### The Immediate Dependence Relation

The Immediate Dependency Relation (IDR) [22] is the propagation threshold of the control information  $CI$ , regarding the messages sent in the causal past that must be transmitted to ensure a causal delivery. We denote it by  $\downarrow$ , and its formal definition is the following

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**Definition 11:** Immediate Dependency Relation  $\downarrow$  (IDR):

$$m \downarrow m' \Leftrightarrow [(m \rightarrow m') \wedge \forall m'' \in M, \neg (m \rightarrow m'' \rightarrow m')]$$

Thus, a message  $m$  directly precedes a message  $m'$ , iff no other message  $m''$  belonging to  $M$  exists ( $M$  is the set of messages of the system), such that  $m''$  belongs at the same time to the causal future of  $m$ , and to the causal past of  $m'$ . This relationship is important since we show that if the delivery of messages respects the order of their diffusion for all pairs of messages in IDR, then the delivery will respect the causal delivery for all messages.

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## Appendix B. Causal Distance Algorithm for Broadcast Case

In order to know the value of the causal distance among two events in this dissertation a collaboration to develop the algorithm that carries out the definition 7 was made. First, the data structures used by the algorithm are presented. Later, the codification of the algorithm is shown in table 3.

### Data Structures

- $VT(p)$  is the vector time. The size of  $VT(p)$  is equal to the number of processes in the group. Each process  $p$  has an element  $VT(p)[j]$  where  $j$  is a process identifier. The  $VT(p)[j]$  represents the greatest number of messages of the identifier  $j$  and “seen” in causal order by  $p$ . The  $VT(p)$  structure contains the local view of the causal history of the system of process  $p$ .
- $H(m)$  is the causal information of message  $m$ . It contains identifiers of messages  $(k,t)$  causally preceding causal message  $m$ . The information in  $H(m)$  ensures the causal delivery of message  $m$ . The  $H(m)$  structure is built before a causal message is transmitted, and then it is attached to the causal message.
- $CI(p)$  is the control information structure. It is a set of entries  $(m, m'=init\_IDR(m), m''=last\_causal(m), d(m,m''))$ , where:
  - $m=(k, t)$ , represents a message diffused by participant  $p_k$  at a logical local timeclock  $t = VT(p_k)[k]$ .
  - $init\_IDR(m)$  represents a message  $m'=(k', t')$  such that  $m \downarrow m'$ . We note that for every message  $m' \in M$  such that  $m \downarrow m'$ , will be an entry  $(m, m', m'', d(m,m''))$  in  $CI(p)$ .
  - $last\_causal(m)=m''=(k'', t'')$ , represents a message, diffused by participant  $k''$  at a logical local timeclock  $t''$ , that is the last message causal received by a process  $p$  such that  $m \rightarrow m''$ .
  - $d(m,m'')$  is a variable that contains the causal distance between  $m$  and  $m''$ . We can refer it only by  $d$ , when there is no ambiguity in the context.

- Each entry  $ci(m,m') \in CI(p)$  is identified by the tuple  $(m,m')$ .

### Causal distance algorithm specification (broadcast case)

1.	<b>Initially</b>	
2.	$VT(p)[i] = 0 \forall i:1 \dots n$	/* Vector clock */
3.	$CI(p) \leftarrow \emptyset$	
4.	<b>For each diffusion of message <math>send(\#)</math> at <math>p_i</math></b>	
5.	$VT(p)[i] = VT(p)[i] + 1$	
6.	<b>for all <math>ci(m,m') = (m=(k,t), m'=(k',t'), m''=(k',t'), d) \in CI(p)</math></b>	/* $ci(m,m')=(m, Init\_IDR(m), last\_causal(m), d(m,m'))$ */
7.	$H(\#) \leftarrow \emptyset$	
8.	<b>if <math>m''=null</math> then</b>	
9.	$m'=(i, t=VT(p)[i])$	/* we do $Init\_IDR(m) = \#$ */
10.	$m''=(i, t=VT(p)[i])$	/* we do $last\_causal(m) = \#$ */
11.	$ci(m,m') \leftarrow (m,m',m'',d+1)$	/* Accounts for causal_distance $d(m,m')$ */
12.	<b>if <math>d==1</math> then</b>	/* means that $m \downarrow \#$ */
13.	$H(\#) \leftarrow H(\#) \cup (k,t)$	
14.	<b>endfor</b>	
15.	$\# = (i, t, content, H(\#))$	
16.	$CI(p) \leftarrow CI(p) \cup (m=(i, t), null, null, d=0)$	
17.	<b>Diffusion: <math>send(\#)</math></b>	
18.		
19.	<b>For each reception <math>receive(\#)</math> at <math>p</math>, <math>\#=(k, t, content, H(\#))</math></b>	
20.	<b>if not <math>(t == VT(p)[k] + 1)</math> and <math>t' \leq VT(p)[k'] \forall (k', t') \in H(\#)</math></b>	
21.	<b>then</b>	
22.	$wait()$	
23.	<b>else</b>	
24.	<b>Delivery: <math>delivery(m)</math></b>	
25.	$VT(p)[k] = VT(p)[k] + 1$	
26.	<b>for all <math>(m,m',m'',d) \in CI(p)</math></b>	/* $(id(m), Init\_IDR(m), last\_causal(m), d(m,m'))$ */
27.	<b>if <math>m''=null</math> and <math>m \in H(\#)</math> then</b>	/* means that $m \downarrow \#$ */
28.	$m', m'' = (k,t)$	/* we do $Init\_IDR(m)$ and $last\_causal(m) = \#$ */
29.	$d=d+1$	
30.	<b>if <math>m'' \in H(\#)</math> then</b>	/* means that $\#, m$ , and $m''$ belongs to the same linearization beginning at $m$ and finishing at this moment at $\#$ */
31.	$d=d+1$	
32.	$m'' = \# = (k,t)$	/* we do $last\_causal(m) = \#$ */
33.	<b>endfor</b>	
34.	<b>for all <math>\#'=(k',t') \in H(\#)</math></b>	
35.	<b>if <math>\exists (m,m',m'',d) \in CI(p)   \#'==m</math> then</b>	/* a new sublinearization is identified that begins at $m$ */
36.	$CI(p) \leftarrow CI(p) \cup (m=\#, m'=(k,t), m''=(k,t), d=1)$	

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37.	<b>for all</b> $(m, m', m'', d) \in CI(p) \mid (init\_IDR(m') == last\_causal(m), m' \neq m)$
38.	$last\_causal(m) = m'$ <span style="float: right;">/* we returns to <math>m^2</math> that is the message before the ramification */</span>
39.	$d = d - 1$
40.	<b>endfor</b>
41.	<b>endif</b>
42.	$CI(p) \leftarrow CI(p) \cup (m = (k, t), null, null, d = 0)$
43.	<b>Endif</b>

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## Appendix C. Maximum error tolerable for multimedia synchronization

Media		Mode, application	Maximum Error synchronization (QoS, $d_{max}$ )
Video	Animation	Correlated	$\pm 120ms$
	Audio	Lip synchronization	$\pm 80ms$
	Image	Overlay	$\pm 240ms$
		No-overlay	$\pm 500ms$
	Text	Overlay	$\pm 240ms$
No-overlay		$\pm 500ms$	
Audio	Animation	Event correlation (e.g. dancing)	$\pm 80ms$
	Audio	Tightly coupled(stereo)	$\pm 11ms$
		Loosely coupled (dialogue mode with various participants)	$\pm 120ms$
Image	Image	Loosely coupled (e.g. background music)	$\pm 500ms$
		Tightly coupled (e.g. music with notes)	$\pm 5ms$
	Text	Loosely coupled (e.g. slide show)	$\pm 500ms$
		Notes of text	$\pm 240ms$
		Pointer	Audio related to the item

Table 3. Maximum error tolerable for multimedia synchronization

## Appendix D. Algorithm codification

The formal codification of the algorithm is presented in the table 3.

	<b>Initially</b>
1.	$VT(p)[j] = 0 \quad \forall j: 1 \dots n$
2.	$CI(p) \leftarrow \emptyset$
3.	$last\_fifo(p) \leftarrow \emptyset$
4.	$VRCD(p)[j] = 0 \quad \forall j: 1 \dots n$
5.	$VQoS(p)[j] = \text{Maximum error allowed} \quad \forall j: 1 \dots n$
6.	$VFR(p)[j] = \text{frame rate} \quad \forall j: 1 \dots n$
7.	$VPeriodo(p)[j] = (VQoS(p)[j] / VFR(p)[j]) \quad \forall j: 1 \dots n$
8.	$VTemp\_periodo(p)[j] = 0 \quad \forall j: 1 \dots n$
9.	$VRTT(p)[j] = 0 \quad \forall j: 1 \dots n$
10.	$VBw(p)[j] = 0 \quad \forall j: 1 \dots n$
11.	$Vjitter(p)[j] = 0 \quad \forall j: 1 \dots n$
12.	$VTime(p)[j] = 0 \quad \forall j: 1 \dots n$
13.	$GP(p)[j] = 0 \quad \forall j: 1 \dots n$
	<b>For continuous messages <math>m</math> sent by <math>p</math> with identifier of the process <math>i</math></b>
14.	<b>Send</b> ( Input: $TP = \{begin \mid end \mid fifo\}$ )
15.	$VT(p)[i] = VT(p)[i] + 1$
16.	If not ( $TP = fifo$ ) then
17.	If not ( $TP = begin$ ) then //construction of the $H(m)$ to messages $end$
18.	$H(m) \leftarrow CI(p)$
19.	Else
20.	//construction of the $H(m)$ to messages $begin$ $\forall (s,r) \in CI(p)$
21.	If $\exists (x,f) \in last\_fifo(p) \mid s=x$ then //Adding $fifo$ information to $CI(p)$
22.	If not ( $(s,r) = \max\{(x,f), (s,r)\}$ ) then
23.	$CI(p) \leftarrow CI(p) \cup (x,f)$
24.	Endif
25.	endif
26.	$H(m) \leftarrow CI(p)$
27.	$last\_fifo(p) \leftarrow \emptyset$
28.	Endif
29.	$CI(p) \leftarrow \emptyset$ //Eliminate the $CI(p)$ for every causal message sent
30.	Else
31.	//construction of the $H(m)$ to messages $fifo$ $H(m) \leftarrow \emptyset$
32.	Endif
33.	$M = (i, t = VT(p)[i], TP, H(m), data)$
34.	$sending(m)$
	<b>Receive function</b>

35.	<i>receive(m)</i> in <i>p</i> with $i \neq j$ and $m=(k, t, \text{event}, f, TP, H(m))$
36.	If not ( $TP=fifo$ ) and not ( $VTemp\_Periodo(p)[k]>0$ ) then
37.	If ( $TP=begin$ or $TP=end$ or $[(t-VT(p)[k]) \geq dc\_max]$ ) then
38.	// Establishing of the period and the necessary parameter to calculate the GP $VTemp\_Periodo(p)[k]=VT(p)[k] + \text{round}(VPeriodo(p)[k]/2)$
39.	$VRTT(p)[k]=\text{get\_RTT}()$
40.	$VBw(p)[k]=\text{get\_Bw}()$
41.	$Vjitter(p)[k]=\text{get\_jitter}()$
42.	$\forall (l, t') \in H(m)$
43.	$Vtemp\_Periodo(p)[l]=VT(p)[l] + \text{round}(VPeriodo(p)[l]/2)$
44.	$VRTT(p)[l]=\text{get\_RTT}()$
45.	$VBw(p)[l]=\text{get\_Bw}()$
46.	$Vjitter(p)[l]=\text{get\_jitter}()$
47.	$VT(p)[k] = VT(p)[k] + 1$
48.	If $\exists (s, r) \in CI(p) \mid k = s$ then
49.	$CI(p) \leftarrow CI(p) \setminus \{(s, r)\}$
50.	Endif
51.	//Updating the $CI(p)$ $CI(p) \leftarrow CI(p) \cup \{(k, t)\}$
52.	$\forall (l, t') \in H(m)$ //Depura $CI(p)$ y <i>last_fifo(p)</i>
53.	If $\exists (s, r) \in CI(p) \mid l=s$ and $r \leq t'$ then
54.	$CI(p) \leftarrow CI(p) \setminus (s, r)$
55.	Endif
56.	If $\exists (x, f) \in \text{last\_fifo}(p) \mid l=x$ and $f \leq t'$ then
57.	$\text{last\_fifo}(p) \leftarrow \text{last\_fifo}(p) \setminus (x, f)$
58.	Endif
59.	Else
60.	// Cheking the range of the period If ( $VTemp\_Periodo(p)[k]<VT(p)[k]$ )
61.	$VTemp\_Periodo(p)[k]=0$
62.	$\forall (l, t') \in H(m)$
63.	If ( $VTemp\_Periodo(p)[l] < VT(p)[l]$ )
64.	$VTemp\_Periodo(p)[l]=0$
65.	End
66.	// Reception and delivery of message inside the period If ( $VTemp\_Periodo(p)[k]>0$ )
67.	$tN = \text{get\_time(actual)} - VTime(p)[k]$
68.	$Vtime(p)[k] = \text{get\_time(actual)}$
69.	$d = t - VT(p)[k]$
70.	If $TP=fifo$
71.	$dc\_max = d$
72.	Else
73.	$dc\_max = 0$
74.	$\forall (l, t') \in H'(m)$
75.	If $dc\_max < d$
76.	$dc\_max = d$
77.	$d = t' - VT(p)[l]$
78.	Endif
79.	$Vdc(p)[k] = dc\_max$



80.	$D = t - VT(p)[k]$
81.	$N = \lceil (tN) / (VQoS2(p)[k]) \rceil$
82.	$D = \lceil (Vdc(p)[k]) / (Vd2(p)[k]) \rceil$
83.	// Calculate of the RCD $VRCD(p)[k] = \max(N, D)$
84.	$\forall (l, t') \in H(m)$
85.	$GP(p)[l] = \lceil VRTT(p)[l] + Vjitter(p)[l] + ((VPeriodo(p)[l] - VPR(p)[l])$
86.	$GP(p)[k] = \lceil VRTT(p)[k] + Vjitter(p)[k] + ((VPeriodo(p)[k] - VPR(p)[k])$
87.	$BChannel = \max(GP(p)[l] \mid \forall (l, t') \in H'(m), GP(p)[k])$
88.	$FCC = 0$
89.	$\forall (l, t') \in H(m)$
90.	$FCC = FCC + (VRCD(p)[l] * VGP(p)[l])$
91.	$CS = CS + (((2 * VBw(p)[l]) / VRTT(p)[l]) + ((VPeriodo(p)[l] - VPR(p)[l]) / VPE(p)[l]) * (GP(p)[l] / BChannel))$
92.	$FCC = FCC + (VRCD(p)[k] * VGP(p)[k])$
93.	$NC = NC + (((2 * VBw(p)[k]) / VRTT(p)[k]) + ((VPeriodo(p)[k] - VPR(p)[k]) / VPE(p)[k]) * (GP(p)[k] / BChannel))$
94.	// Calculate the fuzzy causal consistency $FCC = FCC / ngp$
95.	// Calculate the Network conditions $NC = NC / nGP$
	*/Fuzzy control*/
96.	*/Once obtained the input parameters ( $NC$ , $FCC$ ) for the fuzzy control, explained in Section 5.4.4, the adjustment of the delivery time of a message $m$ is carried out to reduce the synchronization error */
97.	Endif
98.	Else */fifo message delivery outside the period/*
99.	If $t = VT(p)[k] + 1$
100.	$delivery(m)$
101.	$VT(p)[k] = VT(p)[k] + 1$
102.	If $\exists (x, f) \in last\_fifo(p) \mid k = x$ then
103.	$Last\_fifo(p) \leftarrow last\_fifo(p) \setminus (x, f)$
104.	endif
105.	// Update the last_fifo(p) with the last message $last\_fifo(p) \leftarrow last\_fifo(p) \cup (k, t)$
106.	Else
107.	$Wait()$
108.	Endif
109.	Endif

Table 4. Algorithm codification